USER'S HANDBOOK
Model 9100
Universal Calibration System

Volume 2 - Performance

## User's Handbook

For

# The Model 9100 <br> Universal Calibration System 

## Volume 2 - Performance

(for Introduction, Installation, Controls (with Tutorial), Manual Mode and Procedure Mode refer to Volume 1 - Operation)
(for Options 250 and 600 refer to Volume 3 - Operation and Performance)

## This product complies with the requirements of the following European Community Directives: 89/336/EEC (Electromagnetic Compatibility) and 73/23/EEC (Low Voltage) as amended by 93/68/EEC (CE Marking).

However, noisy or intense electromagnetic fields in the vicinity of the equipment can disturb the measurement circuit. Users should exercise caution and use appropriate connection and cabling configurations to avoid misleading results when making precision measurements in the presence of electromagnetic interference

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DANGER
HIGH VOLTAGE


THIS INSTRUMENT IS CAPABLE OF DELIVERING
A LETHAL ELECTRIC SHOCK!
Model 9100: I+, I-, Hi, Lo, sHi and sLo Terminals Model 9105: H (Red), sH (Red), sL (Black) LI- (Black) and I+20 (Yellow) Leads carry the Full Output Voltage THIS CAN KILL!

Avoid damage to your instrument! Refer to User's Handbook, Volume 2, Section 7; for Maximum Output Voltages and Currents.

Unless you are sure that it is safe to do so, DO NOT TOUCH ANY of the following:
Model 9100: I+ I- Hi Lo sHi or SLo leads and terminals Model 9105: H sH sL LI- or I+20 leads

DANGER

## Section 6: 9100 System Application via IEEE-488 Interface

### 6.1 About Section 6

Section 6 describes the environment in which the Model 9100 will operate in remote applications, using the SCPI (Standard Commands for Programmable Instruments) language, within the IEEE-488.1 remote interface. In Section 6 we shall show how the 9100 adopts the IEEE-488.2 message-exchange model and reporting structure, and define the SCPI commands and syntax used to control the 9100 . Section 6 is divided into the following sub-sections:
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### 6.2 Index of IEEE 488.2 and SCPI Codes used in the 9100

6.2.1 Common IEEE 488.2 Commands and Queries

| Program Coding | Description | Appendix C, Page: |
| :--- | :--- | :--- |
| *CLS | Clears event registers and queues (not O/P queue) | $6-C 1$ |
| *ESE Nrf | Enables standard-defined event bits | $6-C 2$ |
| *ESE? | Returns ESE register mask value | $6-C 2$ |
| *ESR? | Reads Event Status register | $6-C 3$ |
| *IDN? | Reports manufacturer, model, etc. | $6-C 4$ |
| *OPC | Sets the 9100 to monitor the 'No-Operations-Pending' flag. | $6-C 5$ |
| *OPC? | For 'No-Operations-Pending' flag 'TRUE', places a 1 in the Output Queue. | $6-C 5$ |
| *OPT? | Recalls the instrument's option configuration. | $6-C 6$ |
| *PSC 0/1 | Sets/resets power-on status clear flag | $6-C 7$ |
| *PSC? | Recalls power-on status clear flag | $6-C 8$ |
| *PUD | Allows entry of user data to protected store | $6-C 9$ |
| *PUD? | Recalls user-entered data | $6-C 10$ |
| *RST | Resets instrument to power on condition | $6-C 11 /$ App D, p6-D1 |
| *SRE Nrf | Enables Service Request Byte bits | $6-C 11$ |
| *SRE? | Returns Service Request Byte mask value | $6-C 12$ |
| *STB? | Non-destructively reads Service Request Byte | $6-C 12$ |
| *TST? | Perform Full Test | $6-C 13$ |
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PASSword. Gains access to Calibration operations, using 'Cal Enable' switch and Password. EXIT. Permits clean exit from calibration operation6-25
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SPECial?
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[SOURce] Used to select the main 9100 Function (Voltage, Current etc.), to be output: ..... 6-30
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PHASe Selects and controls the Phase-shifting facility ..... 6-41
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### 6.3 Introduction

This first part of Section 5 gives the information necessary to put the 9100 into operation on the IEEE 488 bus. For more detailed information, refer to the standard specification in the publications ANSI/IEEE Std. 488.1-1987 and IEEE Std. 488.2-1988.

### 6.3.1 Interface Capability

### 6.3.1.1 IEEE Standards 488.1 and 488.2

The 9100 conforms to the Standard Specification IEEE 488.1-1987: 'IEEE Standard Digital Interface for Programmable Instrumentation', and to IEEE 488.2-1988: ‘Codes, Formats, Protocols and Common Commands'.

### 6.3.1.2 The 9100 in IEEE 488.2 Terminology

In IEEE 488.2 terminology the 9100 is a device containing a system interface. It can be connected to a system via its system bus and set into programmed communication with other bus-connected devices under the direction of a system controller.

### 6.3.1.3 Programming Options

The instrument can be programmed via the IEEE Interface, to:

- Change its operating state (Function, Range, etc).
- Transmit its own status data over the bus.
- Request service from the system controller.


### 6.3.1.4 Capability Codes

To conform to the IEEE 488.1 standard specification, it is not essential for a device to encompass the full range of bus capabilities. For IEEE 488.2, the device must conform exactly to a specific subset of IEEE 488.1, with a minimal choice of optional capabilities.

The IEEE 488.1 document describes and codes the standard bus features, for manufacturers to give brief coded descriptions of their own interfaces' overall capability. For IEEE 488.2, this description is required to be part of the device documentation. A code string is often printed on the product itself.

The codes which apply to the 9100 are given in table 6.1 , together with short descriptions. They also appear on the rear of the instrument next to the interface connector. These codes conform to the capabilities required by IEEE 488.2.

Appendix C of the IEEE 488.1 document contains a fuller description of each code.

### 6.3.1.5 Bus Addresses

When an IEEE 488 system comprises several instruments, a unique 'Address' is assigned to each to enable the controller to communicate with them individually.

Only one address is required for the 9100 . The application program adds information to it to define 'talk' or 'listen'. The method of setting the address, and the point at which the user-initiated address is recognized by the 9100 , is given in Sub-Section 6.4.1.

The 9100 has a single primary address, which can be set by the user to any value within the range from 0 to 30 inclusive. It cannot be made to respond to any address outside this range. Secondary addressing is not available.

### 6.3.1.6 Limited Access

The 9100 has five main modes, which are described briefly in Volume 1 of this Handbook, Section 1, Sub-section 1.2.2. Remote operation is available only subject to the following limitations:

- Procedure Mode

When the 9100 is in Procedure Mode, it is driven essentially from the front panel
Remote Operation will not be allowed in this mode.
N.B. The 9100 can be powered up in either Manual mode or Procedure mode, as set locally in Configuration mode.

- Manual Mode

Remote operation is available for each Manual mode function, but for ease of programming, some remote commands do not mirror front panel operations exactly.

- Configuration Mode

Remote operation is not available, and configuration commands have not been included in the SCPI command set for the 9100.

- Calibration Mode

Remote operation is available, but refer to Sub-section 6.6.2 for details of entry protection.

- Test Mode

Remote operation is not available, but the 'Full' selftest can be initiated by a SCPI command. The 9100 will give a straight Pass/Fail response, but to investigate further, it will be necessary to re-run the test in Test mode from the front panel.

### 6.3.2

Interconnections

Instruments fitted with an IEEE 488 interface communicate with each other through a standard set of interconnecting cables, as specified in the IEEE 488.1 Standard document.
The IEEE-488 interface socket, J101, is fitted on the rear panel. It accommodates the specified connector, whose pin designations are also standardized as shown in Table 6.2


Connector J101-Pin Layout

| Pin | Name | Description |
| :---: | :---: | :---: |
| 1 | DIO 1 | Data Input/Output Line 1 |
| 2 | DIO 2 | Data Input/Output Line 2 |
| 3 | DIO 3 | Data Input/Output Line 3 |
| 4 | DIO 4 | Data Input/Output Line 4 |
| 5 | EOI | End or Identify |
| 6 | DAV | Data Valid |
| 7 | NRFD | Not Ready For Data |
| 8 | NDAC | Not Data Accepted |
| 9 | IFC | Interface Clear |
| 10 | SRQ | Service Request |
| 11 | ATN | Attention |
| 12 | SHIELD | Screening on cable (connected to 9100 safety ground) |
| 13 | DIO 5 | Data Input/Output Line 5 |
| 14 | DIO 6 | Data Input/Output Line 6 |
| 15 | DIO 7 | Data Input/Output Line 7 |
| 16 | DIO 8 | Data Input/Output Line 8 |
| 17 | REN | Remote Enable |
| 18 | GND 6 | Gnd wire of DAV twisted pair |
| 19 | GND 7 | Gnd wire of NRFD twisted pair |
| 20 | GND 8 | Gnd wire of NDAC twisted pair |
| 21 | GND 9 | Gnd wire of IFC twisted pair |
| 22 | GND 10 | Gnd wire of SRQ twisted pair |
| 23 | GND 11 | Gnd wire of ATN twisted pair |
| 24 | GND | 9100 Logic Ground (internally connected to Safety Ground) |
| Table 6.2 Connector J101-Pin Designations |  |  |

### 6.3.3 SCPI Programming Language

Standard Commands for Programmable Instruments (SCPI) is an instrument command language which goes beyond IEEE 488.2 to address a wide variety of instrument functions in a standard manner.

IEEE 488.2 defines sets of Mandatory Common Commands and Optional Common Commands along with a method of Standard Status Reporting. The 9100 implementation of SCPI language conforms with all IEEE-488.2 Mandatory Commands but not all Optional Commands. It conforms with the SCPI-approved Status Reporting method.
Note: Commands in SCPI language, prefaced by an asterisk (eg: *CLS), are IEEE-488.2 standard-defined 'Common' commands.

Conformance of the 9100 remote programming commands to SCPI ensures that the 9100 has a high degree of consistency with other conforming instruments. For most specific commands, such as those relating to frequency and voltage, the SCPI approved command structure already exists and has been used wherever possible.
SCPI commands are easy to learn, self-explanatory and account for a wide variety of usage skills. A summary of the 9100 commands is given on pages $6-2$ and $6-3$. The full range of 9100 commands, with their actions and meanings in the 9100 , is detailed in alphabetical order in Sub-Section 6-6.
6.4 Using the 9100 in a System
6.4.1 Addressing the 9100
6.4.1.1 Accessing the Bus Address

The instrument address can only be set manually; using the Bus Address menu, which is accessed via the Configuration menus.
N.B. A password is required for access to change the bus address.

### 6.4.1.2 Select 'Configuration' Mode

1. Press the Mode key on the right of the
front panel to obtain the 'Mode Selection' menu screen:

## Mode Selection

Select required mode using softkeys
2. Press the CONFIG screen key at the center of the bottom row to progress into 'Configuration' mode. The 9100 will transfer to the open 'Configuration' menu screen:

POAY DAATE
PROC
PROC MA
Configuration


### 6.4.1.3 Select 'MORE' Parameters

The bus address is one of the 'MORE' parameters. By trying to select 'MORE', the 'Configuration' password will be required.

Press the MORE screen key on the right of the bottom row. The 9100 will transfer to the 'Password Entry' screen.

## Note: Address Recognition

With an address selected in the range 0 to 30; control may be manual, or remote as part of a system on the Bus. The address must be the same as that used in the controller program to activate the 9100 . The 9100 is always aware of its stored address, responding to Talk or Listen commands from the controller at that address. When the address is changed by the user, the 9100 recognizes its new address and ignores its old address, as soon as it is stored by the user pressing the EXIT key in the Configuration-Bus Address menu.
6.4.1.4

1. When you enter your password using the alpha-numeric keyboard, security icons will appear on the screen as you type. Finally press the $\lrcorner$ (return) key. If the password is incorrect: an error message will be given and the security icons will be removed, enabling a new attempt to enter the password.

The 'EXIT' screen key acts to escape back to the previous screen.
2. The correct password, followed by لـ, will provide entry to the main 'Configuration' menu screen, which shows the present settings of the parameters which can be changed using screen keys on this display:
3. In this case we are interested in 'BUS ADDRESS'

## Configuration

|  |  |  |  | $\begin{gathered} \text { SELECT } \\ \text { LANG } \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: |
| Ser. No | xxx |  | Rev. XXX | PO |
| Presen | ettin |  |  | UP MODE |
| Langua |  |  | English | BUS |
| Bus Ad | ss |  |  | ADDRESS |
| Printer |  |  | NONE | PRINTER |
| Results |  |  | Disabled |  |
| Safety | tage |  | 100.000 V | RESULTS |
| Border |  |  | $70.00 \%$ | CARD |
| Scope Crystal |  |  | Option 600 <br> High acc |  |
| tooay date |  | TME |  |  |
| VOLTAGE | DATE | BORDER |  | MORE |

## Password Entry

For Configuration

Enter password : © () () () ()


### 6.4.1.5 Change the Bus Address

1. For access from the 'Present Settings' screen, press the BUS ADDRESS screen key on the right. This action will transfer to the 'Change the address' screen:

The 9100 IEEE- 488 bus address can be set to any number within the range 0 to 30 .
2. Use Digit edit or Direct edit to set the required bus address number. If using Direct edit, after typing the number press the $\lrcorner$ key.
3. Press EXIT to return to the 'Present Settings' screen.

## Configuration

Change the address by using digit or direct editing

Bus address $=22$

EXIT

### 6.4.2 <br> Operation via the IEEE-488 Interface

### 6.4.2.1 Genera

The power-up sequence is performed as in local operation. The 9100 can be programmed to generate an SRQ at power-up, also preparing a status response for transmission to the controller when interrogated by a subsequent serial poll.

### 6.4.2.2 Operating Conditions

When the 9100 is operating under the direction of the application program, there are two main conditions, depending on whether the application program has set the 'REN' management line 'true' or 'false':

1. REN True ('REN' line low):

The 9100 can be addressed and commanded if in either 'Manual' or 'Calibration' mode. All access to front panel control will be removed, except for the bottom right screen key, labelled 'Enable Local Usage'. The cursor controls will not be present.
If $L L O$ (Local Lockout) has been sent with REN true, then the 'Enable Local Usage' screen key will be inoperative. If $L L O$ has not been sent, the 'Enable Local Usage' screen key will return to local control as if REN were false (see $\mathbf{2}$ below).

The 9100 will act in response to valid commands, performing any changes in output, etc. The display presentation will track the changes.
Remote control cannot command 'Configuration' mode or 'Procedure' mode. These are Local Modes only. Remote control cannot break into locally-entered 'Configuration' mode, 'Procedure' mode or 'Test' mode. However, 'Test' can be run remotely.
2. REN False ('REN' line high):

The 9100 will remain in Local Operation, but can be addressed and commanded, while full access to front panel control is also retained.

The 9100 will act in response to the commands, performing any changes in output, etc. These changes will occur rapidly enough for the only noticeable effect to be the display presentation tracking the changes.

### 6.4.2.3 Programmed Transfer to Local Control (GTL or REN False)

The application program can switch the 9100 into 'Local' Control (by sending Command GTL, or by setting the REN line false), permitting a user to take manual control from the front panel.
The application program can regain 'Remote' control by sending the overriding command: Listen Address with REN true (addressing the 9100 as a listener with the Remote Enable management line true \{Low\}). This will re-impose remote control, unless the 9100 is in Configuration, Procedure or Test Mode.

### 6.4.2.4 'Device Clear'

Either of the commands $D C L$ or $S D C$ will force the following instrument states:

- all IEEE 488 input and output buffers cleared;
- with 'IFC' (Interface Clear), any device-dependent message bus holdoffs cleared.
- the status byte is changed by clearing the MAV bit.


## These commands will not:

- change any settings or stored data within the device except as listed above;
- interrupt analog output;
- interrupt or affect any functions of the device not associated with the IEEE 488 system;


### 6.4.2.5 Levels of Reset

Three levels of reset are defined for IEEE 488.2 application programs, a complete system reset being accomplished by resetting at all three levels, in order, to every device. In other circumstances they may be used individually or in combination:
IFC Bus initialization;
DCL Message exchange initialization;
*RST Device initialization.
The effects of the $* \mathrm{RST}$ command are described in Appendix $C$ to this section.

### 6.4.3.1 IEEE 488.2 Mode

The IEEE 488.2 Standard document illustrates its Message Exchange Control Interface model at the detail level required by the device designer. Much of the information at this level of interpretation (such as the details of the internal signal paths etc.) is transparent to the application programmer. However, because each of the types of errors flagged in the Event Status Register is related to a particular stage in the process, a simplified 9100 interface model can provide helpful background. This is shown below in Fig. 6.1, together with brief descriptions of the actions of its functional blocks.


## Note: Coupled Commands

Coupled commands are best described by an example:
In Section 7, on pages 7-5 and 7-10, the 'Volt-Hz' and 'Amp-Hz' profiles are given. In the 9100, no AC output can be generated whose product of amplitude and frequency occurs outside the relevant profile.
With sequential execution of commands a change in amplitude and frequency (e.g.:VOLT 121;:FREQ 10E3 - a setting within the profile) would cause an execution error if the present frequency was 50 kHz , as the combination of 121 V and 50 kHz is outside the profile
Such anomalies are overcome by defining a coupling between commands which allows the execution of the individual components to be deferred until all contiguous coupled commands in the same group have been parsed and the validity of the combination checked
Note that this does not require that all the coupled components in a group must be supplied for each new signal but that those programmed will be correctly parsed.
Individual commands may be a member of several coupled command groups. Refer to Appendix A to this Section, page 6-A1, for details of coupled groups.

### 6.4.3.2 $\quad 9100$ STATUS Subsystem

Input/Output Control transfers messages from the 9100 output queue to the system bus; and conversely from the bus to either the input buffer, or other predetermined destinations within the device interface. It receives the Status Byte from the status reporting system, as well as the state of the Request Service bit which it imposes on bit 6 of the Status Byte response. Bit 6 reflects the 'Request Service state true' condition of the interface.

### 6.4.3.3 Incoming Commands and Queries

The Input Buffer is a first in - first out queue, which has a maximum capacity of 128 bytes (characters). Each incoming character in the I/O Control generates an interrupt to the instrument processor which places it in the Input Buffer for examination by the Parser. The characters are removed from the buffer and translated with appropriate levels of syntax checking. If the rate of programming is too fast for the Parser or Execution Control, the buffer will progressively fill up. When the buffer is full, the handshake is held.

The Parser checks each incoming character and its message context for correct Standarddefined generic syntax, and correct device-defined syntax. Offending syntax is reported as a Command Error, by setting true bit 5 (CME) of the Standard-defined Event Status register (refer to Sub-Section 6.5 'Retrieval of Device Status Information').

Execution Control receives successfully parsed messages, and assesses whether they can be executed, given the currently-programmed state of the 9100 functions and facilities. If a message is not viable then an Execution Error is reported, by setting true bit 4 (EXE) of the Standard-defined Event Status register. Viable messages are executed in order, altering the 9100 functions, facilities etc. Execution does not 'overlap' commands; instead, the 9100 Execution Control processes all commands or coupled groups of commands (see Note in left column) 'sequentially' (ie. waits for actions resulting from the previous command to complete before executing the next).

### 6.4.3.4 $\quad 9100$ Functions and Facilities

The 9100 Functions and Facilities block contains all the device-specific functions and features of the 9100, accepting Executable Message Elements from Execution Control and performing the associated operations. It responds to any of the elements which are valid Query Requests (both IEEE 488.2 Common Query Commands and 9100 Devicespecific Commands) by sending any required Response Data to the Response Formatter (after carrying out the assigned internal operations).

Device-dependent errors are detected in this block. Bit 3 (DDE) of the Standard Event Status register is set true when an internal operating fault is detected. Each reportable error number is appended to the Error Queue as the error occurs.

### 6.4.3.5 Outgoing Responses

The Response Formatter derives its information from Response Data (being supplied by the Functions and Facilities block) and valid Query Requests. From these it builds Response Message Elements, which are placed as a Response Message into the Output Queue.
The Output Queue acts as a store for outgoing messages until they are read over the system bus by the application program. For as long as the output queue holds one or more bytes, it reports the fact by setting true bit 4 (Message Available-MAV) of the Status Byte register. Bit 4 is set false when the output queue is empty (refer to Sub-Section 6.5 'Retrieval of Device Status Information').

### 6.4.3.6 'Query Error'

This is an indication that the application program is following an inappropriate message exchange protocol, resulting in the Interrupted, Unterminated or Deadlocked condition: Refer to 'Bit 2' in paras 6.5.3.5.
The Standard document defines the 9100 's response, part of which is to set true bit 2 (QYE) of the Standard-defined Event Status register.

### 6.4.4 Request Service (RQS)

### 6.4.4.1 Reasons for Requesting Service

There are two main reasons for the application program to request service from the controller:

- When the 9100 message exchange interface is programmed to report a system programming error;
- When the 9100 is programmed to report significant events by RQS.

The significant events vary between types of devices; thus there is a class of events which are known as 'Device-Specific'. These are determined by the device designer.

### 6.4.4.2 RQS in the IEEE 488.2 Model

The application programmer can enable or disable the event(s) which are required to originate an RQS at particular stages of the application program. The IEEE 488.2 model is extended to incorporate a flexible SCPI status reporting structure in which the requirements of the device designer and application programmer are both met.

This structure is described in Sub-Section 6.5, dealing with 'Retrieval of Device Status Information'.

### 6.5 Retrieval of Device Status Information <br> 6.5.1 General

For any remotely-operated system, the provision of up-to-date information about the performance of the system is of major importance. In the case of systems which operate under automatic control, the controller requires the necessary feedback to enable it to progress the task; any break in the continuity of the process can have serious results.
When developing an application program, the programmer needs to test and revise it, knowing its effects. Confidence that the program elements are couched in the correct grammar and syntax (and that the program commands and queries are thus being accepted and acted upon), helps to reduce the number of iterations needed to confirm and develop the viability of the whole program. So any assistance which can be given in closing the information loop must benefit both program compilation and subsequent use.

Such information is given in the following pages.


### 6.5.2 IEEE-488 and SCPI Standard-Defined Features (Fig. 6.2)

Two main categories of information are provided: 'Status Summary' information, and 'Event Register' conditions.

### 6.5.2.1 Status Summary Information and SRQ

The Status Byte consists of four 'summary' bits which notify events in the 8-bit latched IEEE-488.2-defined 'Event Status Register' (ESB), the two 16-bit latched SCPI-defined registers (OSS \& QSS), and the Output Queue (MAV). Whenever one of these summary bits is enabled and set true, the Status Byte summary bit (MSS) is also set true. The buffered bit 'RQS' follows true when MSS goes true, and will set the IEEE-488 SRQ line true (Note that in Fig 6.2 no arrow points at bit 6 of the Service Request Enable Register - bit 6 is always enabled).
A subsequent serial poll by the Application Program will discover that the 9100 was the requesting device (while resetting RQS false again, MSS remaining true), and which of the summary bits is true. The $*$ STB? command is an equivalent command to serial poll, where serial poll is not available.

### 6.5.2.2 Event Register Conditions

The Status Byte summary bits direct the application program down the structure towards causal events.

ESB and MAV are standard IEEE-488 features, described in detail in Sub-Section 6.5.3.

OSS and QSS are features of the SCPI structure, described in Sub-Section 6.5.4.

### 6.5.2.3 Access via the Application Program

Referring to Fig. 6.2, take as an example the main Event Status register:

## Enabling the Event

The main Standard-Defined Event Status Register' has a second 'EventStatus Enable Register'. A program command (*ESE phs Nrf) can be used to set the state of the bits in the Enable register. This enables or disables the events which will set the main register's summary bit true.

## Reading the Enable Register

A 'query' command (*ESE?) permits the application program to read the state of the Enable register, and hence find out which events are enabled to be reported.

## Reading the Main Register

Another 'query' command (*ESR?) reads the state of the main Standard-Defined register, to discover which event has occurred (i.e. has caused the summary bit to be set true) Reading this register clears all its bits.

## Reporting the Event

If an event is to be reported via the SRQ , its corresponding enable bit will have been set true, (using the number $N r f$ ). Each bit in the Standard-Defined register remains in false condition unless its assigned event occurs, when its condition changes to true and remains true until cleared by *ESR? or *CLS. This causes the register's summary bit in the Status Byte also to be set true. If this bit is enabled, then the Status Byte bit 6 (MSS/RQS) will be set true, and the 9100 will set the IEEE-488 bus SRQ line true

## SCPI Status Registers

The two SCPI Status registers operate in the same way, using the appropriate program commands to set the enable registers, and query commands to discover the condition of the registers.

## Subsequent Action

Thus the application programmer can enable any assigned event to cause an SRQ, or not. The controller can be programmed to read the Status Byte, using a serial poll to read the Status Byte register and the true summary bit (ESB, OSS, QSS or MAV). The application program then investigates the appropriate event structure until the causal event is discovered. The detail for each register is expanded in the following paragraphs, and in the command descriptions.

### 6.5.3.1 EEE 488.2 Mode

This develops the IEEE 488.1 model into an extended structure with more definite rules. These rules invoke the use of standard 'Common' messages and provide for devicedependent messages. A feature of the structure is the use of 'Event' registers, each with its own enabling register as shown in Fig. 6.2.

### 6.5.3.2 $\quad 9100$ Model Structure

The IEEE 488.2 Standard provides for an extensive hierarchical structure with the Status Byte at the apex, defining its bits 4,5 and 6 and their use as summaries of a Standarddefined event structure, which must be included if the device is to claim conformance with the Standard. The 9100 employs these bits as defined in the Standard.

Bits $0,1,2$ and 3 and 7 are available to the device designer; only bits 3 and 7 are used in the 9100 , and these are as defined by the SCPI standard.
It must be recognized by the application programmer that whenever the application program reads the Status Byte, it can only receive summaries of types of events, and further query messages will be needed to probe the details relating to the events themselves. For example: a further byte is used to expand on the summary at bit 5 of the Status Byte.

### 6.5.3.3 Status Byte Register

In this structure the Status Byte is held in the 'Status Byte Register'; the bits being allocated as follows:
Bits: $\mathbf{0}$ (DIO1), $\mathbf{1}$ (DIO2) and $\mathbf{2}$ (DIO3) are not used in the 9100 status byte. They are always false.
Bit 3 (DIO4) SCPI-defined Questionable Status Summary Bit (QSS)
Summarizes the state of the 'Questionable Status data', held in the 'Questionable Status register' (QSR), whose bits represent SCPI-defined and device-dependent conditions in the 9100. The QSS bit is true when the data in the QSR contains one or more enabled bits which are true; or false when all the enabled bits in the byte are false. The QSR and its data are defined by the SCPI Standard; they are described in Sub-Section 6.5.4.
Bit 4 (DIO5) IEEE 488.2-defined Message Available Bit (MAV)
The MAV bit helps to synchronize information exchange with the controller. It is true when a message is placed in the Output Queue; or false when the Output Queue is empty.
The common command $*$ CLS can clear the Output Queue, and the MAV bit 4 of the Status Byte Register; providing it is sent immediately following a 'Program Message Terminator'.

## Bit 5 (DIO6) IEEE 488.2-defined Standard Event Summary Bit (ESB)

Summarizes the state of the 'Event Status byte', held in the 'Event Status register' (ESR), whose bits represent IEEE 488.2-defined conditions in the device. The ESB bit is true when the byte in the ESR contains one or more enabled bits which are true; or false when all the enabled bits in the byte are false.

Bit 6 (DIO7) is the Master Status Summary Message (MSS bit), and is set true if one of the bits 0 to 5 or bit 7 is true (bits 0,1 and 2 are always false in the 9100).

Bit 7 (DIO4) SCPI-defined Operation Status Summary Bit (QSS)
Summarizes the state of the 'Operation Status data', held in the 'Operation Status register' (OSR), whose bits represent processes in progress in the 9100. The OSS bit is true when the data in the OSR contains one or more enabled bits which are true; or false when all the enabled bits in the byte are false. The OSR is described in Sub-Section 6.5.4.

## Reading the Status Byte Register

## *STB?

The common query: $*$ STB? reads the binary number in the Status Byte register. The response is in the form of a decimal number which is the sum of the binary weighted values in the enabled bits of the register. In the 9100 , the binary-weighted values of bits 0,1 and 2 are always zero.

### 6.5.3.4 Service Request Enable Register

The SRE register is a means for the application program to select, by enabling individual Status Byte summary bits, those types of events which are to cause the 9100 to originate an RQS. It contains a user-modifiable image of the Status Byte, whereby each true bit acts to enable its corresponding bit in the Status Byte.

## Bit Selector: *SRE phs Nrf

The common program command: *SRE phs Nrf performs the selection, where $N r f$ is a decimal numeric, whose binary decode is the required bit-pattern in the enabling byte.

For example:
If an RQS is required only when a Standard-defined event occurs and when a message is available in the output queue, then $N r f$ should be set to 48 . The binary decode is 00110000 so bit 4 or bit 5 , when true, will generate an RQS; but with this decode, even if bit 3 is true, no RQS will result. The 9100 always sets false the Status Byte bits 0 , 1 and 2, so they can never originate an RQS whether enabled or not.

## Reading the Service Request Enable Register

The common query: *SRE? reads the binary number in the SRE register. The response is in the form of a decimal number which is the sum of the binary-weighted values in the register. The binary-weighted values of bits 0,1 and 2 will always be zero.

## Note about the ERROR Queue

The Error Queue is a sequential memory stack. Each reportable error has been given a listed number and explanatory message, which are entered into the error queue as the error occurs. The queue is read destructively as a First-In/First-Out stack, using the query command SYSTem ERRor? to obtain a code number and message.

Repeated use of the query SYSTem ERRor? will read successive DeviceDependent, Command and Execution errors until the queue is empty, when the 'Empty' message (0, "No error") will be returned.

It would be good practice to repeatedly read the Error Queue until the 'Empty' message is returned.
The common command *CLS clears the queue.

### 6.5.3.5 IEEE 488.2-defined Event Status Register

The 'Event Status Register' holds the Event Status Byte, consisting of event bits, each of which directs attention to particular information. All bits are 'sticky'; ie. once true, cannot return to false until the register is cleared. This occurs automatically when it is read by the query: $* E S R ?$. The common command $*$ CLS clears the Event Status Register and associated error queue, but not the Event Status Enable Register.

Note that because the bits are 'sticky', it is necessary to read the appropriate subordinate register of the status structure in order to clear its bits and allow a new event from the same source to be reported.
The 'Event Status Register' bits are named in mnemonic form as follows:
Bit 0 Operation Complete (OPC)
This bit is true only if $*$ OPC has been programmed and all selected pending operations are complete. As the 9100 operates in serial mode, its usefulness is limited to registering the completion of long operations, such as self-test.

Bit 1 Request Control (RQC)
This bit is not used in the 9100. It is always set false.
Bit 2 Query Error (QYE)
QYE true indicates that the application program is following an inappropriate message exchange protocol, resulting in the following situations:

- Interrupted Condition. When the 9100 has not finished outputting its Response Message to a Program Query, and is interrupted by a new Program Message.
- Unterminated Condition. When the application program attempts to read a Response Message from the 9100 without having first sent the complete Query Message (including the Program Message Terminator) to the instrument.
- Deadlocked Condition. When the input and output buffers are filled, with the parser and the execution control blocked.
Bit 3 Device Dependent Error (DDE)
DDE is set true when an internal operating fault is detected, and the appropriate error message is added to the Error Queue. See the 'Note about the Error Queue' in the previous column.


## Bit 4 Execution Error (EXE)

An execution error is generated if the received command cannot be executed, owing to the device state or the command parameter being out of bounds. The appropriate error message is added to the Error Queue. See the 'Note about the Error Queue' in the previous column.

Bit 5 Command Error (CME)
CME occurs when a received bus command does not satisfy the IEEE 488.2 generic syntax or the device command syntax programmed into the instrument interface's parser, and so is not recognized as a valid command. The appropriate error message is added to the Error Queue. See the 'Note about the Error Queue' on the previous page.

Bit 6 User Request (URQ)
This bit is not used in the 9100. It is always set false.
Bit 79100 Power Supply On (PON)
This bit is set true only when the Line Power has just been switched on to the 9100 , the subsequent Power-up Selftest has been completed successfully, and the 9100 defaults into Manual mode at Power-on. (If the Power-on default is Procedure mode, remote operation is not available. If the selftest is unsuccessful, the 9100 will report the fact in Test mode, which also does not permit remote operation).

Whether or not an SRQ is generated by setting bit 7 true, depends on the previouslyprogrammed 'Power On Status Clear' message $*$ PSC phs Nrf:

- For an $N r f$ of 1, the Event Status Enable register would have been cleared at power on, so PON would not generate the ESB bit in the Status Byte register, and no SRQ would occur at power on.
- If $N r f$ was zero, and the Event Status Enabling register bit 7 true, and the Service Request Enabling register bit 5 true; a change from Power Off to Power On will generate an SRQ. This is only possible because the enabling register conditions are held in non-volatile memory, and restored at power on.
This facility is included to allow the application program to set up conditions so that a momentary Power Off followed by reversion to Power On (which could upset the 9100 programming) will be reported by SRQ. To achieve this, the Event Status register bit 7 must be permanently true (by *ESE phs Nrf, where $N r f \geq 128$ ); the Status Byte Enable register bit 5 must be set permanently true (by command *SRE phs Nrf, where $N r f$ lies in one of the ranges 32-63, 96-127, 160-191, or 224-255); Power On Status Clear must be disabled (by *PSC phs $N r f$, where $N r f=0$ ); and the Event Status register must be read destructively immediately following the Power On SRQ (by the common query *ESR?).


### 6.5.3.6 Standard Event Status Enable Register

The ESE register is a means for the application program to select, from the positions of the bits in the standard-defined Event Status Byte, those events which when true will set the ESB bit true in the Status Byte. It contains a user-modifiable image of the standard Event Status Byte, whereby each true bit acts to enable its corresponding bit in the standard Event Status Byte.

## Bit Selector: *ESE phs Nrf

The program command: *ESE phs Nrf performs the selection, where Nrf is a decimal numeric, which when decoded into binary, produces the required bit-pattern in the enabling byte.

For example:
If the ESB bit is required to be set true only when an execution or device-dependent error occurs, then $N r f$ should be set to 24 . The binary decode is 00011000 so bit 3 or bit 4 , when true, will set the ESB bit true; but when bits $0-2$, or 5-7 are true, the ESB bit will remain false.

## Reading the Standard Event Enable Register

The common query: *ESE? reads the binary number in the ESE register. The response is a decimal number which is the sum of the binary-weighted values in the register.

### 6.5.3.7 The Error Queue

As errors in the 9100 are detected, they are placed in a 'first in, first out' queue, called the 'Error Queue'. This queue conforms to the format described in the SCPI Command Reference (Volume 2) Chapter 19, para 19.7, although errors only are detected. Three kinds of errors are reported in the Error Queue, in the sequence that they are detected:

## Command Errors, Execution Errors and Device-Specific errors

## Reading the Error Queue

The queue is read destructively as described in the SCPI Command Reference, using the query command SYSTem ERRor? to obtain a code number and error message. The query SYSTem ERRor? can be used to read errors in the queue until it is empty, when the message '0, No Error' will be returned.

### 6.5.4 <br> 9100 Status Reporting - SCPI Elements

### 6.5.4.1 General

In addition to IEEE 488.2 status reporting the 9100 implements the Operation and Questionable Status registers with associated 'Condition', 'Event' and 'Enable' commands. The extra status deals with current operation of the instrument and the quality of operations.

The structure of these two registers is detailed in Fig. 6.2, together with the nature of the reported events. Access to the registers is detailed in the STATus subsystem of SubSection 6.6 of this handbook.

### 6.5.4.2 SCPI Status Registers

The SCPI states are divided into two groups, reporting from the Operation or Questionable Status event register. Each Status register has its own 'Enable' register, which can be used as a mask to enable bits in the event register itself, in a similar way to that set by the *ESE command for the Standard Event status Register (ESR).

Each Status Register is associated with its own third 'Condition' register (not illustrated in Fig. 6.2), in which the bits are not 'sticky', but are set and reset as the internal conditions change.

Each Enable Register can be commanded to set its mask to enable selected bits in the corresponding Event Register. All registers (Event, Enable and Condition) can be interrogated by appropriate 'Queries' to divulge their bits' states.

### 6.5.4.3 Reportable SCPI States

## Operation Status Event Register

The following 'sticky' bits are set by their associated conditions:

| bit 0 | CALIBRATING: | a capacitance self-calibration operation is in progress. |
| :--- | :--- | :--- |
| bit 8 | TESTING: | the instrument is performing a self test. |
| bit 9 | PRETESTING: | the instrument is performing a power-up self test. |

## Questionable Status Event Register

The following 'sticky' bits are set by their associated conditions:
bit 4 TEMPerature: Thermocouple Reference Junction conditions doubtful
bit 9 INV OHM CURR 1: High/Low Current warning - outside specification
bit 10 INV OHM CURR 2: High/Low Current warning - change setting

### 6.6 9100 SCPI Language - Commands and Syntax

The command subsystems are placed in alphabetical order.

### 6.6.1 Introduction

This Sub-Section lists and describes the set of SCPI-compatible remote commands used to operate the 9100 .
To provide familiar formatting for users who have previously used the SCPI reference documentation, the command descriptions are dealt with in a similar manner. In particular, each sub-system's documentation starts with a short description, followed by a table showing the complete set of commands in the sub-system; finally the effects of individual keywords and parameters are described. Some extra identification of style and syntax is detailed in paras 6.6.1.1 and 6.6.1.2 to clarify shorthand meanings.

### 6.6.1.1 SCPI Syntax and Styles

Where possible the syntax and styles used in this section follow those defined by the SCPI consortium. The commands on the following pages are broken into three columns; the KEYWORD, the PARAMETER FORM, and any NOTES.
The KEYWORD column provides the name of the command. The actual command consists of one or more keywords since SCPI commands are based on a hierarchical structure, also known as the tree system.
Square brackets ([]) are used to enclose a keyword that is optional when programming the command; that is, the 9100 will process the command to have the same effect whether the optional node is omitted by the programmer or not.
Letter case in tables is used to differentiate between the accepted shortform (upper case) and the long form (upper and lower case). The PARAMETER FORM column indicates the number and order of parameter in a command and their legal value. Parameter types are distinguished by enclosing the type in angle brackets ( <> ). If parameter form is enclosed by square brackets ( [ ] ) these are then optional (care must be taken to ensure that optional parameters are consistent with the intention of the associated keywords). The vertical bar ( $\mid$ ) can be read as "or" and is used to separate alternative parameter options.

### 6.6.1.2 Legend

<DNPD> = Decimal Numeric Program Data, used to identify numerical information needed to set controls to required values. The numbers should be in ' $N r f$ ' form as described in the IEEE 488.2 Standard Specification.
$=$ Character Program Data. This normally represents alternative groups of unique 'literate' parameter names, available for the same keyword. In the notation the set of alternatives will follow the <CPD> in the Parameter Form column of the Sub-System table, enclosed in a pair of braces. For example, in the OUTPut sub-system, the compound command header (keyword): OUTPut: COMPensation is followed by the parameter form <CPD> $\{O N|O F F| 0 \mid 1\}$. The <CPD> gives the denomination of 'Character' program data, and $\{O N|O F F| O \mid 1\}$ gives the actual characters to be used to command each unique parameter.
$=$ String Program Data. This is a string of variable literate characters which will be recognized by the internal 9100 software. They are used for such inputs as passwords, serial numbers and date/time.
$=$ Indicate query commands with no associated command form, and no attached parameters.
(for example: CALibration:TRIGger?).
$=$ All commands which may include parameters in the command form, but also have an additional query form without parameters.
(for example: OUTPut: COMPensation(?) <CPD>\{HIGHi|LOWi\})
The response from this query will be one of the parameters listed in association with the command.

This subsystem is used to calibrate the functions and hardware ranges of the 9100 . This will correct for any system errors due to drift or ageing effects.
Before any calibration can take place, two security levels must be set. First, there is a switch on the 9100 itself that must be set to CAL ENABLE. Having done this, the calibration password command must be sent.
Once entered into Calibration mode, the commands present in the table at 6.6.2.1 are enabled.

### 6.6.2.1 CALibration Subsystem Table

Keyword Parameter Form

## Notes

CALibration
: SECure
: PASSword
:EXIT
:TARGet
:TRIGger?
:SPECial?
: CJUNction?

```
<SPD>
[<SPD>,<CPD> {PRD7|PRD14|PRD30|PRD60}]
<DNPD>,<DNPD> [, <DNPD>]
```

[query only]
Final Width $=215 \mathrm{~mm}$
6.6.2.2 CAL : SEC:PASS <SPD>

## Purpose

This command is used to gain access to Calibration mode. The <SPD> must be the correct 'Calibration' password registered in the 9100 software. The calibration password can be changed only in Configuration mode from the 9100 front panel.
(Refer to Volume 1 of this User's Handbook, Section 3, Paras 3.3.2.11 and 3.2.2.22).

### 6.6.2.3 CAL:SEC:EXIT [<SPD>, <CPD> \{PRD7|PRD14|PRD30|PRD60\}]

## Purpose

This command is used to switch off Calibration mode, cancelling any set CAL:TARG command and protecting the calibration by positively disabling the calibration commands. Parameters in the command permit a user optionally to date-stamp the calibration, record the next-due calibration date, and set up an advance warning for that calibration. Certain Functions are not available in Calibration Mode (such as Conductance and Logic Pulses/Levels, for which calibration is not required). When finishing a calibration procedure, it is necessary to exit from Calibration mode in order to access these functions.

- The <SPD> must be the due date of the next calibration for the 9100. It must conform to the format decided by the SYStem FORmat <spd> command.
- In the <CPD>, PRDXX gives the required number of days advance warning of the cal due date.
(Refer to Section 10, Paras 10.3.6).


### 6.6.2.4 CAL:TARG <DNPD>, <DNPD> [, <DNPD>]

## Purpose

For each calibration operation, the required calibration point (factor) must be targetted (Refer to Section 10, Paras 10.3.4). This command permits the user to define three parameters associated with the calibration point in the current operation:

- The first <DNPD> is an integer from 1 to 6 , allocated to the calibration point at which calibration is intended. This will be one of those listed on the Calibration mode screen, in 'Target State', for the corresponding function and hardware range.
- The second $<$ DNPD $>$ is a value which will determine the required hardware range (amplitude) of the 9100 for that calibration point.
- The third, optional, <DNPD> is a value which will determine the required hardware range (frequency) of the 9100 for that calibration point.

For example when the 9100 is in AC Voltage at 30 V 1 kHz :

$$
\text { CAL:TARG } 1,29.001,1.05
$$

indicates that calibration of point 1 is required, at a voltage of 29.001 V and a frequency of 1.05 kHz .
Once a target has been set, the 9100 adjustment is restricted to values within the selected hardware voltage span and frequency band. In order to release this restriction, one of the following commands must be sent:

TRIG?, EXIT or a new TARG command
Any error which occurs will also release the restriction.
6.6.2.5

CAL : TRIG?

## Purpose

After the parameters are set for calibration at a single calibration point, this command initiates the internal calibration process.

## Response

If the calibration operation is a success then the command returns a' $0^{\prime}$. If the process fails for any reason, then a' 1 ' is returned and an error message is put in the error queue.

### 6.6.2.6 CAL : SPEC?

## Purpose

This command characterizes the instrument's main Digital-to-Analog Converter.

## Response

The process takes approximately 15 minutes to complete. If the characterization operation is a success then the command returns $a^{\prime} 0$ '. If the process fails for any reason, then a ' 1 ' is returned and an error message is put in the error queue.

### 6.6.2.7 CAL : CJUN? <dnpd>

## Purpose

To obtain a calibration factor from an external measurement of the temperature of the reference junction in its pod, and a similar internal measurement which is triggered by this command..
The <dnpd> MUST be supplied and should be the externally-measured temperature of the pod.
For successful calibration, the pod MUST be fitted and the external measurement MUST be supplied with the command.
This is the remote equivalent of the manual calibration of the pod detailed in Section 10, paras 10.2.5. Identification of the association of the pod with a particular host 9100 unit should be recorded as for the manual case (paras 10.2.5.7)

## Response

If the calibration operation is a success then the command returns a ${ }^{\prime} 0^{\prime}$. If the process fails for any reason, then a ' 1 ' is returned and an error message is put in the error queue.

### 6.6.3

OUTPut Subsystem
This subsystem is used to select the output connections of the 9100 , switch the output on and off, and switch the lead compensation on and off.

### 6.6.3.1 OUTPut Subsystem Table

Keyword Parameter Form
oUTPut
[:STATe] (?) <CPD>\{ON|OFF|0|1\}
:COMPensation(?) <CPD>\{ON|OFF|0|1\}
:ISELection(?) <CPD>\{HIGHi|HI50turn|HI10turn|LOWi\}

### 6.6.3.2 OUTP [:STAT] (?) <CPD> $\{\mathrm{ON}|\mathrm{OFF}| 0 \mid 1\}$

## Purpose

This command turns the 9100 output on and off.

- ON or 1 will set the output on
- OFF or 0 will set the output off


## Response to Query Version

The 9100 will return ON if output is on, or OFF if output is off.
6.6.3.3 OUTP : COMP (?) <CPD> $\{O N|O F F| 0 \mid 1\}$

## Purpose

This command switches the output connections for 4 -wire/2-wire in the impedance functions.

## Impedance Functions:

Resistance, Conductance, Capacitance and PRT Temperature.

## Response to Query Version

The 9100 will return ON if compensation is on (4-wire), or OFF if compensation is off (2-wire).

### 6.6.3.4 OUTP:ISEL(?) <CPD>\{HIGHi|HI50|HI10|LOWi\}

## Purpose

The I+ Output in Current function can be passed out via the unguarded front panel I+ terminal, or on a guarded line (pin 8) through the D-type socket ('Signal Output' J109) beneath the terminals. Pin 7 of J109 is connected to internal Guard shields for this purpose, and is available for external guard connection. The return is always via the front panel main I- terminal.
The front panel I+ terminal can carry all DC currents and AC currents up to the maximum -20A to +20 A output (refer to Volume 1, Section 4, paras 4.5.5.3 for time limitations). Pin 8 of J109 is limited to -1 A to +1 A output.

OUTP : ISEL HIGH switches current outputs via the front panel I+ terminal,
OUTP : ISEL HI50 (Option 200) switches current outputs via the front panel I+ terminal, and provides equivalent currents of $\pm(16.0 \mathrm{~A}$ to 1000 A$)$ into the 50 -turn current coil.
OUTP : ISEL HI10 (Option 200) switches current outputs via the front panel I+ terminal, and provides equivalent (Option 200) switches current outputs via the front pan
currents of $\pm(3.2 \mathrm{~A}$ to 200 A ) into the 10 -turn current coil.
OUTP:ISEL LOW switches current outputs via J109 pin 8.

## Response to Query Version

The 9100 will return HIGH/HI50/HI10/LOW to match the active programming parameter.

# This subsystem is used to select the sources of 9100 output . 

6.6.4.1 SOURce Subsystem Table

| Keyword | Parameter Form | Notes |
| :---: | :---: | :---: |
| [SOURce] |  |  |
| :FUNCtion |  |  |
| [:SHAPe] (?) <CPD> ${ }^{\text {d }}$ ( | <CPD> DC $^{\text {S }}$ SINusoid\|PULSe|SQUare|IMPulse|TRIangle|TRAPezoid|SYMSquare\} |  |
| :VoLTage |  |  |
| [:LEVE]] |  |  |
| [:IMMediate] |  |  |
| [:AMPLitude] (?) | <DNPD> |  |
| : HIGH(?) | <DNPD> |  |
| :LOW(?) | <DNPD> |  |
| : CURRent |  |  |
| [:LEVEl] |  |  |
| [:IMMediate] |  |  |
| [:AMPLitude] (?) | <DNPD> |  |
| :RESistance |  |  |
| [:LEVE] $]$ |  |  |
| [:IMMediate] |  |  |
| [:AMPLitude] (?) | <DNPD> |  |
| :UUT_I (?) | <CPD> [LOW\|HIGH|SUPer\} |  |
| : Conductance |  |  |
| [:LEVE] ] |  |  |
| [:IMMediate] |  |  |
| [:AMPLitude] (?) | <DNPD> |  |
| :UUT_I (?) |  |  |
| :CAPacitance |  |  |
| [:LEVEl] |  |  |
| [:IMMediate] |  |  |
| [:AMPLitude] (?) | <DNPD> |  |
| :UUT_I (?) | <CPD> \{LOW\|SUPer\} |  |
| :FREQuency |  |  |
| [:CW\|FIXed] (?) | <DNPD> |  |
| : PHASe |  |  |
| [:ADJust] (?) | <DNPD> |  |
| : INPut |  |  |
| [:STATE] (?) |  |  |
| : OUTPut |  |  |
| [:STATe] (?) | <CPD> (ON\|OFF|O|1\} |  |


| [SOURce] (Contd) |  |
| :---: | :---: |
| : PULSe |  |
| : PERiod(?) | <DNPD> |
| :WIDth(?) | <DNPD> |
| : DCYCle(?) | <DNPD> |
| :TEMPerature |  |
| : UNITs (?) | <CPD> ${ }^{\text {C }}$ \|CEL $\mid$ F $\mid$ FAH $\mid$ K $\}$ |
| : SCALe (?) | <CPD> TS68\|TS90\} |
| : THERmocouple |  |
| [:LEVEl] |  |
| [:IMMediate] |  |
| [:AMPLitude] (?) | <DNPD> |
| :TYPE (?) | <CPD> $\left.\mathrm{B}^{\text {\| }} \mathrm{C}\|\mathrm{E}\| \mathrm{J}\|\mathrm{K}\| \mathrm{N}\|\mathrm{R}\| \mathrm{S} \mid \mathrm{T}\right\}$ |
| : PRT |  |
| [:LEVEl] |  |
| [:IMMediate] |  |
| [:AMPLitude] (?) | <DNPD> |
| :TYPE (?) | <CPD> \{PT385\|PT392\} |
| :NRESistance(?) | <DNPD> |
| :UUT_I (?) | <CPD> \{LOW\|HIGH|SUPer\} |
| : CONTinuity |  |
| [:LEVEl] |  |
| [:IMMediate] |  |
| [:AMPLitude] (?) | <DNPD> |
| : TCURrent? |  |
| : INSulation |  |
| [:LEVEl] |  |
| [:IMMediate] |  |
| [:AMPLitude] (?) | <DNPD> |
| :UUT_I (?) | <CPD> \{HIGH\|SUPer\} |
| : TVOLtage? |  |
| : TCURrent? |  |

## Note to the [SOURce] Subsystem Table

Many optional keywords are included in the table; shown in square brackets, as required by the SCPI reference document. The structure of the command set is such that in all cases, these optional keywords can be omitted.

## Notes about Types of Command Separators

The [SOURce] subsystem has a complex tree structure. To clarify descriptions (as, for instance, in the table overleaf), examples of branching are referred to the root. In the table, when transferring from, say, a VOLT HIGH command to a VOLT LOW command, the command string returns to the root, so that rather than using the valid short-cut ; branching separator, it is shown as returning to the root by a ; : separator.

This does not mean that valid short-cut 'program message unit' separators cannot be used, but merely that we are defining the commands in full, to avoid confusion.

### 6.6.4.2

<CPD> \{DC|SIN|PULS|SQU|IMP|TRI|TRAP|SYMS \}

## Purpose

Defines the waveshape of the required output. In certain cases this also steers the 9100 towards the required source. This is necessary to select a 9100 source in a particular group, if the present 9100 source lies outside that group.
For example:
DC Voltage and DC Current are listed below in Group 2. To select either of these when neither of Group 2 is already selected, then the command FUNC DC must be used before selecting Voltage or Current.

For those users who are familiar with local (front panel) operation of the 9100, the relationships between the local Function selections and the corresponding remote commands are given in the following table:

| [SOURce] Command Group | Equivalent 9100 Local Function | Remote Commands |
| :---: | :---: | :---: |
| $1 \mathrm{a}$ <br> b <br> c <br> d <br> e | Resistance <br> Conductance <br> Capacitance <br> PRT Temp. <br> T'coupl. Temp. | ```RES <DNPD> or RES <DNPD>;:RES:UUT_I <CPD> COND <DNPD> or COND <DNPD>;:COND:UUT_I <CPD> CAP <DNPD> or CAP <DNPD>;:CAP:UUT_I <CPD> TEMP:UNIT <CPD>;:TEMP:SCAL <CPD>;:TEMP:PRT <DNPD> or TEMP:UNIT <CPD>;:TEMP:SCAL <CPD>;:TEMP:PRT <DNPD>;:TEMP:PRT:UUT_I <CPD> TEMP:UNIT <CPD>;:TEMP:THER <DNPD>``` |
| $\begin{array}{ll} 2 & a \\ & b \\ & c \end{array}$ | DC Voltage Logic Levels DC Current | FUNC DC;:VOLT <DNPD> <br> FUNC DC;:VOLT <DNPD> <br> FUNC DC;:CURR <DNPD> |
| $\begin{array}{ll} 3 \mathrm{a} \\ & \mathrm{~b} \end{array}$ | AC Voltage AC Current | FUNC \{SIN\|IMP|TRI|TRAP|SYMS\};:VOLT <DNPD>; :FREQ <DNPD> FUNC \{SIN\|IMP|TRI|TRAP|SYMS\};:CURR <DNPD>; :FREQ <DNPD> |
| 4 | Frequency | FUNC SQU;:FREQ <DNPD>;:VOLT:HIGH <DNPD>;:VOLT:LOW <DNPD> |
| $\begin{array}{ll} 5 & a \\ & b \\ & b \end{array}$ | Mark/Period \% Duty Logic Pulses | FUNC PULS;:PULS:PER <DNPD>;:PULS:WID <DNPD>;:VOLT:HIGH <DNPD>;:VOLT:LOW <DNPD> FUNC PULS;:PULS:PER <DNPD>;:PULS:DCYC <DNPD>;:VOLT:HIGH <DNPD>;:VOLT:LOW <DNPD> FUNC PULS;:PULS:PER <DNPD>;:PULS:WID <DNPD>;:VOLT:HIGH <DNPD>;:VOLT:LOW <DNPD> |

Notes:
Group 1 No FUNC steering is required. The Thermocouple Temperature source (1e) is included in the same group as the other (PRT) Temperature source. Group 2 Steering command: FUNC DC is required. The remote equivalent of the local 'Logic Levels' Function uses the same commands as those for the main local DC Voltage Function.
Group 3 Steering command: FUNC \{SIN|IMP|TRI|TRAP|SYMS\} is required. All alternative waveshapes shown are available only in this group. Group 4 Steering command: FUNC SQU is required. 'Hz (Frequency)' employs a fixed $50 \%$ duty cycle.
Group 5 Steering command: FUNC PULS is required. All local equivalents include variable Mark/Period ratio.
N.B. The groups of [SOURce] commands, listed in the table, are not required by SCPI protocol, they have been devised specially for this description only for clearer explanation.

## Function Changes and Parameter Defaults

The values set as parameters are not retained on change of Equivalent Local Function (ELF), as indicated in the table
When the 9100 is transferred from, say, $E L F \mathbf{1 a}$ to $E L F \mathbf{1 b}$, the programmable parameters of $E L F \mathbf{1 a}$ will be set to default values, and must be re-programmed on re-entry if different values are required.

## <CPD>

The 'character program data' determines the waveshape of the output signal. It can be chosen from eight alternatives:
DC Determines that subsequent selection of VOLT or CURR will choose DC hardware for the output voltage or current. Voltage or Current levels will be set subsequently using the VOLT <DNPD> or CURR <DNPD> commands.

SINusoid Subsequent selection of VOLT or CURR will choose AC hardware for the output voltage or current. Voltage or Current RMS values will be set using the VOLT <DNPD> or CURR <DNPD> commands. Frequency values will be set using the FREQ <DNPD> command.

SQUare Selects a pulsed voltage output, and determines that the mark/period ratio will be 0.5 for any related FREQ selection. High and low voltage levels will be set to default values of +5 V and 0 V unless otherwise set using the VOLT HIGH and VOLT LOW commands
PULSe Selects a pulsed voltage output and determines that the mark/period ratio will be set by selections of PULS PER, together with PULS WID or PULS DCYC. High and low voltage levels will be set to default values of +5 V and 0 V unless otherwise set using the VOLT HIGH and VOLT LOW commands.

## IMPulse|TRIangle|TRAPezoid|SYMSquare

Subsequent selection of VOLT or CURR will choose AC hardware for the output voltage or current, with the 'Impulse, Triangular, Trapezoidal or Symmetrical Square' waveshape (refer to Volume 1, Section 4, paras 4.4.3.4 and 4.4.6.4). Voltage or Current RMS values will be set using the VOLT <DNPD> or CURR <DNPD> commands. Frequency values will be set using the FREQ <DNPD> command.

## Examples of using the FUNC element:

An example command message to select a Group 2 source of +10.5 V from outside Group 2 would be:

$$
\text { FUNC DC;:VOLT } 10.5
$$

Alternatively, to select a Group 3 sinusoidal current source of 200 mA at 1 kHz from outside Group 3:
FUNC SIN;:CURR 200E-3;:FREQ 1E3

To select (from outside Group 5) a pulsed signal of period $200 \mu$ s and duty cycle $60 \%$, switching between +3.5 V and -1.5 V : FUNC PULS;:PULS:PER 2E-4;:PULS:DCYC 60;:VOLT:HIGH 3.5;:VOLT:LOW -1.5

## Sources in the Same Group

When selecting a source from within the same group as the previous [SOURce] command, it is not necessary to prefix the FUNC command.

## Response to Query Version

The 9100 will return the appropriate <CPD> from the selection \{DC|SIN|PULS |SQU|IMP|TRI|TRAP|SYMS\} which represents the present source 'shape'. If the 9100 is programmed in one of the impedance functions (Group 1 in the table), then it will return NONE.

### 6.6.4.3 <br> [SOUR](FUNC%5B:SHAP%5D(?)): VOLT [:LEVE][:IMM] [:AMPL] (?) <br> <DNPD>

Purpose
This command selects either DC or AC Voltage hardware, dependent upon the DC or SIN | IMP \| TRI \| TRAP | SYMS parameter included in the most-recent FUNC command.

## <DNPD>

The 'decimal numeric program data' is a number which sets the required output voltage, expressed in units of DC or RMS AC Volts. It will automatically choose the 'best' hardware range for the defined voltage output. The 9100 will accept signed or unsigned positive values for DC Voltage.
For details of local operation and parameter limitations, refer to Volume 1, Section 4, Sub-Sections 4.3 (DCV), 4.4 (ACV) or 4.17 (Logic Levels).

## Response to Query Version

The instrument will return the present DC or AC voltage output value, dependent upon the DC or SIN \| IMP \| TRI | TRAP | SYMS parameter implicit, or included, in the most-recent FUNC command. The returned number will be in standard scientific format (for example: $-200 \mu \mathrm{~V}$ DC would be returned as $-2.0 \mathrm{E}-4$ - positive numbers, however, are unsigned)

### 6.6.4.4 [SOUR](FUNC%5B:SHAP%5D(?)):VOLT[:LEVE][:IMM]:HIGH(?) <DNPD>

## Purpose

This command sets the high (most positive) voltage level for the square or pulsed voltage output, which has been selected by the SQU or PULS parameter included in the most-recent FUNC command.

## <DNPD>

The 'decimal numeric program data' is a number which sets the required high-level (most-positive) output voltage of the programmed waveshape, expressed in units of Volts. It will automatically choose the 'best' hardware range for the defined voltage output, in conjunction with the corresponding VOLT: LOW command for the same waveshape.
The value of <DNPD> cannot be equal to or more negative than that sent as the <DNPD> with the corresponding VOLT: LOW command for the same waveshape. The 9100 will accept signed or unsigned positive values.

For details of local operation and parameter limitations, refer to Volume 1, Section 4, Sub-Sections 4.9 (Frequency), 4.10 (Mark/ Period), 4.11 (\% Duty Cycle) or 4.16 (Logic Pulses).

## Response to Query Version

The instrument will return the present high level voltage output value, associated with the SQU or PULS parameter implicit, or included, in the query command. The returned number will be in standard scientific format (for example: +200 mV would be returned as $2.0 \mathrm{E}-1$ - positive numbers are unsigned).

### 6.6.4.5 [SOUR](FUNC%5B:SHAP%5D(?)):VOLT [:LEVE][:IMM]:LOW(?) <DNPD>

## Purpose

This command sets the low (most negative) voltage level for the square or pulsed voltage output, which has been selected by the SQU or PULS parameter included in the most-recent FUNC command. Separate values are recorded for SQU and PULS functions.

## <DNPD>

The 'decimal numeric program data' is a number which sets the required low-level (most-negative) output voltage of the programmed waveshape, expressed in units of Volts. It will automatically choose the 'best' hardware range for the defined voltage output, in conjunction with the corresponding VOLT:HIGH command for the same waveshape.
The value of <DNPD> cannot be equal to or more positive than that sent as the <DNPD> with the corresponding VOLT:HIGH command for the same waveshape. The 9100 will accept signed or unsigned positive values.
For details of local operation and parameter limitations, refer to Volume 1, Section 4, Sub-Sections 4.9 (Frequency), 4.10 (Mark/ Period), 4.11 (\% Duty Cycle) or 4.16 (Logic Pulses).

## Response to Query Version

The instrument will return the present low level voltage output value, associated with the SQU or PULS parameter implicit, or included, in the query command. The returned number will be in standard scientific format (for example: +200 mV would be returned as $2.0 \mathrm{E}-1$ - positive numbers are unsigned)

### 6.6.4.6 [SOUR](FUNC%5B:SHAP%5D(?)) : CURR [ :LEVE] [: IMM] [:AMPL] (?) <DNPD>

## Purpose

This command selects either DC or AC Current hardware, dependent upon the DC or SIN \| IMP \| TRI \| TRAP \| SYMS parameter included in the most-recent FUNC command.

## <DNPD>

The 'decimal numeric program data' is a number which sets the required output current, expressed in units of DC or RMS AC Amps.
It will automatically choose the 'best' hardware range for the defined current output. The 9100 will accept signed or unsigned positive values for DC Current.
For details of local operation and parameter limitations, refer to Volume 1, Section 4, Sub-Sections 4.5 (DCI) or 4.6 (ACI).

## Response to Query Version

The instrument will return the present DC or AC current output value, dependent upon the DC or SIN \| IMP \| TRI | TRAP | SYMS parameter implicit, or included, in the most-recent FUNC command. The returned number will be in standard scientific format (for example: $-200 \mu \mathrm{~A} D C$ would be returned as $-2.0 \mathrm{E}-4$ - positive numbers, however, are unsigned)

### 6.6.4.7 <br> [SOUR](FUNC%5B:SHAP%5D(?)):RES [:LEVE] [:IMM] [:AMPL] (?) <br> <DNPD>

## Purpose

This command selects Resistance hardware.

## <DNPD>

The 'decimal numeric program data' is a number which sets the required output resistance, expressed in units of Ohms. It will automatically choose the 'best' hardware range for the defined resistance output.

For details of local operation and parameter limitations, refer to Volume 1, Section 4, Sub-Section 4.7 (Resistance).

## Response to Query Version

The instrument will return the present resistance output value. The returned number will be in standard scientific format (for example: $200 \mathrm{k} \Omega$ would be returned as 2.0 E 5 )

### 6.6.4.8 [SOUR](FUNC%5B:SHAP%5D(?)):RES:UUT_I (?) <CPD> \{LOW|HIGH|SUPer \}

## Purpose

In the synthesized resistance technology used in the 9100 , the current sourced from the UUT must fall within certain spans of values for each commanded resistance value. For UUTs producing source currents which are larger than the values in the 'Low' (default) span, the greater current can be accommodated by selecting 'HIGH' or 'SUPER'.
The RES: UUT_I \{LOW|HIGH|SUPer\} command is used to switch between the three current configurations. There is no default setting; refer to Volume 1 of this User's Handbook, Section 4, Sub-section 4.7, paras 4.7.5.7 for a description of UUT_I current tracking during Resistance span changes.

## <CPD>

The 'character program data' performs the required action. Refer to Volume 1, Section 4, paras 4.7.5.7, for a description of the current limits and output voltage limitation.

- LOW will select the UUT source current 'Low' limits.
- HIGH will select the UUT source current 'High' limits.
- SUPer will select the UUT source current 'Super' limits.


## Response to Query Version

The 9100 will return either LOW, HIGH or SUP, dependent on the active limits selection.

### 6.6.4.9 [SOUR](FUNC%5B:SHAP%5D(?)) : COND [:LEVE][:IMM] [:AMPL] (?) <DNPD>

## Purpose

This command selects Conductance hardware.

## <DNPD>

The 'decimal numeric program data' is a number which sets the required output conductance, expressed in units of Siemens. It will automatically choose the 'best' hardware range for the defined conductance output.
For details of local operation and parameter limitations, refer to Volume 1, Section 4, Sub-Section 4.8 (Conductance).

## Response to Query Version

The instrument will return the present conductance output value. The returned number will be in standard scientific format (for example: $200 \mu \mathrm{~S}$ would be returned as $2.0 \mathrm{E}-4$ )

### 6.6.4.10 [SOUR](FUNC%5B:SHAP%5D(?)) : COND:UUT_I (?) <CPD> \{LOW|HIGH|SUPer\}

## Purpose

In the synthesized conductance technology used in the 9100, the current sourced from the UUT must fall within certain spans of values for each commanded conductance value. For UUTs producing source currents which are larger than the values in the 'Low' (default) span, the greater current can be accommodated by selecting 'HIGH' or 'SUPER'.
The COND:UUT_I \{LOW|HIGH|SUPer\} command is used to switch between the three current configurations. There is no default setting; refer to Volume 1 of this User's Handbook, Section 4, Sub-section 4.8, paras 4.8.5.7 for a description of UUT_I current tracking during Conductance span changes.
<CPD>
The 'character program data' performs the required action. Refer to Volume 1, Section 4, paras 4.8.5.7, for a description of the current limits and output voltage limitation.

- LOW will select the UUT source current 'Low' limits.
- HIGH will select the UUT source current 'High' limits.
- SUPer will select the UUT source current 'Super' limits.


## Response to Query Version

The 9100 will return either LOW, HIGH or SUP, dependent on the active limits selection.

## Purpose

This command selects Capacitance hardware.

## <DNPD>

The 'decimal numeric program data' is a number which sets the required output capacitance, expressed in units of Farads. It will automatically choose the 'best' hardware range for the defined capacitance output.

For details of local operation and parameter limitations, refer to Volume 1, Section 4, Sub-Section 4.13 (Capacitance).

## Response to Query Version

The instrument will return the present capacitance output value. The returned number will be in standard scientific format (for example: 200 nF would be returned as $2.0 \mathrm{E}-7$ ).

### 6.6.4.12 [SOUR](FUNC%5B:SHAP%5D(?)) : CAP : UUT_I (?) <CPD> \{LOW|SUPer\}

## Purpose

In the synthesized capacitance technology used in the 9100, the current sourced from the UUT must fall within certain spans of values for each commanded capacitance value. For UUTs producing source currents which are larger than the values in the 'Low' (default) span, the greater current can be accommodated by selecting 'SUPER'.
The CAP:UUT_I \{LOW|SUPer\} command is used to switch between the two current configurations (refer to Volume 1 of this User's Handbook, Section 4, Sub-section 4.7, paras 4.7 .5 .7 for a description of UUT-I levels). There is no default setting.
Most capacitance spans do not allow SUP. Thus if SUP is already selected, and a transition is made to a capacitance span for which it is not available, then LOW will be enforced.

## <CPD>

The 'character program data' performs the required action. Refer to Volume 1, Section 4, paras 4.13.5.7, for a description of the current limits and output voltage limitation.

- LOW will select the UUT source current 'Low' limits.
- SUPer will select the UUT source current 'Super' limits.


## Response to Query Version

The 9100 will return either LOW or SUP, dependent on the active limits selection.

### 6.6.4.13 [SOUR](FUNC%5B:SHAP%5D(?)) :FREQ[:CW|FIX] (?) <DNPD>

## Purpose

This command is used to set one of three frequency parameters, each associated with either 'AC Voltage' function, 'AC Current' function or 'Hz' (Frequency) function.
For Example:
An 'AC Voltage' function output is programmed by:

$$
\text { FUNC:\{SIN|IMP|TRI|TRAP|SYMS\};:VOLT <DNPD>;:FREQ <DNPD> }
$$

A (squarewave) 'Hz' (Frequency) function output is programmed by:
FUNC SQU;:FREQ <DNPD>;:VOLT:HIGH <DNPD>;:VOLT:LOW <DNPD>
An 'AC Current' function output is programmed by:
FUNC: \{SIN|IMP|TRI|TRAP|SYMS\};:CURR <DNPD>; :FREQ <DNPD>

## <DNPD>

The 'decimal numeric program data' is a number which sets the required output frequency of the selected operation, expressed in units of Hertz. It will automatically choose the 'best' hardware range for the defined frequency of output.

For details of local operation and parameter limitations, refer to Volume 1, Section 4, Sub-Section 4.9 (Frequency).

## Response to Query Version

The instrument will return the present output frequency value for the selected operation, dependent upon the SIN or SQU parameter implicit, or included, in the most-recent FUNC command, and the most-recent VOLT or CURR command. The returned number will be in standard scientific format (for example: 20 kHz would be returned as 2.0 E 4 ).

## For Example:

If in AC Voltage or AC Current Function, a sinewave frequency is returned by the query: FREQ?
If in 'Hz' (Frequency) Function, the squarewave frequency is returned by the query: FREQ?

### 6.6.4.14

[SOUR](FUNC%5B:SHAP%5D(?)):PHAS [:ADJust] (?) <DNPD>

## Purpose

This command is used to set the phase angle of the 9100 output, with respect to 'Phase Lock In', when operating in either 'AC Voltage' or 'AC Current' function.

## <DNPD>

The 'decimal numeric program data' is a number which sets the required phase angle of the selected operation, expressed in units of Degrees. The Phase angle is resolved in increments of $0.01^{\circ}$, over a range of acceptable values from $-180^{\circ}$ to $+180^{\circ}$.
Example:
An 'AC Voltage' function output phase angle could be programmed by:

$$
\text { FUNC:\{SIN|IMP|TRI|TRAP|SYMS\};:VOLT <DNPD>;:FREQ <DNPD>;:PHAS <DNPD>;:PHAS:INP ON; }
$$

## Function Change, *RST Common Command and Power-up

The 9100 phase angle is set to zero degrees (equivalent to PHAS : ADJ 0). For details of operation and parameter limitations, refer to Volume 1, Section 4, Sub-Sections 4.4 and 4.6 (AC Voltage and AC Current).

## Response to Query Version

The instrument will return the present phase angle value for the selected operation, dependent upon the most-recent VOLT or CURR command. The returned number will be in standard scientific format (for example: $90^{\circ}$ would be returned as 9.0 E 1 ).

### 6.6.4.15 [SOUR](FUNC%5B:SHAP%5D(?)): PHAS:INP[:STATE](?) <CPD> $\{O F F|O N| 0 \mid 1\}$

## Purpose

The 9100 AC Voltage or AC Current output can be phase-shifted from a reference-phase input via the 'PHASE LOCK IN' plug on the rear panel (by a phase angle set by the PHASe : ADJust command - see 6.6.4.14 earlier).
This command switches the 9100: either to free run; or to be locked to the reference phase.

## <CPD>

The 'character program data' switches the 9100: either to free run (OFF or 0 ); or to be locked to the reference phase, after setting the phase angle ( ON or 1).
Example:
An 'AC Voltage' function output phase angle could be programmed by:

$$
\text { FUNC:\{SIN|IMP|TRI|TRAP|SYMS\};:VOLT <DNPD>;:FREQ <DNPD>;:PHAS <DNPD>;:PHAS:INP ON; }
$$

## Function Change, *RST Common Command and Power-up

The 9100 state changes to free run (equivalent to PHAS: INP $\{O F F \mid 0\}$ ). For details of operation and parameter limitations, refer to Volume 1, Section 4, Sub-Sections 4.4 and 4.6 (AC Voltage and AC Current).

## Response to Query Version

The instrument will return the present 'phase input state' setting: $\{\mathrm{OFF} \mid \mathrm{ON}\}$.

### 6.6.4.16 [SOUR](FUNC%5B:SHAP%5D(?)): PHAS: OUTP[:STATE] (?) <CPD>\{OFF|ON|0|1\}

Purpose
The 9100 AC Voltage or AC Current output phase can be used as a reference-phase output via the 'PHASE LOCK OUT' plug on the rear panel. This command switches the reference phase on or off.

## <CPD>

The 'character program data' switches the 9100: either to output the reference phase (ON or 1); or not (OFF or 0 ).
Example:
An 'AC Voltage' function output phase angle could be programmed by:

$$
\text { FUNC:\{SIN|IMP|TRI|TRAP|SYMS\};:VOLT <DNPD>;:FREQ <DNPD>;:PHAS:OUTP ON }
$$

## Function Change, *RST Common Command and Power-up

The 9100 switches reference phase off (equivalent to PHAS: OUTP \{OFF|0 \}). For details of operation and parameter limitations, refer to Volume 1, Section 4, Sub-Sections 4.4 and 4.6 (AC Voltage and AC Current).

## Response to Query Version

The instrument will return the present 'phase output state' setting: $\{O F F \mid O N\}$.

### 6.6.4.17 [SOUR](FUNC%5B:SHAP%5D(?)) : PULS : \{PER|WID|DCYC \} (?) <DNPD>

## Purpose

This command is used to set one of three parameters, each associated with Pulsed Voltage operation.
For definition of Period:
FUNC PULS; :PULS:PER <DNPD> selects the period of the pulsed voltage.
For definition of Pulsewidth (in conjunction with Period, implicitly defining Mark/Period Ratio):
FUNC PULS;:PULS:WID <DNPD> selects the pulsewidth. Alternatively:
For definition of Mark/Period Ratio regardless of Period:
FUNC PULS; :PULS:DCYC <DNPD> selects the percentage duty cycle of the pulsed voltage.
Voltage levels are programmed by VOLT:HIGH <DNPD> and VOLT:LOW <DNPD> commands.

## <DNPD>

The 'decimal numeric program data' is a number which sets the required period time interval or pulse-width time interval of the selected operation, expressed in units of Seconds. For duty cycle, this will be in units of Percentage. The <DNPD>s will, together, automatically choose the 'best' hardware configuration for the defined time intervals of output.
For Example:
A Pulsed Voltage (equivalent to the local selection of 'Mark/Period' or 'Logic Pulses' Function) is programmed by: FUNC PULS;:PULS:PER <DNPD>;:PULS:WID <DNPD>;:VOLT:HIGH <DNPD>;:VOLT:LOW <DNPD>

A Pulsed Voltage (equivalent to the local selection of '\% Duty Cycle' Function) is programmed by:
FUNC PULS;:PULS:PER <DNPD>;:PULS:DCYC <DNPD>;:VOLT:HIGH <DNPD>;:VOLT:LOW <DNPD>
For details of local operation and parameter limitations, refer to Volume 1, Section 4,Sub-Sections 4.10 (Mark/Period), 4.11 (\% Duty Cycle) or 4.16 (Logic Pulses).

## Responses to Query Versions

The instrument will return the present period, pulsewidth or percentage duty cycle for the selected operation. The returned number will be in standard scientific format (for example: 50 ms would be returned as $5.0 \mathrm{E}-2$, and $30 \%$ would be returned as 3.0 E 1 ). For Example:
If in 'Mark/Period', 'Logic Pulses' or '\% Duty Cycle' Function, the squarewave period is returned by the query: PULS:PER?
If in 'Mark/Period' or 'Logic Pulses' Function, the squarewave pulsewidth is returned by the query: PULS :WID?
If in '\% Duty Cycle' Function, the squarewave duty cycle percentage is returned by the query: PULS:DCYC?

### 6.6.4.18 [SOUR](FUNC%5B:SHAP%5D(?)):TEMP:UNIT(?) <CPD>\{C|CEL|F|FAH|K\}

## Purpose

This command affects the values of subsequently programmed temperature. This is clearly demonstrated by the following examples:

1. A 9100 unit is already programmed to simulate a thermocouple at $200^{\circ} \mathrm{C}$ (Celsius). To simulate $300^{\circ} \mathrm{C}$, it is necessary only to send the value command: TEMP:THER 300.
2. If now the same unit is required to respond to Fahrenheit values, the command: TEMP : UNIT F can be sent. The voltage output resulting from the previous $300^{\circ} \mathrm{C}$ programming will not change, but now the unit recognizes that voltage as having the equivalent Fahrenheit value (572). For instance; if the TEMP : THER? query is sent, then the unit will respond with the number 572 only. The other change is that subsequent value-programming commands must be sent with the required temperatures expressed in Fahrenheit.
3. Reprogramming must now follow in Fahrenheit values, so the command: TEMP : THER 482 can be sent, resulting in an output voltage representing a simulated temperature of $482^{\circ} \mathrm{F}\left(250^{\circ} \mathrm{C}\right.$ or 523 K$)$.

## <CPD>

The 'character program data' selects the factor which will govern the conversion from temperature value to simulated thermocouple voltage output (selected thermocouple type) or resistance output (selected RTD type). Where users wish to enter temperature values in units of Celsius, Fahrenheit or Kelvin, this command permits the required entry unit to be selected.
C|CEL For subsequent commands TEMP:THER <DNPD> or TEMP:PRT <DNPD>, the 9100 will recognize the units of the <DNPD> value as 'degrees Celsius'.
$\boldsymbol{F} \mid \boldsymbol{F A H}$ For subsequent commands TEMP:THER <DNPD> or TEMP:PRT <DNPD>, the 9100 will recognize the units of the <DNPD> value as 'degrees Fahrenheit'.
K For subsequent commands TEMP:THER <DNPD> or TEMP:PRT <DNPD>, the 9100 will recognize the units of the <DNPD> value as 'Kelvins'.

## Function Change, *RST Common Command and Power-up

The most-recently programmed 'units' setting is remembered regardless of [SOUR](FUNC%5B:SHAP%5D(?)) keyword changes until either the setting is changed by another TEMP : UNIT command, a $*$ RST command is sent, or the next power down. Power-up and $*$ RST default units are 'Celsius'.

## Response to Query Version

The instrument will return the present 'units' setting $\{C|F| K\}$.

### 6.6.4.19 [SOUR](FUNC%5B:SHAP%5D(?)):TEMP:SCAL(?) <CPD>\{TS68|TS90\}

## Purpose

The 9100 supports two types of temperature scale: IPTS-68 (default) and ITS-90. This command determines which of the two temperature scales will be used for subsequently programmed temperature.

## <CPD>

The 'character program data' selects the type of scale:
TS68 For subsequent commands TEMP:THER <DNPD> or TEMP:PRT <DNPD>, the 9100 will use the IPTS-68 temperature scale.
TS90 For subsequent commands TEMP:THER <DNPD> or TEMP:PRT <DNPD>, the 9100 will use the ITS-90 temperature scale.

## Function Change, *RST Common Command and Power-up

The most-recently programmed 'scale' setting is remembered regardless of [SOUR](FUNC%5B:SHAP%5D(?)) keyword changes until either the setting is changed by another TEMP : SCAL command, a $*$ RST command is sent, or the next power down. Power-up and $*$ RST default units are 'TS68'.

## Response to Query Version

The instrument will return the present 'scale' setting \{TS68|TS90\}.

### 6.6.4.2 [SOUR](FUNC%5B:SHAP%5D(?)) : TEMP : THER[:LEVE][:TMM] [:AMPL] (?)

## <DNPD>

Purpose
This command will select Thermocouple function with a default of Type K , setting the required temperature value, which will determine the output voltage (refer to the Programming Example after paras 6.6.4.21).

## <DNPD>

The 'decimal numeric program data' is a number which sets the required temperature value. It must be expressed as a value relating to the units (degrees Celsius, Degrees Fahrenheit, or Kelvin), already set into the 9100 by the most-recent TEMP : UNIT <CPD> command (see paras 6.6.4.18). Power-up and $*$ RST default units are Celsius.
The value of <DNPD>, in conjunction with the 'UNIT', 'SCAL' and 'TYPE' commands, will automatically choose the 'best' hardware range for the defined thermocouple voltage output.

For details of local operation and parameter limitations, refer to Volume 1, Section 4, Sub-Section 4.14 (Thermocouple Temperature).

## Software Compensation

Software compensation takes account of the temperature of the isothermal block on which the Reference Junction is mounted, behind the D-type socket on the 9100 front panel (refer to Volume 1, Section 4, Sub-section 4.14.4).

The block temperature is sensed at OUTPut ON, and regularly at 5 -second intervals until OUTPut OFF.

## Response to Query Version

The instrument will return a number which is the value of the present output temperature in currently-programmed units. The returned number will be in standard scientific format (for example: $200^{\circ} \mathrm{C}$ would be returned as 2.0 E 2 ).

### 6.6.4.21 [SOUR](FUNC%5B:SHAP%5D(?)):TEMP:THER:TYPE (?) <CPD> $\{B|C| E|J| K|L| N|R| S \mid T\}$

## Purpose

This command will select the Thermocouple function with the type selected and a default of $25^{\circ} \mathrm{C}$. (refer to the Programming Example below).

## <CPD>

The 'character program data' automatically selects the required simulation software. The <CPD> 'type' character is the same as the internationally-recognized thermocouple type. Power-up and *RST default is 'K-type'.

## Response to Query Version

The instrument will return the character which represents the presently-programmed thermocouple 'type' simulation: $\{B|C| E|J| K|L| N|R| S \mid T\}$.

Programming Example: To ensure the setup of a required thermocouple type and temperature, use:
:TEMP:THER 200; :TEMP:THER:TYPE B<nl>
or :TEMP:THER 353;:TYPE S<nl>

### 6.6.4.22

[SOUR](FUNC%5B:SHAP%5D(?)) : TEMP : PRT [: LEVE] [: IMM] [: AMPL] (?) <DNPD>

## Purpose

This command selects PRT simulation hardware, and sets the required temperature value, which determines the output resistance, once the type of PRT has been selected (refer to paras 6.6.4.23 and to the Programming Example after paras 6.6.4.25).

## <DNPD>

The 'decimal numeric program data' is a number which sets the required temperature value. It must be expressed as a value relating to the units (degrees Celsius, Degrees Fahrenheit, or Kelvin), already set into the 9100 by the most-recent TEMP : UNIT <CPD> command (see paras 6.6.4.18). Power-up and $*$ RST default units are Celsius. For this command sent on its own; other defaults are: NRES $=100 \Omega$, TYPE $=$ PT385 and UUT_I $=$ HIGH.

The value of <DNPD>, in conjunction with the 'UNIT', 'SCAL' and 'TYPE' commands, will automatically choose the 'best' hardware range for the defined PRT resistance output.
For details of local operation and parameter limitations, refer to Volume 1, Section 4, Sub-Section 4.15 (RTD Temperature).

## Response to Query Version

The instrument will return a number which is the value of the present output temperature in currently-programmed units. The returned number will be in standard scientific format (for example: $200^{\circ} \mathrm{C}$ would be returned as 2.0 E 2 ).

### 6.6.4.23 [SOUR](FUNC%5B:SHAP%5D(?)):TEMP:PRT:TYPE(?) <CPD>\{PT385|PT392\}

## Purpose

This command selects the appropriate conversion software to simulate the selected RTD type (refer to the Programming Example after paras 6.6.4.25).

## <CPD>

The 'character program data' selects the required simulation software for the required type of RTD:
PT385 For subsequent commands TEMP : PRT <DNPD>, the 9100 will use the PT385 (European) conformance curve.
PT392 For subsequent commands TEMP : PRT <DNPD>, the 9100 will use the PT392 (USA) conformance curve.
Power-up and $* \operatorname{RST}$ default is 'PT385'. For this command sent on its own; other defaults are: $\mathrm{LEVE}=25^{\circ} \mathrm{C}, \mathrm{NRES}=100 \Omega$ and UUT_I = HIGH.

## Response to Query Version

The instrument will return the characters which represent the presently-programmed RTD 'type' simulation: \{PT385|PT390\}.

### 6.6.4.24 [SOUR](FUNC%5B:SHAP%5D(?)):TEMP:PRT:NRESistance(?) <DNPD>

Purpose
The system defaults to provide parameters which simulate a platinum-resistance thermometer whose $0^{\circ} \mathrm{C}$ nominal value is $100 \Omega$. The nominal value can be adjusted between $10 \Omega$ and $2 \mathrm{k} \Omega$ to match the nominal $0^{\circ} \mathrm{C}$ value of the simulated thermometer. This command is invalid unless PRT function is programmed.

The TEMP:PRT:NRES command is used to adjust the $0^{\circ} \mathrm{C}$ nominal resistance parameter in the 9100 system (refer to the Programming Example after paras 6.6.4.25).

## <DNPD>

The 'decimal numeric program data' is a number which sets the required $0^{\circ} \mathrm{C}$ nominal value. It must be expressed as a decimal value in Ohms which is the same as that of the $0^{\circ} \mathrm{C}$ nominal value for the simulated thermometer

The value of <DNPD>, in conjunction with the 'UNIT', 'SCAL' and 'TYPE' commands, will automatically adjust the software parameters for the PRT resistance output defined by the PRT [:LEVE] [:IMM] [:AMPL] <DNPD> command.

For details of local operation and parameter limitations, refer to Volume 1, Section 4, Sub-Section 4.15 (RTD Temperature).

## Response to Query Version

The instrument will return a number which is the value of the presently-programmed $0^{\circ} \mathrm{C}$ nominal value. The returned number will be in standard scientific format (for example: $200 \Omega$ would be returned as 2.0 E 2 ).

### 6.6.4.25 [SOUR](FUNC%5B:SHAP%5D(?)):TEMP:PRT:UUT_I(?) <CPD>\{LOW|HIGH|SUPer\}

## Purpose

In the synthesized resistance technology used for RTD simulation in the 9100, the current sourced from the UUT must fall within certain spans of values for each commanded temperature value. For UUTs producing source currents which are larger than the values in the 'Low' (default) span, the greater current can be accommodated by selecting 'HIGH' or 'SUPER'.

The TEMP:PRT:UUT_I \{LOW|HIGH|SUPer\} command is used to switch between the three current configurations (refer to the Programming Example below). There is no default setting.

## <CPD>

The 'character program data' performs the required action. Refer to Volume 1, Section 4, paras 4.15.4.7, for a description of the current limits and output voltage limitation.

- LOW will select the UUT source current 'Low' limits.
- HIGH will select the UUT source current 'High' limits
- SUPer will select the UUT source current 'Super' limits.


## Response to Query Version

The 9100 will return either LOW, HIGH or SUP, dependent on the active limits selection
Programming Example: To ensure the setup of a required Type, Temperature, Nominal Resistance and Source Current use: :TEMP:PRT 270;:TYPE PT392;:NRES 1E3;:UUT_I HIGH<nl>

### 6.6.4.26 [SOUR](FUNC%5B:SHAP%5D(?)) : CONT [:LEVE][:IMM][:AMPL] (?) <DNPD>

## Purpose

This command activates the Continuity function. The value <DNPD> is the desired resistance value in ohms demanded by the user.

### 6.6.4.27 [SOUR](FUNC%5B:SHAP%5D(?)) : CONT : TCUR?

## Purpose

This query only command requests the test current provided by the UUT for confirmation that the UUT is providing sufficient test current to comply with its calibration specification (also see Note 1 below).

### 6.6.4.28 [SOUR](FUNC%5B:SHAP%5D(?)) : INS [:LEVE] [: IMM] [:AMPL] (?) <br> <DNPD>

## Purpose

This command activates the Insulation Resistance function. The value <DNPD> is the resistance value in ohms demanded by the user.
6.6.4.29 [SOUR](FUNC%5B:SHAP%5D(?)):INS:UUT_I(?) <CPD>

## Purpose

This command operates in the same manner as that for Active Resistance, with the exception that the only two permissible values of current setting <CPD> are HIGH and SUPer.

### 6.6.4.30 [SOUR](FUNC%5B:SHAP%5D(?)) : INS : TVOL?

## Purpose

This query only command returns the value of UUT test voltage (also see Note 1 below)

### 6.6.4.31 [SOUR](FUNC%5B:SHAP%5D(?)) : INS:TCUR?

## Purpose

This query only command returns the value of UUT test current (also see Note 1 below).

Note $1:$ If the commands :CONT:TCUR?, :INS:TVOL? or :INS: TCUR? are executed when the output is OFF, or the Model 9100 is not in the relevant function, the value returned will be $2.0 E+35$.

### 6.6.5

STATus Subsystem
This subsystem is used to enable bits in the Operation and Questionable Event registers. The Operation and Questionable: Event, Enable and Condition registers can be interrogated to determine their state. For further information regarding the Status structure, refer to Sub-Section 6.5.4.

### 6.6.5.1 STATus Subsystem Table

## Keyword <br> Parameter Form

: OPERation
[:EVENt]?
:ENABle (?)
: CONDition
: QUEStionable
[:EVENt]?
: ENABle(?)
:CONDition?
:PRESet

### 6.6.5.2 STAT : OPER[: EVEN] ?

## Purpose

OPER? returns the contents of the Operation Event register, clearing the register.

## Response

A <DNPD> in the form of an Nr1 number is returned. The value of the number, when converted to base 2 (binary), identifies the Operation Event register bits to determine their current status.

For example (refer to Fig. 6.2):
If the 9100 had just performed a selftest, the 'TESTING' bit 8 of the register would be set, and if no other Operation Event bits were enabled, the number 256 would be returned. Bit 8 (indeed, all bits in the register) would be reset by this query.

### 6.6.5.3

STAT : OPER:ENAB (?) <DNPD>

## Purpose

OPER: ENAB <DNPD> sets the mask which enables those Operation Event register bits which are required to be summarized at bit 7 of the IEEE 488.2 Status Byte register.

## <DNPD>

This is a decimal integer whose binary equivalent represents the bits required to be enabled.
For example (refer to Fig. 6.2):
The command: OPER: ENAB 768 would be required to enable only the 'TESTING' and 'PRETESTING' bits 8 and 9 of the
Operation Event register.

## Response to the Query Version

A <DNPD> in the form of an Nr1 number is returned. The value of the number, when converted to base 2 (binary), identifies the bits set in the Operation Enable mask.
For example (refer to Fig. 6.2):
If the 'CALIBRATING' and 'PRETESTING' bits 0 and 9 of the register are enabled, the number 513 would be returned.

### 6.6.5.4 STAT : OPER : COND?

## Purpose

OPER: COND? returns the contents of the Operation Condition register, which is not cleared by the command.
N.B. This register contains transient states, in that its bits are not 'sticky', but are set and reset by the referred operations. The response to the query therefore represents an instantaneous 'Snapshot' of the register state, at the time that the query was accepted.

## Response

A <DNPD> in the form of an Nr1 number is returned. The value of the number, when converted to base 2 (binary), identifies the Operation Condition register bits to determine their current status.
For example (refer to Fig. 6.2):
If the 9100 was in the process of performing a selftest, only the 'TESTING' bit 8 of the register would be temporarily set, and the number 256 would be returned.

### 6.6.5.5 STAT:QUES[:EVEN] ?

## Purpose

QUES? returns the contents of the Questionable Event register, clearing the register.

## Response

A <DNPD> in the form of an Nr1 number is returned. The value of the number, when converted to base 2 (binary), identifies the Questionable Event register bits to determine their current status
For example (refer to Fig. 6.2):
If an error had been initiated by an incorrect constant current during Resistance operations, the 'sticky' 'INV OHM CURR1 ' bit
9 of the register would be set, and if no other Questionable Event bits were enabled, the number 512 would be returned. Bit
9 (indeed, all bits in the register) would be reset by this query.

### 6.6.5.6 STAT:QUES:ENAB (?) <DNPD>

## Purpose

QUES : ENAB <DNPD> sets the mask which enables those Questionable Event register bits which are required to be summarized at bit 3 of the IEEE 488.2 Status Byte register.

## <DNPD>

This is a decimal integer whose binary equivalent represents the bits required to be enabled.
For example (refer to Fig. 6.2):
The command: QUES: ENAB 1536 would be required to enable only the 'INV OHM CURR1' and 'INV OHM CURR2' bits 9 and 10 of the Questionable Event register.

## Response to the Query Version

A <DNPD> in the form of an Nr1 number is returned. The value of the number, when converted to base 2 (binary), identifies the bits set in the Questionable Enable mask.

## For example (refer to Fig. 6.2):

If the 'INV OHM CURR1' bit 9 of the register is the only enabled bit, the number 512 would be returned.

## Purpose

QUES : COND? returns the contents of the Questionable Condition register, which is not cleared by the command.
N.B. This register contains transient states, in that its bits are not 'sticky', but are set and reset by the referred conditions. The response to the query therefore represents an instantaneous 'Snapshot' of the register state, at the time that the query was accepted.

## Response

A <DNPD> in the form of an Nr1 number is returned. The value of the number, when converted to base 2 (binary), identifies the Questionable Condition register bits to determine their current status.
For example (refer to Fig. 6.2):
If an incorrect UUT source current was generating an error during Resistance operations, and the temporary 'INV OHM CURR1'
bit 9 of the Condition register was set; and if no other Questionable Condition bits were set, the number 512 would be returned.

### 6.6.5.8 STAT: PRES

## SCPI-Mandated Command

The intention behind mandating the PRES command is to enable all bits in the SCPI-defined 'Device-dependent' and 'Transition registers in order to provide a "device-independent structure for determining the gross status of a device".

## Purpose in the 9100

In the 9100, the functions of the 'Transition' registers are not required, so no access is given. The PRES command therefore affects only the two device-dependent enabling registers:

The Operation Event Enable register
The Questionable Event Enable register.
Refer to Fig. 6.2 and Sub-Section 6.5.4. Sending PRES will set true all bits in both Enable registers. This will enable all bits in the two Event registers, so that all reportable device-dependent events, reported in the two registers, will be capable of generating an SRQ; providing only that bits 3 and 7 in the IEEE-488.2 Status Byte Register are also enabled.
The use of PRES in the 9100 allows the status-reporting structure to be set to a known state, not only for the intention of the SCPI mandate, but also to provide a known starting point for application programmers.

### 6.6.6

 SYSTem SubsystemThis subsystem collects the functions that are not related to 9100 performance.
6.6.6.1 SYSTem Subsystem Table
$\left.\begin{array}{llr}\text { Keyword } & \text { Parameter Form } & \text { Notes } \\ \text { SYSTem } & & \\ & \text { : ERRor? } & \\ & \text { :DATE (?) } & \text { <SPD> }\end{array}\right]$

### 6.6.6.2 SYST:ERR?

## The Error Queue

As errors in the 9100 are detected, they are placed in a 'first in, first out' queue, called the 'Error Queue'. This queue conforms to the format described in the SCPI Command Reference (Volume 2), although errors only are detected. Three kinds of errors are reported in the Error Queue, in the sequence that they are detected:

Command Errors, Execution Errors and Device-Dependent errors

## Queue Overflow

Any time the Error Queue overflows, the earliest errors remain in the queue, and the most-recent error is discarded. the latest error in the queue is replaced by the error: -350, "Queue overflow".

## Purpose of SYSt : ERR? - Reading the Error Queue

This query is used to return any error which has reached the head of the Error Queue, and delete the error from the queue. The Error Queue is first in / first out, so the returned string will represent the earliest error in the queue.

The queue is read destructively as described in the SCPI Command Reference to obtain a code number and error message. The query can be used successively to read errors in the queue until it is empty, when the message 0, "No error" will be returned.

## Response

The response is in the form of 'String Program Data', and consists of two elements: a code number and error message.
The list of possible responses is given in Appendix 'A' to Section 8.

The date format can only be changed locally; using the Date Format menu, which is accessed via the Configuration menus.
N.B. A password is required for access to change the date format. Refer to Volume 1 of this User's Handbook; Section 3, Subsection 3.3.2, paras 3.3.2.2 and 3.3.2.10.

## Purpose

This command is not used to change the date format. It only changes the present date, as recognized by the 9100 , within the current date format, as defined locally.

## <SPD>

This string defines the present date, and consists of the three two-digit numbers, separated by forward slashes. The numbers represent day, month and year, but not necessarily in that order. The locally-defined date format governs the sequence in which these three numbers are recognized, and their order within the string must reflect the locally-defined sequence.

## Possible Formats

The three possible formats are shown on the Configuration screen given in Volume 1 of this User's Handbook; Section 3, Subsection 3.3.2, paras 3.3.2.10.

The string must conform to the scheme: $\mathrm{X} / \mathrm{Y} / \mathrm{Z}$, where $\mathrm{X}, \mathrm{Y}$ and Z are two-digit numbers.
The combination of the two-digit numbers must have one of the following meanings:

## Day/Month/Year, Month/Day/Year or Year/Month/Day;

where the chosen sequence also agrees with that set locally in paras 3.3.2.10.

## Response to Query Version SYST : DATE?

The Query will return the presently-programmed date, as three slash-separated two-digit numbers, in the date format that they are currently set.

### 6.6.6.4 SYST:TIME (?) <SPD>

## Purpose

This command changes the present time as recorded by the 9100 software. Any new time will be updated from a non-volatile realtime internal 24-hour clock.

## <SPD>

This string defines the present time, consisting of two 2-digit numbers, separated by a hyphen. The numbers represent hour and minute, in that order. Their order within the string must reflect the fixed sequence.

The string must conform to the scheme: $X-Y$, where $X$ and $Y$ are 2-digit numbers
The combination of the 2-digit numbers must have the following meaning, within the context of a 24 -hour clock:

## Hour-Minute

## Response to Query Version SYST : TIME?

The Query will return the updated time at the moment the query was accepted, as two hyphen-separated 2-digit numbers, in the fixed time format.

### 6.6.6.5 SYST:SVOL (?) <DNPD>

## Purpose

This command sets the voltage value of the threshold of operation for the High Voltage Warning as employed in DC Voltage and AC Voltage functions. The 9100 need not be currently set in either of these functions to program the voltage.

## <DNPD>

The 'decimal numeric program data' is a number which sets the required voltage safety warning threshold, expressed in units of DC or RMS AC Volts. It should be unsigned. The parameter <DNPD> must have a value in the range 10.000 V to 110.000 V inclusive.

## Response to Query Version: SYST : SVOL?

The instrument will return the present DC or AC voltage safety warning threshold value. The returned number will be in standard scientific unsigned format (for example: 90 V would be returned as 9.0 E 1 ).
6.6.6.6 SYST : VERS?

## Purpose

This query returns a numeric value corresponding to the SCPI version number for which the 9100 complies.

## Response

At the time of writing, this will be 1994.0

### 6.6.6.7 SYST : FOR?

## Purpose

This query returns the present date format, as programmed locally.

## Response

SYST : FOR? returns one of three sets of three characters: DMY, MDY or YMD (Day/Month/Year, Month/Day/Year or Year/Month/
Day). Formatting is carried out from a screen in 'Configuration' mode (Refer to Volume 1 of this User's Handbook; Section 3, Subsection 3.3.2, paras 3.3.2.10).

### 6.7 The IEEE Bus Interface for the Power Option

This section explains the IEEE command set specifcally added for the power option. It makes the assumption that existing 9100 commands will behave, where possible, in the same manner as described in the preceding section.

Key to the following:
<spd> String program data type (e.g. "abc123")
<cpd> Character program data type consisting of one of the following
\{... $|..| \ldots\}$
<dnpd> Decimal numeric program data type (i.e. a number, 5, 5.1, 1.0E3)
<abpd> Arbitrary block program data type (i.e. all ASCII character values 0~255)
<nr3> Numeric response data
<hnrd> Hexadecimal numeric response data

### 6.7.1 General Comments

- If the 9100 does not have the option fitted, then a settings conflict error will be generated.
- Queries of <dnpd> values will return the invalid number value (2.0E35) if the function is not active/selected.
- The query of <cpd> commands shall return the short-form version of the setting. If function/setting is not selected then the word 'NONE' will be returned.


### 6.7.2 Output Selection

This sub-system is used to configure the output connections of the 9100 .

### 6.7.2.1 OUTPut [:STATE] (?) <CPd> \{OFF|ON|O|1\}

This command will connect the output signal to the Main (hi/lo) and Auxiliary (I+/I-) channels.

- This command behaves in the same manner as described in the 9100 manual. It is included in this document for completeness only.


### 6.7.2.2 OUTPut:ISELection(?) <cpd>\{HIGHi|HI50turn|HI10turn|LOWi\}

This command is used to select the high current coils and which output terminals source the signal.

- This command behaves in the same manner as described in the 9100 manual. It is included in this document for completeness only


### 6.7.3 Power Selection

This sub-section defines the major hardware configuration of the power option.

### 6.7.3.1 [SOURce]: POWer[:LEVel] [: IMMediate] [:AMPLitude] (?) <dnpd>

This command is used to select and query the value of the power to be output.

- If the instrument is not already in a power function (DC or AC ) then DC power will be selected as default.
- The units of power amplitude will be determined by the : POWer: UNITs command.
- The Voltage will be adjusted to generate this power.


### 6.7.3.2 [SOURce] : POWerUNITs (?) <cpd> \{WATTs|VA|VAR\}

This command selects the units that power is displayed in. For the case of AC, the WATTs and VAR mode will take into account the Phase Angle. In the case of VA, then power is simply RMS Volts times RMS Amps.

- If DC power is selected, then a settings conflict error will be generated.


### 6.7.3.3 [SOURCe]:POWer:PANGle(?) <dnpd>

This command sets the angular difference between the main and auxiliary waveforms. It is set as a phase angle in degrees.

- If the instrument is not in AC power, then a settings conflict error will be generated.
- The range of the PANGle <dnpd> is +180.0 to -180.0 . Values outside this will generate Data out of range error.


### 6.7.3.4 [SOURCe]: POWer:MAIN: SHAPe (?)

<cpd>\{DC|SINusoid|IMPulse|TRIangle|TRAPezoid|SYMSquare\}

### 6.7.3.5 [SOURce]: POWer:AUXiliary:SHAPe (?)

<cPd> \{DC|SINusoid|IMPulse|TRIangle|TRAPezoid|SYMSquare\}
These two commands select the waveshape of the main and auxiliary signals.

- Selection of 'DC' in either the main or auxiliary will change function to DC Power.

Selecting any of the other waveshapes will select AC power and default the other channel waveshape to SIN.

- If a waveform is selected for whom the present amplitude is to large, then a settings conflict will be reported.


### 6.7.3.6 <br> [SOURce]:POWer:POLarity: (?) <br> <cpd> \{DC|SIGNed|ABSolute \}

This command sets the polarity mode of the DC or AC power functions. If the ABSolute parameter is received, then power will not have a sign attached. The SIGNed parameter will allow positive and negative powers. (Note this may result in a change of phase angle in AC).

- If the instrument is not in DC nor AC power then a settings conflict error will be generated.
6.7.3.7 [SOURCe]: POWer:MAIN : VOLTage [ : LEVel] [: IMMediate] [:AMPLitude] (?) <dnpd>

This sets the voltage amplitude of the selected channel.

- All waveshapes are specified in RMS.
- Only DC may have a negative <dnpd> .
6.7.3.8 [SOURCe]:POWerAUXiliary:CURRent [:LEVel][:IMMediate][:AMPLitude](?) <dnpd>

This sets the current amplitude of the auxiliary channel (Note the main channel is voltage only).

- All waveshapes are specified in RMS.
- Only DC may have a negative <dnpd> .
- This command is still used for the auxiliary amplitude even when POWer:AUXiliary:MODE VOLTage is selected.


### 6.7.3.9 [SOURCe]: POWer:AUXiliary:MODE (?) <cpd> \{VOLTage|CURRent \}

This command determines the type of signal output on the auxiliary channel.
When in the VOLTage mode, the display continues to show current $(\mathrm{I}=\mathrm{xxx} . \mathrm{xx})$ but the output on the auxiliary channel is calculated using the factor supplied by POWer: SCALe:

$$
\text { Vout }_{\text {aux }}=I_{\text {aux }} * \text { Scale }
$$

- The default mode on entry to DC or AC will be CURRent.


### 6.7.3.10 [SOURCe]: POWer:AUXiliary:SCALe (?) <dnpd>

This command determines the scale factor applied to the auxiliary channel, when in 'auxiliary voltage' mode, to calculate the effective voltage on the auxiliary channel:

$$
\operatorname{VOUT}_{\text {aux }}=I_{\text {aux }} * \text { Scale }
$$

- This is equivalent to the scale value set in the manual configuration screen.


### 6.7.4 Harmonic Selection

This sub-system defines the major hardware configuration of the power option harmonic feature.
6.7.4.1 [SOURCe] : HARMonic (?) <dnpd>

This command selects the harmonic frequency on the auxiliary channel.

- The range of the $<\operatorname{dnpd}>$ is 1.0 to 40.0. Values outside this will generate a Data out of range error.
6.7.4.2 [SOURce]:HARMonic:MAIN:VOLTage[:LEVel][:IMMediate][:AMPLitude](?) <dnpd>

This sets the voltage amplitude, in RMS of the main channel
6.7.4.3 [SOURCe]: HARMOnic:AUXiliary:CURRent [:LEVel][:IMMediate][:AMPLitude] (?) <dnpd>
This sets the current amplitude, in RMS, of the auxiliary channel (Note the main channel is voltage only).

### 6.7.4.4 [SOURce]: HARMOnic:AUXiliary:VOLTage [:LEVel] [:IMMediate] [:AMPLitude] (?) <dnpd>

This sets the voltage amplitude, in RMS of the auxiliary channel.
6.7.4.5 [SOURce] : HARMonic:PANGle (?) <dnpd>

This command sets the angular difference between the main and auxiliary waveforms. It is set as a phase angle in degrees.

- If the instrument is not in harmonics, then a settings conflict error will be generated.
- The range of the PANGle<dnpd> is +180.0 to -180.0 . Values outside this will generate a Data out of range error.


### 6.7.5 Other Commands

These are existing 9100 commands and are shown here as they are used to manipulate parameters associated with the power option.

### 6.7.5.1 [SOURce]:FREQuency[:CW|FIXed(?) <dnpd>

This command sets the frequency of the currently selected waveform. The units of this command are assumed to be Hertz. The CW and FIXed optional parameters are included to keep with the SCPI definition of the frequency command:
"The Continuous Wave or FIXed node is used to select a frequency of a non-swept signal".

- This command is valid in AC waveshapes only.
- In Harmonics, it sets the fundamental frequency.


### 6.7.5.2 [SOURce]: PHASe [:ADJust (?) <dnpd>

This command is used to set the phase angle of the 9100 output, with respect to 'Phase Lock In', when operation in either AC Voltage, Current or Power functions.

- The range of the $<d n p d>$ is +180.0 to -180.0 . Values outside this will generate a Data out of range error.


### 6.7.5.3 [SOURCe]:PHAse:INPut[:STATe](?) <CPd>\{ON|OFF|O|1\}

The 9100 AC Voltage or AC Current output can be phase-shifted from a reference-phase input via the 'PHASE LOCK IN' plug on the rear panel (by a phase angle set by the PHASe:ADJust command).

### 6.7.5.4 [SOURCe]: OUTPut:STATe] <CPd>\{ON|OFF|O|1\}

The 9100 AC Voltage or AC Current output phase used as a reference-phase output via the 'PHASE LOCK OUT' plug on the rear panel. This command switches the reference phase on or off.

### 6.7.6 Calibration

The calibration commands available to the user are the normal SCPI extensions:
For use on the factory calibration system only, three "hidden commands" are used.

### 6.7.6.1 A command to turn off one (either) channel.

This will be used in calibration and verification. The result will be to set the appropriate DAC to zero, while otherwise leaving the channel connected.

### 6.7.6.2 Current routing

A command to route the Auxiliary current o/p via the guarded (D-type) terminals, provided it is less than 2 Amps. This is primarily used in calibration and verification.

A user performing manual cal will not have the factory cal system and will be using standard 4 mm leads only. These IEEE commands are not duplicated on the front panel

### 6.7.6.3 Voltage Routing

A command to route the auxiliary voltage to the High and Low terminals. A user performing manual cal will not have the factory cal system and does not need this command.
6.7.7 IEEE488.2 COMMON COMMANDS

This section briefly outlines the mandatory IEEE 488.2 commands.

### 6.7.7.1 *OPT?

This command returns a string of comma separated characters. A ' 1 ' indicates an option is fitted, a ' 0 ', that the option is not fitted.

The meaning of the characters is position dependent:

$$
\mathrm{x} 6, \mathrm{x} 5, \mathrm{x} 4, \mathrm{x} 3, \mathrm{x} 2, \mathrm{x} 1
$$

where x 1 indicates option 250 ( 250 MHz scope option).
where x 2 indicates option 100 (High stability crystal reference).
where $x 3$ indicates option 600 ( 600 MHz scope option).
where x 4 indicates option 135 (High voltage resistance option).
where x5 indicates option PWR (Power option).
where x 6 is reserved for future use.

## IEEE 488.2 Device Documentation Requirements

IEEE 488.2 requires that certain information be supplied to the user about how the device has implemented the standard. The Device Documentation Requirements are detailed in Section 4.9 of the Standard document IEEE Std 488.2-1992, on page 22. In this handbook, the required information is already contained within the descriptions of the system, and this appendix provides cross-references to those descriptions in which it is presented. The following paragraphs have the same numbers as the paragraphs of Section 4.9 in the Standard document to which they refer.

1. The list of IEEE 488.1 Interface Functions subsets implemented is given as Table 6.1 (page 6-4). The list is also printed close to the IEEE 488 connector on the rear of the instrument
2. The instrument address is set manually, and the instrument firmware refuses to set any address outside the range 0-30. It responds instead with a Device Dependent Error, displayed on the front panel screen:
"Bus address must be within the range $\varnothing$ - $3 \varnothing$ ".
3. The (manual only) method of setting the address is described on pages 6-8/9, including the point in time when the 9100 recognizes a user-initiated address change.
4. Appendix E to Section 6 describes the active and nonactive settings at power-on.
5. Message Exchange Options:
a. The Input Buffer is a first in - first out queue, which has a maximum capacity of 128 bytes (characters). Each character generates an interrupt to the instrument processor which places it in the Input Buffer for examination by the Parser. The characters are removed from the buffer and translated with appropriate levels of syntax checking. If the rate of programming is too fast for the Parser or Execution Control, the buffer will progressively fill up When the buffer is full, the handshake is held.
b. No query returns more than one $<$ RESPONSE MESSAGE UNIT>
c. All queries generate a response when parsed.
d. No query generates a response when read.
e. The following commands are coupled:

VOLT and FREQ
CURR and FREQ and ISEL
WID and PER and VOLT:HIGH and VOLT:LOW
DCYC and PER and VOLT: HIGH and VOLT: LOW
THER and UNIT and TYPE
PRT and UNIT and TYPE
6. The following functional elements are used in constructing the device-specific commands:

- Command Program Header
- Query Program Header
- Character Program Data
- Decimal Numeric Program Data.
- String Program Data (PASS, DATE, TIME)
- Arbitrary Block Program Data (*PUD)

Compound Command Program Headers are used within the SCPI format.
7. $*$ PUD blocks are limited to 63 bytes.
8. Expression Program Data elements are not used.
9. The syntax for each command is described in the genera list of commands in Subsection 6.6 and Section 6, Appendix C. This list includes all queries, for which the response syntax is also described.
10. All device-to-device message transfer traffic follows the rules for <RESPONSE MESSAGE> elements.
11. The only command which elicits a Block Data response is the query $*$ PUD?
Its response consists of \#, 2, two digits and a data area of 63 bytes; 67 bytes in all.
12. A separate list of every implemented Common Command and Query is given in the alphabetical index at the start of Section 5.

They are also described in Section 6, Appendix C
13. *CAL? is not implemented.
14. $*$ DDT is not implemented.
15. Macro commands are not implemented
16. $*$ IDN? is described in Section 6 , Appendix C.
17. $*$ DDT is not implemented.
18. Neither $*$ RDT nor $*$ RDT? are implemented.
19. The states affected by $*$ RST are described for each command in the list of commands and queries in Section 6, Appendix C.
Query Command $*$ LRN? is not implemented; neither are Commands $*$ RCL and $* S A V$.
20. *TST? invokes the Operational Selftest. The response to *TST? is described in Section 6, Appendix C, with a list of possible errors detailed in Appendix A to Section 8 of this handbook.
21. The additional status data structures used in the instrument's status reporting are fully described in Section 6; Subsection 6.5.

Operating instructions for the status reporting facilities are given in Section 6, Appendix C.
22. All commands are sequential - overlapped commands are not used.
23. As all commands are sequential, there are no pending parallel operations. The functional criterion which is met, therefore, is merely that the associated operation has been completed.
24. No representations are used for 'Infinity' and 'Not-aNumber'.

## SCPI Command Set and Conformance Information

The SCPI Standard requires that certain information be supplied to the user about how the device has implemented the standard. The Documentation Requirements are detailed in Section 4.2.3 of the Standard document Standard Commands for Programmable Instruments SCPI 1994; Volume 1: Syntax and Style; on page 4-6. The following paragraphs comply with those requirements:

## 1. The SCPI Version to which the Instrument Complies:

The instrument complies with the version 1994. The Confirmed Query: SYSTem:VERSion? will return this version number.
2. Syntax of All SCPI Commands and Queries Implemented in the Model 9100

All the Commands and Queries are present, each annotated with the state of its SCPI approval.

| Keyword | Parameter Form | Notes | SCPI Approval |
| :---: | :---: | :---: | :---: |
| CALibration<n> |  |  | Confirmed |
| :SECure |  |  | Not SCPI Approved |
| :PASSword | <SPD> |  | Not SCPI Approved |
| :EXIT | [<SPD>,<CPD>\{PRD7\|PRD14|PRD30|PRD60\}] |  | Not SCPI Approved |
| :TARGet | <DNPD>,<DNPD>[,<DNPD>] |  | Not SCPI Approved |
| :TRIGger? |  | [query on | Not SCPI Approved |
| :SPECial? |  | [query on | Not SCPI Approved |
| :CJUNction? | <DNPD> |  | Not SCPI Approved |
| OUTPut<n> |  |  | Confirmed |
| [:STATe](?) | $\begin{aligned} & \text { <CPD> }\{\mathrm{ON}\|\mathrm{OFF}\| 0 \mid 1\} \\ & \text { <CPD>\{ON\|OFF\|0\|1\} } \\ & \text { <CPD>\{HIGHi\|HI50turn\|HI10turn\|LOWi }\} \end{aligned}$ |  | Confirmed |
| :COMPensation(?) |  | .... | Not SCPI Approved |
| :ISELection(?) |  | ......... | Not SCPI Approved |
| [SOURce<n>] |  | ......... | Confirmed |
| :FUNCtion |  |  | Confirmed |
| [:SHAPe](?) |  |  |  |
| :VOLTage |  | ... | Confirmed |
| [:LEVEI] |  |  | Confirmed |
| [:IMMediate] |  |  | Confirmed |
| [:AMPLitude](?) | <DNPD> |  | Confirmed |
| :HIGH(?) | <DNPD> |  | Confirmed |
| :LOW(?) | <DNPD> |  | Confirmed |
| :CURRent |  | $\ldots . . . . .$. | Confirmed |
| [:LEVEl] |  |  | Confirmed |
| [:IMMediate] |  |  | Confirmed |
| [:AMPLitude](?) | <DNPD> |  | Confirmed |


| Keyword | Parameter Form | Notes | SCPI Approval |
| :---: | :---: | :---: | :---: |
| [SOURce] (Contd.) |  |  |  |
| :RESistance |  |  | Confirmed |
| [:LEVEl] |  |  | Confirmed |
| [:IMMediate] |  |  | Confirmed |
| [:AMPLitude](?) | <DNPD> |  | Confirmed |
| :UUT_I(?) | <CPD> ${ }^{\text {LOW }}$ \|HIGH|SUPer\} |  | Not SCPI Approved |
| :CONDuctance |  |  | Not SCPI Approved |
| [:LEVEl] |  |  | Not SCPI Approved |
| [:IMMediate] |  |  | Not SCPI Approved |
| [:AMPLitude](?) | <DNPD> |  | Not SCPI Approved |
| :UUT_I(?) | <CPD>\{LOW\|HIGH|SUPer\} |  | Not SCPI Approved |
| :CAPacitance |  |  | Not SCPI Approved |
| [:LEVEl] |  |  | Not SCPI Approved |
| [:IMMediate] |  |  | Not SCPI Approved |
| [:AMPLitude](?) | <DNPD> |  | Not SCPI Approved |
| :UUT_I(?) | <CPD>\{LOW\|SUPer\} |  | Not SCPI Approved |
| :FREQuency |  |  | Confirmed |
| [:CW\|FIXed](?) | <DNPD> |  | Confirmed |
| :PHASe |  |  | Confirmed |
| [:ADJust](?) | <DNPD> |  | Confirmed |
| :INPut |  |  | Not SCPI Approved |
| [:STATe](?) | <CPD> ONN $\mid$ OFF $\|0\| 1\} ~_{\text {d }}$ |  | Not SCPI Approved |
| :OUTPut |  |  | Not SCPI Approved |
| [:STATe](?) | <CPD>\{ON\|OFF|0|1\} |  | Not SCPI Approved |
| :PULSe |  |  | Confirmed |
| :PERiod(?) | <DNPD> |  | Confirmed |
| :WIDth(?) | <DNPD> |  | Confirmed |
| : DCYCle (?) | <DNPD> |  | Confirmed |
| :TEMPerature |  |  | Confirmed |
| :UNITs(?) | <CPD> ${ }^{\text {C }}$ \|CEL $\mid$ F\|FAH|K $\}$ |  | Not SCPI Approved |
| :SCALe(?) | <CPD>\{TS68\|TS90\} |  | Not SCPI Approved |
| :THERmocouple |  |  | Not SCPI Approved |
| [:LEVEl] |  |  | Not SCPI Approved |
| [:IMMediate] |  |  | Not SCPI Approved |
| [:AMPLitude](?) | <DNPD> |  | Not SCPI Approved |
| :TYPE(?) | <CPD> $\mathrm{BB}\|\mathrm{C}\| \mathrm{E}\|\mathrm{J}\| \mathrm{K}\|\mathrm{L}\| \mathrm{N}\|\mathrm{R}\| \mathrm{S} \mid \mathrm{T}\}_{\text {, }}$ |  | Not SCPI Approved |
| :PRT |  |  | Not SCPI Approved |
| [:LEVEl] |  |  | Not SCPI Approved |
| [:IMMediate] |  |  | Not SCPI Approved |
| [:AMPLitude](?) | <DNPD> |  | Not SCPI Approved |
| :TYPE(?) | <CPD> \{PT385\|PT392\} |  | Not SCPI Approved |
| :NRESistance(?) | <DNPD> |  | Not SCPI Approved |
| :UUT_I(?) | <CPD>\{LOW\|HIGH|SUPer\} |  | Not SCPI Approved |


| Keyword | Parameter Form | Notes SCPI Approval |
| :---: | :---: | :---: |
| STATus <br> :OPERation [:EVENt]? ENABle(?) :CONDition? | <DNPD> |  |
| QUEStionable [:EVENt]? ENABle(?) CONDition? | <DNPD> |  |
| :PRESet |  | ...............................................................Confirmed |
| SYSTem :ERRor? |  |  |
| :DATE(?) <SPD> |  | .........................................................Not SCPI Approved |
| :TIME(?) <SPD> |  | Not SCPI Approved |
| :SVOLtage(?) | <DNPD> | Not SCPI Approved |
| :VERSSion? |  | [Query Only] ............................................. Confirmed |
| :FORmat? |  | [Query Only] ............................................ Not SCPI Approved |

## IEEE 488.2 Common Commands and Queries Implemented in the Model 9100

6.C. 1

Clear Status
This measurement event status data structure conforms to the IEEE 488.2 standard requirements for this structure.

*CLS
clears all the event registers and queues except the output queue.
The output queue and MAV bit will be cleared if *CLS immediately follows a 'Program Message Terminator'; refer to the IEEE 488.2 standard document.

Execution Errors:
None.

## Power On and Reset Conditions

Not applicable.

## 6.C. 2 Event Status Enable

This event status data structure conforms to the IEEE 488.2 standard requirements for this structure.

*ESE enables the standard defined event bits which will generate a summary message in the status byte. Refer to Section 6 ; Subsection 6.5.

Nrf is a Decimal Numeric Data Element representing an integer decimal value equivalent to the Hex value required to enable the appropriate bits in this 8 -bit register. The detailed definition is contained in the IEEE 488.2 standard document. Note that numbers will be rounded to an integer.

## 6.C. 3 Recall Event Status Enable

This event status data structure conforms to the IEEE 488.2 standard requirements for this structure.


## *ESE?

recalls the enable mask for the standard defined events. Refer
to Section 6; Subsection 6.5.

## Response Decode:

The value returned, when converted to base 2 (binary), identifies the enabled bits which will generate a summary message in the service request byte, for this data structure. The detailed definition is contained in the IEEE 488.2 document.

Execution Errors:
None.

## Power On and Reset Conditions

Not applicable.

## Execution Errors:

None

## Power On and Reset Conditions

The Power On condition depends on the condition stored by the common $*$ PSC command - if 0 then it is not cleared; if 1 then the register is cleared. Reset has no effect.

## 6.C. $4 \quad$ Read Event Status Register

This event status data structure conforms to the IEEE 488.2 standard requirements for this structure.


## *ESR?

recalls the standard defined events. Refer to Section 6; Subsection 6.5.

## Response Decode:

The value returned, when converted to base 2 (binary), identifies the bits as defined in the IEEE 488.2 standard.

## Execution Errors:

None

## 6.C.5 I/D (Instrument Identification)

This command conforms to the IEEE 488.2 standard requirements.


## *IDN?

will recall the instrument's manufacturer, model number, serial number and firmware level.

## Response Format:

Character position
$\begin{array}{llllllllllll}1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12\end{array}$
W a v e t e k L t d ,
$\begin{array}{lllll}13 & 14 & 15 & 16 & 17\end{array}$
$9 \quad 1 \quad 0 \quad 0 \quad$,
18192021222324252627282930

31323334
x . X X

## Where:

The data contained in the response consists of four commaseparated fields, the last two of which are instrument-dependent. The data element type is defined in the IEEE 488.2 standard specification.
A single query sent as a terminated program message will elicit a single response terminated by:

$$
\mathrm{nl}=\text { newline with EOI }
$$

If multiple queries are sent as a string of program message units (separated by semi-colons with the string followed by a permitted terminator), then the responses will be returned as a similar string whose sequence corresponds to the sequence of the program queries. The final response in the string will be followed by the terminator:
$\mathrm{nl}=$ newline with EOI

## Response Decode:

The data contained in the four fields is organized as follows:

- First field - manufacturer
- Second field - model
- Third field - serial number
- Fourth field - firmware level (will possibly vary from one instrument to another).


## Execution Errors:

## None.

Power On and Reset Conditions
Not applicable.

## 6.C. $6 \quad$ Operation Complete

This command conforms to the IEEE 488.2 standard requirements.

*OPC
is a synchronization command which will generate an operation complete message in the standard Event Status Register when all pending operations are complete.

## Execution Errors

## None.

## Power On and Reset Conditions

Not applicable.

## 6.C. $7 \quad$ Operation Complete?

This query conforms to the IEEE 488.2 standard requirements.


## Response Decode:

The value returned is always 1 , which is placed in the output
queue when all pending operations are complete.

## Recall the 9100 Instrument Hardware Fitment

This command conforms to the IEEE 488.2 standard requirements.


## *OPT?

will recall the instrument's hardware fitment

## Response Format:

Character position

$$
\begin{array}{cccccccccccc}
1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 \\
x 6 & , & x 5 & , & x 4 & , & x 3 & , & x 2 & , & x 1 & \mathrm{nl}
\end{array}
$$

## Where:

The data in the response consists of comma-separated characters, each being either 1 or 0 .

$$
\mathrm{nl}=\text { newline with EOI }
$$

The data element type is Nr 1 as defined in the IEEE 488.2 standard specification.

## Response Decode:

The character positions represent the following hardware fitment:
x1 - Option 250: 250 MHz Oscilloscope Option
x2 - Option 100: High Stability Crystal Reference
x3 - Option 600: 600 MHz Oscilloscope Option
x4 - Option 135: High Voltage Resistance Option
x5 - Option PWR: Power Option
x6-0 (Reserved for future use)
a response of 0 indicates option not fitted; a response of 1 indicates option fitted.

## Execution Errors:

None.
Power On and Reset Conditions
Not applicable.

## 6.C. $8 \quad$ Power On Status Clear

This common command conforms to the IEEE 488.2 standard requirements.


## *PSC

sets the flag controlling the clearing of defined registers at Power On.

Nrf is a decimal numeric value which, when rounded to an integer value of zero, sets the power on clear flag false. This allows the instrument to assert SRQ at power on, providing that the PON bit in the ESR is enabled at the time of power-down, by the corresponding bit in its Enable register (ESE).

When the value rounds to an integer value other than zero it sets the power on clear flag true, which clears the standard event status enable and service request enable registers so that the instrument will not assert an SRQ on power up.

Examples:
*PSC 0 or *PSC 0.173 sets the instrument to assert an SRQ at Power On.
*PSC 1 or *PSC 0.773 sets the instrument to not assert an SRQ on Power On.

## Execution Errors:

None.

## Power On and Reset Conditions

## 6.C. $9 \quad$ Recall Power On Status Clear Flag

This common query conforms to the IEEE 488.2 standard requirements. The existing flag condition will have been determined by the $*$ PSC command.

## *PSC?

will recall the Power On Status condition.

## Response Format

A single ASCII character is returned.
A single query sent as a terminated program message will elicit a single response terminated by:
$\mathrm{nl}=$ newline with EOI
If multiple queries are sent as a string of program message units (separated by semi-colons with the string followed by a permitted terminator), then the responses will be sent as a similar string whose sequence corresponds to the sequence of the program queries. The final response in the string will be followed by the terminator:
$\mathrm{nl}=$ newline with EOI

## Response Decode:

The value returned identifies the state of the saved flag:
Zero indicates false. The instrument is not programmed to clear the Standard Event Status Enable Register and Service Request Enable Register at Power On, so the instrument will generate a 'Power On' SRQ, providing that the PON bit in the ESR is enabled at the time of power-down, by the corresponding bit in its Enable register (ESE).

One indicates true. The instrument is programmed to clear the Standard Event Status Enable Register and Service Request Enable Register at Power On, so the instrument cannot generate any SRQ at Power On.

## Execution Errors:

None

## Power On and Reset Conditions

No Change. This data is saved in non-volatile memory at Power Off, for use at Power On.

## 6.C. 10

## Protected User Data - Entry of User Data

This command conforms to the IEEE 488.2 standard requirements.

where:
phs = Program Header Separator,
digit $=$ one of the ASCII-coded numerals,
user message $=$ any message up to 63 bytes maximum.

## Note

The slash-delimited /^END/ box is not outlined. This is to draw attention to the fact that it is not a data element, but represents the EOI line being set true with the last byte 'NL' to terminate the program message.
Refer to the Standard document IEEE Std 488.2-1992, Sub-section 7.7.6, page 78.

## *PUD

allows a user to enter up to 63 bytes of data into a protected area to identify or characterize the instrument. The two representations above are allowed depending on the message length and the number of 'digits' required to identify this. The instrument must be in calibration mode for this command to execute.

The data can be recalled using the $*$ PUD? query.

## Execution Errors

*PUD is executable only when the rear panel calibration switch is in the enabled position and calibration has been enabled. Otherwise an Execution Error is returned.

## Command Errors

A Command Error is returned if the user message exceeds 63 bytes, or if the data does not conform to the standard format.

## Power On and Reset Conditions

Data area remains unchanged.

## 6.C. 11 Protected User Data - Recall of User Data



This common command conforms to the IEEE 488.2 standard requirements. $*$ PUD? recalls previously entered user data. Refer to program command $*$ PUD.

## Response Syntax:



## where:

digit $=$ one of the ASCII-coded numerals previously determined from the length of the user message string, user message $=$ the saved user message.

## Response Decode:

The previously-saved message is recalled.
If no message is available, the value of the two digits is 00 . The data area contains up to 63 bytes of data.

A single query sent as a terminated program message will elicit a single response terminated by:
$\mathrm{nl}=$ newline with EOI
If multiple queries are sent as a string of program message units (separated by semi-colons with the string followed by a permitted terminator), then the responses will be sent as a similar string whose sequence corresponds to the sequence of the program queries. The final response in the string will be followed by the terminator:
$\mathrm{nl}=$ newline with EOI

## Execution Errors:

None.

## Power On and Reset Conditions

Data area remains unchanged.


## *RST

will reset the instrument to a defined condition, stated for each applicable command with the command's description, and listed in Appendix D to Section 6.
The reset condition is not dependent on past-use history of the instrument except as noted below:
*RST does not affect the following:

- the selected address of the instrument
- calibration data that affect specifications;
- SRQ mask conditions;
- the state of the IEEE 488.1 interface.


## 6.C. 13 Service Request Enable

This Status Byte data structure conforms to the IEEE 488.2 standard requirements for this structure.

$*$ SRE enables the standard and user-defined summary bits in the service request byte, which will generate a service request. Refer to Section 6, Subsection 6.5.
Nrf is a Decimal Numeric Data Element representing an integer decimal value equivalent to the Hex value required to enable the appropriate bits in this 8 -bit register. The detail definition is contained in the IEEE 488.2 document. Note that numbers will be rounded to an integer.

## Execution Errors:

None.

## Power On and Reset Conditions

Not applicable

## 6.C. $14 \quad$ Recall Service Request Enable

This Status Byte data structure conforms to the IEEE 488.2 standard requirements for this structure.


## *SRE?

recalls the enable mask for the standard defined events. Refer to Section 6, Subsection 6.5.

## Response Decode:

The value returned, when converted to base 2 (binary), identifies
the enabled bits which will generate a service request. The detail
is contained in the IEEE 488.2 standard document.

## Execution Errors:

None.
Power On and Reset Conditions
The Power On condition depends on the condition stored by the common $* \mathrm{PSC}$ command - if 0 then it is not cleared; if 1 then the register is cleared. Reset has no effect.

## 6.C. 15 Read Service Request Register

This Status Byte data structure conforms to the IEEE 488.2 standard requirements for this structure.


## *STB?

recalls the service request register for summary bits. Refer to Section 6, Subsection 6.5.

## Response Decode:

The value returned, when converted to base 2 (binary), identifies the summary bits for the current status of the data structures involved. For the detail definition see the IEEE 488.2 standard document. There is no method of clearing this byte directly. Its condition relies on the clearing of the overlying status data structure.

## Execution Errors:

None.

## Power On and Reset Conditions

Not applicable.

## 6.C. 16 Test Operations - Full Selftest

This query conforms to the IEEE 488.2 standard requirements.

*TST?
executes a Full selftest. A response is generated after the test is completed.
N.B. Operational selftest is valid only at temperatures: $23^{\circ} \mathrm{C} \pm 10^{\circ} \mathrm{C}$.

## Response Decode:

The value returned identifies pass or failure of the operational selftest:

ZERO indicates operational selftest complete with no errors detected.

ONE indicates operational selftest has failed.
The errors can be found only by re-running the self test manually. Refer to Section 8 .

## Execution Errors:

Operational selftest is not permitted when calibration is successfully enabled.

## Power On and Reset Conditions

Not applicable.

## 6.C. $17 \quad$ Wait

This command conforms to the IEEE 488.2 standard requirements.

*WAI
prevents the instrument from executing any further commands or queries until the No Pending Operations Flag is set true. This is a mandatory command for IEEE-488.2 but has little relevance to this instrument as there are no parallel processes requiring Pending Operation Flags.

## Execution Errors:

## None.

## Power On and Reset Conditions

Not applicable.

## Model 9100 - Device Settings after *RST

## 6.D. 1 Introduction

## *RST

will reset the instrument to a defined condition, stated for each applicable command
The reset condition is not dependent on past-use history of the instrument except as noted below:
*RST does not affect the following:

- the selected address of the instrument;
- calibration data that affect specifications;
- SRQ mask conditions;
- the contents of:
the Status Byte Register;
the Status Byte Enable Register;
the Standard Event Status Register;
the Standard Event Status Enable Register;
the SCPI Operation Status Register;
the SCPI Operation Status Enable Register;
the SCPI Questionable Status Register;
the SCPI Questionable Status Enable Register;
- the state of the IEEE 488.1 interface;
- the Error Queue;
- the Power-on Status Clear flag setting;
- the Protected User Data Query response.

The 'Enable Macro Command' (*EMC) is not used in the 9100
The 'Define Device Trigger Command' ( $*$ DDT) is not used in the 9100 .
Parallel Poll is not implemented in the 9100 .
*RST enforces the following states:

- The 9100 reverts to Manual mode;
- the 9100 is returned to 'Operation Complete Command Idle State' (OCIS)
- the 9100 is returned to 'Operation Complete Query Idle State' (OQIS);
- Settings Related to Common IEEE 488.2 Commands are as detailed in paras 6.D.2, overleaf;
- Settings related to SCPI Commands are as detailed in paras 6.D.3, overleaf;


## 6.D. $2 \quad *$ RST Settings Related to Common IEEE 488.2 Commands

| Program Coding | Condition |
| :--- | :--- |
| *CLS | Not applicable |
| *ESE Nrf | Not applicable |
| *ESE? | Previous state preserved |
| *ESR? | Previous state preserved |
| *IDN? | No Change |
| *OPC | OPIC state forced |
| *OPC? | OPIQ state forced |
| *OPT? | Not applicable |
| *PSC 0/1 | Not applicable |
| *PSC? | No change. |
| *PUD | Data area remains unchanged |
| *PUD? | Data area remains unchanged |
| *SRE Nrf | Not applicable |
| *SRE? | Previous state preserved |
| *STB? | Previous state preserved |
| *TST? | Not applicable |
| *WAI | Not applicable |

## 6.D. $3 \quad *$ RST Settings Related to SCPI Commands

## Keyword

CALibration
Disabled
:PASSword required to enter Calibration mode output
[:STATe] .............................. OFF
:COMPensation(?) ................... . OFF
:ISELection(?) ....................... HIGHi
[SOURCe]
: FUNCtion
[:SHAPe] (?) $\qquad$
: VOLTage
[:LEVE1]
...................... . Active
[:AMPLitude] (?) ........ 1V
:HIGH(?) ................ Not applicable
:LOW(?) ........................ Not applicable
: CURRent $\qquad$
:CURRent ................................ Inactive
:RESistance ....................... Inactive :UUT_I (?) Low
:CONDuctance .......................... Inactive :UUT_I(?) . . . ..................... . LOW
:CAPacitance ....................... Inactive :UUT_I (?) LOW
:FREQuency .......................... Inactive
: PHASe Inactive
[:ADJust] (?) ..................
INPut
: OUTPut
:TEMPerature ........................ Inactive
:UNITs (?) ......................... C

:THERmocouple ....................... Inactive
:TYPE (?)
Inactive
…… . . . . . . . . . . . . . . Inac
TYPE (?) . . . . . . . . . . . . . . . . . PT38
NRESistance(2) .................... $100 \Omega$
UUT_I (?)

## Keyword

STATus
:OPERation
[:EVENt]? .... No change
[:EVENT]? .... No change
:CONDition? .. Not applicable
: QUEStionable
[:EVENt]? .... No change
:ENABle(?) ... No change
:CONDition? .. Not applicable
PRESet ......... Not applicable
SYSTem
:ERRor? .......... Not applicable
DATE(?) ........As previously set, updated
:TIME (?) ........ As previously set, updated
SVOLtage(?) ....As previously set
:VERSion? ........ 1993

## Model 9100 - Device Settings at Power On

## 6.E. 1 General

## Active Mode:

The 9100 can power-up in either 'Manual or 'Procedure' mode, but Manual Mode or Calibration mode must be selected for Remote Operation.
The required mode is selected by pressing Mode key on front panel and choosing from the Mode Menu (Calibration mode requires a password).

Device I/D (Serial Number) Factory serial number preserved Protected User Data Previous entry preserved

## Status Reporting Conditions:

Status Byte Register
Status Byte Enable Register
Event Status Register
Event Status Enable Register
Operation Status Event Register
Operation Status Enable Register
Questionable Status Event Register
Questionable Status Enable Register
Error Queue
Depends on state of $* \mathrm{PSC}$ Depends on state of $* P S C$ Depends on state of $*$ PSC Depends on state of *PSC Depends on state of *PSC Depends on state of *PSC Depends on state of *PSC Error Queue Empty until first error is detected
6.E. 2 Power-On Settings Related to Common IEEE 488.2 Commands
Program Coding
*CLS
*ESE Nrf
*ESE?
*ESR?
*IDN?
*OPC
*OPC?
*OPT?
*PSC 0/1
*PSC?

*PUD
*PUD?
*RST
*SRE Nrf
*SRE?
*STB?
*TST?
*WAI

Condition
Not applicable
Not applicable
Response depends on state of *PSC Response depends on state of *PSC
Not applicable
Not applicable
Not applicable
Not applicable
Not applicable
No change. This data is saved at power off
or use at power on
Data area remains unchanged
Data area remains unchanged
Not applicable
Not applicable
Response depends on state of *PSC
Response depends on state of *PSC
Not applicable
Not applicable

## 6.E. 3 Settings related to SCPI Commands



## SECTION 79100 SPECIFICATIONS

### 7.1 General

### 7.1.1 Line Power Supply

| Voltage (single $\phi$ ):$100 \mathrm{~V} / 120 \mathrm{~V} / 220 \mathrm{~V} / 240 \mathrm{~V}$ <br> selectable from rear panel <br> Variation: $\leq \pm 10 \%$ Nominal Voltage |  |
| :--- | :--- |
| Line Frequency: | 48 Hz to 63 Hz |
| Consumption: | 450 VA max |
| Power Fuses: | $220 / 240 \mathrm{~V}:$ T3.15A HBC, 250 V , IEC127 <br>  <br>  $100 / 120 \mathrm{~V}:$ T5.0A HBC, 250 V, IEC127 |

### 7.1.2 Mechanical

| Dimensions: | Height: | 3 U |
| :---: | :---: | :---: |
|  | Width: | 427 mm (16.8 inches) |
|  | Depth: | 460 mm (18.1 inches) |
| Weight: | 18.5 kg (41 lbs) |  |

### 7.1.3 SAFETY:

Designed to UL1244, IEC348, IEC1010-1: Pollution degree 2; installation category II; Protection class I.
7.1.4 Peak Terminal Voltages and Currents

|  | Peak Volts <br> to Ground | Peak <br> Current |
| :--- | :---: | :---: |
| SHi | 1500 V | - |
| Hi | 1500 V | 90 mA |
| SLo | 15 V | - |
| Lo | 15 V | 90 mA |
| $\mathrm{I}+$ | 10 V | 30 A |
| $\mathrm{I}-$ | -15 V | 30 A |
| Aux Analog Output | 1.5 A |  |

### 7.1.5 Environmental Conditions

| Temperature: | Operating: | $5^{\circ} \mathrm{C}$ to $40^{\circ} \mathrm{C}$ |
| :--- | :--- | :--- |
|  | Transit: | $-20^{\circ} \mathrm{C}$ to $60^{\circ} \mathrm{C}<100 \mathrm{hrs}$ |
|  | Storage: | $0^{\circ} \mathrm{C}$ to $50^{\circ} \mathrm{C}$ |
| Warm-up Time: | 20 minutes |  |

Max. Relative Humidity (non-condensing):

| Operating: | $+5^{\circ} \mathrm{C}$ to $+30^{\circ} \mathrm{C}:$ | $<90 \%$, |
| :--- | :--- | :--- |
|  | $+30^{\circ} \mathrm{C}$ to $+40^{\circ} \mathrm{C}:$ | $<75 \%$, |
| Storage: | $0^{\circ} \mathrm{C}$ to $+50^{\circ} \mathrm{C}:$ | $<95 \%$, |


| Altitude |  |  |
| :--- | :--- | :--- |
|  | Operating: | 0 to $2000 \mathrm{~m}(6,562 \mathrm{ft})$ |
|  | Non-operating: | 0 to $12,000 \mathrm{~m}(40,000 \mathrm{ft})$ |

Shock: MIL-T-28800, type III, class 5, style E.

Vibration: MIL-T-28800, type III, class 5, style E.
Enclosure: MIL-T-28800, type III, class 5, style E.
EMC:
Designed to:

| Generic Emissions: | EN50081. |
| :--- | :--- |
| Generic Immunity: | EN50082. |

FCC Rules part 15 sub-part J class B

### 7.1.6 The Meaning of 'Accuracy' when used in the

 Function Accuracy TablesAccuracy includes long-term stability, temperature coefficient, linearity, load and line regulation and the traceability of factory and National calibration standards. Nothing further needs to be added to determine the Test Uncertainty Ratio over the instrument under test.
N.B. These specifications apply to both the Model 9100 output terminals and at the remote end of the Model 9105 lead kit unless otherwise stated.
7.2 Options and Associated Products

### 7.2.1 Model 9100 Option Summary

Option $10 \quad$ Blank 256kByte, Flash memory.

Option 30 Blank 256kByte, Static RAM (SRAM), battery backed.
Option 60 Soft Carry Case.
Option $70 \quad$ NAMAS Calibration Certificate traceable to National Standards.
Option $90 \quad$ Rack Mounting Kit.
Option 100 High Stability Crystal Reference.
Option $200 \quad 10$ - and 50-Turn Current Coils.
Option $250 \quad 250 \mathrm{MHz}$ Oscilloscope Calibrator Module
or
Option $600 \quad 600 \mathrm{MHz}$ Oscilloscope Calibrator Module.
Line Voltage: The 9100 is configured for use at the correct voltage at the shipment point.

### 7.2.2 Products Associated with the Model 9100

PLC-XXX Procedure Library Cards (User's Handbook Section 1, Sub-section 1.4).
Model $9105 \quad$ Comprehensive Lead Set (one unit supplied with each Model 9100 unit).
Model 9010 Memory Card Procedure Generator, inventory management software and memory card drive, supplied in 3.5 " integral PC mount format, with accessories for external mounting.
(Minimum hardware requirements: $100 \%$ IBM compatible, 8048625 MHz DX $^{\mathrm{TM}}$ or better, with MS-DOS $5.0^{\text {TM }}$ or later plus Windows ${ }^{\text {TM }}$ Version 3.1 or later. 4MBytes of memory, 30MBytes of hard disk space is required for installation; further hard disk space will be required for generation of procedures, etc. One full-size expansion slot will be required.)

### 7.3 DC Voltage Specifications

### 7.3.1 DC Voltage Accuracy and Resolution

| Voltage Output <br> +ve \& -ve Polarities | Accuracy ${ }^{*}$ <br> $\pm(\%$ of Output + Floor $)$ <br> 1Year - Tcal $\pm 5^{\circ} \mathrm{C}[1]$ | Compliance <br> Current | Absolute <br> Resolution |
| :---: | :---: | :---: | :---: |
| 000.000 mV to 320.000 mV | $0.006 \%+4.16 \mu \mathrm{~V}$ | $<20 \mathrm{~mA}$ | $1 \mu \mathrm{~V}$ |
| 0.32001 V to 3.20000 V | $0.006 \%+41.6 \mu \mathrm{~V}$ | $<20 \mathrm{~mA}$ | $10 \mu \mathrm{~V}$ |
| 03.2001 V to 32.0000 V | $0.0065 \%+416 \mu \mathrm{~V}$ | $<20 \mathrm{~mA}$ | $100 \mu \mathrm{~V}$ |
| 032.001 V to 320.000 V | $0.0065 \%+4.48 \mathrm{mV}$ | $<6 \mathrm{~mA}$ | 1 mV |
| 0320.01 V to 1050.00 V | $0.006 \%+19.95 \mathrm{mV}$ | $<6 \mathrm{~mA}$ | 10 mV |

* = For loads $<1 \mathrm{M} \Omega$ : add load regulation error.
7.3.2 Other DCV Specifications

| Settling Time: | to within $10 \%$ of accuracy: 0.08 s |
| :--- | :--- |
| Load Regulation: | For loads $<1 \mathrm{M} \Omega:$ add $\left(200 / \mathrm{R}_{\text {LOAD }}\right) \%$ of output |
| Maximum Capacitance: | 1000 pF. |

7.4 AC Voltage Specifications
7.4.1 AC Voltage Accuracy (Sinusoidal Waveshape) and Resolution

| Voltage Output | Frequency Band ${ }^{[2]}$ (Hz) | Accuracy * $\begin{aligned} & \pm(\% \text { Output + Floor }) \\ & \mathbf{1} \text { Year - Tcal }[1] \pm 5^{\circ} \mathrm{C} \end{aligned}$ | Current Compliance | Total Harmonic Distortion (\% of Output) | Absolute Resolution |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 000.000 mV to 010.000 mV | $\begin{array}{r} 10-3 \mathrm{k} \\ 3 \mathrm{k}-10 \mathrm{k} \\ 10 \mathrm{k}-30 \mathrm{k} \\ 30 \mathrm{k}-50 \mathrm{k} \\ 50 \mathrm{k}-100 \mathrm{k} \end{array}$ | $\begin{aligned} & 0.04+384 \mu \mathrm{~V} \\ & 0.04+512 \mu \mathrm{~V} \\ & 0.06+960 \mu \mathrm{~V} \\ & 0.09+1.92 \mathrm{mV} \\ & 0.20+5.12 \mathrm{mV} \end{aligned}$ | $\begin{aligned} & 20 \mathrm{~mA} \\ & 20 \mathrm{~mA} \\ & 20 \mathrm{~mA} \\ & 10 \mathrm{~mA} \\ & 10 \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & 0.06 \\ & 0.10 \\ & 0.13 \\ & 0.20 \\ & 0.32 \end{aligned}$ | $\begin{aligned} & 1 \mu \mathrm{~V} \\ & 1 \mu \mathrm{~V} \\ & 1 \mu \mathrm{~V} \\ & 1 \mu \mathrm{~V} \\ & 1 \mu \mathrm{~V} \end{aligned}$ |
| 010.001 mV to 032.000 mV | $\begin{array}{r} 10-3 \mathrm{k} \\ 3 \mathrm{k}-10 \mathrm{k} \\ 10 \mathrm{k}-30 \mathrm{k} \\ 30 \mathrm{k}-50 \mathrm{k} \\ 50 \mathrm{k}-100 \mathrm{k} \end{array}$ | $\begin{aligned} & 0.04+96.0 \mu \mathrm{~V} \\ & 0.04+128 \mu \mathrm{~V} \\ & 0.06+240 \mu \mathrm{~V} \\ & 0.09+480 \mu \mathrm{~V} \\ & 0.20+1.28 \mathrm{mV} \end{aligned}$ | $\begin{aligned} & 20 \mathrm{~mA} \\ & 20 \mathrm{~mA} \\ & 20 \mathrm{~mA} \\ & 10 \mathrm{~mA} \\ & 10 \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & 0.06 \\ & 0.10 \\ & 0.13 \\ & 0.20 \\ & 0.32 \end{aligned}$ | $\begin{aligned} & 1 \mu \mathrm{~V} \\ & 1 \mu \mathrm{~V} \\ & 1 \mu \mathrm{~V} \\ & 1 \mu \mathrm{~V} \\ & 1 \mu \mathrm{~V} \end{aligned}$ |
| 032.001 mV to 320.000 mV | $\begin{array}{r} 10-3 \mathrm{k} \\ 3 \mathrm{k}-10 \mathrm{k} \\ 10 \mathrm{k}-30 \mathrm{k} \\ 30 \mathrm{k}-50 \mathrm{k} \\ 50 \mathrm{k}-100 \mathrm{k} \end{array}$ | $\begin{aligned} & 0.04+19.2 \mu \mathrm{~V} \\ & 0.04+25.6 \mu \mathrm{~V} \\ & 0.06+48.0 \mu \mathrm{~V} \\ & 0.09+96.0 \mu \mathrm{~V} \\ & 0.20+256 \mu \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 20 \mathrm{~mA} \\ & 20 \mathrm{~mA} \\ & 20 \mathrm{~mA} \\ & 10 \mathrm{~mA} \\ & 10 \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & 0.06 \\ & 0.10 \\ & 0.13 \\ & 0.20 \\ & 0.32 \end{aligned}$ | $\begin{aligned} & 1 \mu \mathrm{~V} \\ & 1 \mu \mathrm{~V} \\ & 1 \mu \mathrm{~V} \\ & 1 \mu \mathrm{~V} \\ & 1 \mu \mathrm{~V} \end{aligned}$ |
| 0.32001 V to 3.20000 V | $\begin{array}{r} 10-3 \mathrm{k} \\ 3 \mathrm{k}-10 \mathrm{k} \\ 10 \mathrm{k}-30 \mathrm{k} \\ 30 \mathrm{k}-50 \mathrm{k} \\ 50 \mathrm{k}-100 \mathrm{k} \end{array}$ | $\begin{aligned} & 0.04+192 \mu \mathrm{~V} \\ & 0.04+256 \mu \mathrm{~V} \\ & 0.06+480 \mu \mathrm{~V} \\ & 0.09+960 \mu \mathrm{~V} \\ & 0.20+2.56 \mathrm{mV} \end{aligned}$ | $\begin{aligned} & 20 \mathrm{~mA} \\ & 20 \mathrm{~mA} \\ & 20 \mathrm{~mA} \\ & 10 \mathrm{~mA} \\ & 10 \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & 0.06 \\ & 0.10 \\ & 0.13 \\ & 0.20 \\ & 0.32 \end{aligned}$ | $\begin{aligned} & 10 \mu \mathrm{~V} \\ & 10 \mu \mathrm{~V} \\ & 10 \mu \mathrm{~V} \\ & 10 \mu \mathrm{~V} \\ & 10 \mu \mathrm{~V} \end{aligned}$ |
| 03.2001 V to 32.0000 V | $\begin{array}{r} 10-3 \mathrm{k} \\ 3 \mathrm{k}-10 \mathrm{k} \\ 10 \mathrm{k}-30 \mathrm{k} \\ 30 \mathrm{k}-50 \mathrm{k} \\ 5 \mathrm{k}-100 \mathrm{k} \end{array}$ | $\begin{aligned} & 0.04+1.92 \mathrm{mV} \\ & 0.06+2.56 \mathrm{mV} \\ & 0.08+4.80 \mathrm{mV} \\ & 0.15+9.60 \mathrm{mV} \\ & 0.35+32.0 \mathrm{mV} \end{aligned}$ | $\begin{aligned} & 20 \mathrm{~mA} \\ & 20 \mathrm{~mA} \\ & 20 \mathrm{~mA} \\ & 20 \mathrm{~mA} \\ & 20 \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & 0.10 \\ & 0.10 \\ & 0.16 \\ & 0.20 \\ & 0.32 \end{aligned}$ | $\begin{aligned} & 100 \mu \mathrm{~V} \\ & 100 \mu \mathrm{~V} \\ & 100 \mu \mathrm{~V} \\ & 100 \mu \mathrm{~V} \\ & 100 \mu \mathrm{~V} \end{aligned}$ |
| 032.001 V to 105.000 V | $\begin{array}{r} 10-3 \mathrm{k} \\ 3 \mathrm{k}-10 \mathrm{k} \\ 10 \mathrm{k}-30 \mathrm{k} \\ 30 \mathrm{k}-50 \mathrm{k} \\ 50 \mathrm{k}-100 \mathrm{l} \end{array}$ | $\begin{aligned} & 0.04+6.30 \mathrm{mV} \\ & 0.06+8.40 \mathrm{mV} \\ & 0.08+15.8 \mathrm{mV} \\ & 0.15+31.5 \mathrm{mV} \\ & 0.35+105 \mathrm{mV} \end{aligned}$ | $\begin{aligned} & 20 \mathrm{~mA} \\ & 20 \mathrm{~mA} \\ & 20 \mathrm{~mA} \\ & 20 \mathrm{~mA} \\ & 20 \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & 0.10 \\ & 0.10 \\ & 0.16 \\ & 0.20 \\ & 0.32 \end{aligned}$ | $\begin{aligned} & 1 \mathrm{mV} \\ & 1 \mathrm{mV} \\ & 1 \mathrm{mV} \\ & 1 \mathrm{mV} \\ & 1 \mathrm{mV} \end{aligned}$ |
| 105.001 V to 320.000 V | $\begin{array}{r} 40-100 \\ 100-1 \mathrm{k} \\ 1 \mathrm{k}-3 \mathrm{k} \\ 3 \mathrm{k}-10 \mathrm{k} \\ 10 \mathrm{k}-20 \mathrm{k} \\ 20 \mathrm{k}-30 \mathrm{k} \end{array}$ | $\begin{aligned} & 0.05+19.2 \mathrm{mV} \\ & 0.05+19.2 \mathrm{mV} \\ & 0.08+1.2 \mathrm{mV} \\ & 0.08+32.0 \mathrm{mV} \\ & 0.12+48.0 \mathrm{mV} \\ & 0.15+64.0 \mathrm{mV} \end{aligned}$ | $6 \mathrm{~mA}^{\text {\# }}$ <br> $6 \mathrm{~mA}^{\#}$ <br> $6 \mathrm{~mA}^{\#}$ <br> 20mA <br> 20 mA <br> 20 mA | $\begin{aligned} & 0.50 \\ & 0.32 \\ & 0.32 \\ & 0.32 \\ & 0.32 \\ & 0.32 \end{aligned}$ | $\begin{aligned} & 1 \mathrm{mV} \\ & 1 \mathrm{mV} \\ & 1 \mathrm{mV} \\ & 1 \mathrm{mV} \\ & 1 \mathrm{mV} \\ & 1 \mathrm{mV} \end{aligned}$ |
| 0320.01 V to 0800.00 V | $\begin{gathered} 40-100 \\ 100-1 \mathrm{k} \\ 1 \mathrm{k}-3 \mathrm{k} \\ 3 \mathrm{k}-10 \mathrm{k} \\ 10 \mathrm{k}-20 \mathrm{k} \dagger \\ 20 \mathrm{k}-30 \mathrm{k} \dagger \end{gathered}$ | $\begin{aligned} & 0.05+63.0 \mathrm{mV} \\ & 0.05+63.0 \mathrm{mV} \\ & 0.08+63.0 \mathrm{mV} \\ & 0.08+105 \mathrm{mV} \\ & 0.12+158 \mathrm{mV} \\ & 0.15+210 \mathrm{mV} \end{aligned}$ | 6 mA 6 mA 6 mA 20 mA 20mA 20 mA | $\begin{aligned} & 0.50 \\ & 0.32 \\ & 0.32 \\ & 0.32 \\ & 0.32 \\ & 0.32 \end{aligned}$ | 10 mV <br> 10 mV <br> 10 mV <br> 10 mV <br> 10 mV <br> 10 mV |
| 0800.01 V to 1050.00 V | $\begin{array}{r} 40-100 \\ 100-1 \mathrm{k} \\ 1 \mathrm{k}-3 \mathrm{k} \\ 3 \mathrm{k}-10 \mathrm{k} \\ 10 \mathrm{k}-20 \mathrm{k} \dagger \end{array}$ | $\begin{aligned} & 0.05+126 \mathrm{mV} \\ & 0.05+126 \mathrm{mV} \\ & 0.08+126 \mathrm{mV} \\ & 0.08+210 \mathrm{mV} \\ & 0.12+315 \mathrm{mV} \end{aligned}$ | 6 mA 6 mA 6 mA 20 mA 20 mA | $\begin{aligned} & 0.50 \\ & 0.32 \\ & 0.32 \\ & 0.32 \\ & 0.32 \end{aligned}$ | 10 mV <br> 10 mV <br> 10 mV <br> 10 mV <br> 10 mV |

$=$ For loads $<|1 \mathrm{M} \Omega|$ : add load regulation error.
$=$ Availability of voltage and frequency combinations is subject to the Volt-Hertz limit (see V-Hz profile).

### 7.4.2 Volt-Hertz Profile (Sinusoidal Waveshape)


7.4.3 Frequency Spans vs Frequency Resolution

| Absolute <br> Resolution | Span of Frequencies |
| :--- | :---: |
| 1 mHz | 010.000 Hz to 320.000 Hz |
| 10 mHz | 0.01000 kHz to 3.20000 kHz |
| 100 mHz | 00.0100 kHz to 32.0000 kHz |
| 1 Hz | 000.010 kHz to 100.000 kHz |

7.4.4 AC Voltage Phase (Sinusoidal Waveshape) *

Output Voltage Phase Span with respect to Phase Lock In $= \pm 180^{\circ}$
Resolution of output voltage phase increments $=0.01^{\circ}$

| Voltage <br> Output | Selected <br> Frequency <br> $\mathbf{f ( H z )}$ | Output Phase Error <br> with respect to <br> 'Phase Lock In' | Output Phase Error <br> with respect to <br> 'Phase Lock Out' | 1V to 3V RMS Sine Input $\dagger$ <br> Output Phase Error <br> with respect to <br> 'Phase Lock In' |
| :---: | :---: | :---: | :---: | :---: |
| 0.30000 V to 105.000 V | $10-40$ | $\pm 0.07^{\circ}$ | $\pm 0.07^{\circ}$ | $\pm 0.0^{\circ}$ |
|  | $40-65$ | $\pm 0.07^{\circ}$ | $\pm 0.07^{\circ}$ | $\pm 0.14^{\circ}$ |
|  | $65-1 \mathrm{k}$ | $\pm(0.07+0.001 \mathrm{xf})^{\circ}$ | $\pm(0.07+0.001 \mathrm{xf})^{\circ}$ | $\pm(0.14+0.001 \mathrm{xf})^{\circ}$ |
| 105.001 V to 0750.00 V | $45-65$ | $\pm 0.16^{\circ}$ | $\pm 0.16^{\circ}$ | $\pm 0.23^{\circ}$ |
|  | $65-1 \mathrm{k}$ | $\pm(0.16+0.0037 \mathrm{xf})^{\circ}$ | $\pm(0.16+0.0037 \mathrm{xf})^{\circ}$ | $\pm(0.23+0.0037 \mathrm{xf})^{\circ}$ |

Note: An application can be employed in which the 'Slave' frequency is set to a harmonic (multiple) of the 'Master' frequency. In this case the slave frequency must not exceed 1 kHz .

* = If two or more 9100 units are being used in a 'Master and Slave' configuration, this specification applies only when both Master and Slave are set to the same frequency. Mark/Space ratio of the input must not be less than 1:4
$\dagger=$ DC-coupled input. Do not AC-couple. Up to 10 mV p-p noise is rejected
- = Maximum load current: 2 mA ; maximum load capacitance: 200 pF .

NOTES: [1] Tcal = temperature at calibration. Factory calibration temperature $=23^{\circ} \mathrm{C}$.
[2] Frequency Accuracy: 25ppm of output frequency.
7.4 AC Voltage Specifications (Contd.)
7.4.5 AC Voltage Accuracy (Square-Wave)

| Frequency Band ${ }^{[2]}$ (Hz) | Output Voltage Span |  | Accuracy * | Current |
| :---: | :---: | :---: | :---: | :---: |
|  | RMS | Peak | $\begin{aligned} & \pm(\% \text { Output + Floor }) \\ & 1 \text { Year }- \text { Tcal } \\ & {[1] \pm 5^{\circ} \mathrm{C}} \end{aligned}$ | Compliance |
| 10-1k | OV-14.08mV | OV-14.14mV | $0.12+450 \mu \mathrm{~V}$ | 20 mA |
| 10-1k | 14.08 mV - 45.08 mV | 14.14mV - 45.25 mV | $0.12+150 \mu \mathrm{~V}$ | 20 mA |
| 10-1k | 45.08 mV - 450 mV | 45.25 mV - 452.5 mV | $0.12+40 \mu \mathrm{~V}$ | 20 mA |
| 10-1k | 450 mV - 4.5 V | 452.5mV - 4.525 V | $0.12+400 \mu \mathrm{~V}$ | 20 mA |
| 10-1k | 4.5 V - 45 V | 4.525 V - 45.25 V | $0.12+4 \mathrm{mV}$ | 20 mA |
| 10-1k | 45V-147.9V | 45.25V-148.4V | $0.12+10 \mathrm{mV}$ | 20 mA |
| 45-65 | 147.9V-450V | 148.4V-452.5V | $0.15+40 \mathrm{mV}$ | 6 mA |
| 45-65 | 450V-500V | 452.5V-502V | $0.15+110 \mathrm{mV}$ | 6 mA |

Ratios and Factors based on Square-Wave Unit-Value Peak

Peak
1.0000

Peak
2.0000

RMS:
0.9962

Mean:
0.9958

Crest Factor: 1.0038
Form Factor: 1.0004
7.4.6 AC Voltage Accuracy (Impulse-Wave)

$\left.$| Frequency <br> Band <br> $(\mathrm{Hz})$ | Output Voltage Span <br> RMS |  | Peak | Accuracy * <br> $\pm(\%$ Output + Floor) <br> $\mathbf{1 ~ Y e a r ~ - ~ T c a l ~}[1] \pm 5^{\circ} \mathrm{C}$ |
| :---: | :---: | :---: | :---: | :---: | | Current |
| :---: |
| Compliance | \right\rvert\,

## Ratios and Factors based on

 Impulse-Wave Unit-Value Peak| Peak: | 1.0000 |
| :--- | :--- |
| Peak to Peak: | 2.0000 |
| RMS: | 0.5270 |
| Mean: | 0.3333 |
| Crest Factor: | 1.8974 |
| Form Factor: | 1.5811 |

* $=$ For loads $<|1 \mathrm{M} \Omega|$ : add load regulation error
7.4.7 AC Voltage Accuracy (Triangular-Wave)

| Frequency Band [2] (Hz) | Output Voltage Span |  | Accuracy * | Current |
| :---: | :---: | :---: | :---: | :---: |
|  | RMS | Peak | $\begin{aligned} & \pm \text { (\% Output + Floor) } \\ & 1 \text { Year }- \text { Tcal }[1] \pm 5^{\circ} \mathrm{C} \end{aligned}$ | Compliance |
| 10-1k | OV-8.16mV | OV-14.14mV | $0.15+500 \mu \mathrm{~V}$ | 20 mA |
| 10-1k | 8.16mV-26.11mV | 14.14mV - 45.25 mV | $0.15+175 \mu \mathrm{~V}$ | 20 mA |
| 10-1k | 26.11mV-261mV | 45.25 mV - 452.5 mV | $0.15+40 \mu \mathrm{~V}$ | 20 mA |
| 10-1k | 261mV-2.61V | 452.5mV - 4.525 V | $0.15+400 \mu \mathrm{~V}$ | 20 mA |
| 10-1k | 2.61V-26.1V | 4.525V-45.25V | $0.15+4 \mathrm{mV}$ | 20 mA |
| 10-1k | 26.1V-85.7V | 45.25V-148.4V | $0.15+10 \mathrm{mV}$ | 20 mA |
| 45-65 | 85.7V-261V | 148.4V-452.5V | $0.18+40 \mathrm{mV}$ | 6 mA |
| 45-65 | 261V-500V | 452.5 V - 866V | $0.18+120 \mathrm{mV}$ | 6 mA |

## Ratios and Factors based on Triangular-Wave Unit-Value Peak

| Peak: | 1.0000 |
| :--- | :--- |
| Peak to Peak: | 2.0000 |
| RMS: | 0.5774 |
| Mean: | 0.5000 |
| Crest Factor: | 1.7321 |
| Form Factor: | 1.1547 |

* $=$ For loads $<|1 \mathrm{M} \Omega|$ : add load regulation error.

NOTES: [1] Tcal $=$ temperature at calibration. Factory calibration temperature $=23^{\circ} \mathrm{C}$.
[2] Frequency Accuracy: 25ppm of output frequency.
7.4.8 AC Voltage Accuracy (Trapezoidal-Wave)

$\left.$| Frequency <br> Band $[2]$ <br> $(\mathrm{Hz})$ | Output Voltage Span <br> RMS |  | Peak | Accuracy ${ }^{*}$ <br> $\pm(\%$ Output + Floor) <br> (Year - Tcal $[1] \pm 5^{\circ} \mathrm{C}$ |
| :---: | :---: | :---: | :---: | :---: | | Current |
| :---: |
| Compliance | \right\rvert\,

## Ratios and Factors based on

Trapezoidal-Wave Unit-Value Peak
Peak: 1.000
Peak to Peak: 2.0000
RMS:
2.0000
0.8819

Mean: 0.8333
Crest Factor: 1.3390
Form Factor: $\quad 1.0583$
7.4.9 Waveshape Harmonic Analysis
(Peak values as a percentage of the Fundamental's Peak Value)

| Harmonic | Square | Impulse | Triangular | Trapezoidal |
| :---: | :---: | :---: | :---: | :---: |
| 1 | 100.00 | 100.00 | 100.00 | 100.00 |
| 3 | -33.32 | 60.71 | 11.11 | -22.22 |
| 5 | 19.98 | 14.93 | 4.000 | 4.000 |
| 7 | -14.25 | -7.616 | 2.041 | 2.041 |
| 9 | 11.07 | -6.746 | 1.235 | -2.469 |
| 11 | -9.040 | -0.826 | 0.826 | 0.826 |
| 13 | 7.626 | -0.592 | 0.592 | 0.592 |
| 15 | -6.590 | -2.428 | 0.444 | -0.889 |
| 17 | 5.795 | -1.291 | 0.346 | 0.346 |
| 19 | -5.165 | 1.034 | 0.277 | 0.277 |
| 21 | 4.654 | 1.239 | 0.227 | -0.454 |
| 23 | -4.230 | 0.189 | 0.189 | 0.189 |
| 25 | 3.872 | 0.160 | 0.160 | 0.160 |
| 27 | -3.565 | 0.750 | 0.137 | -0.274 |
| 29 | 3.300 | 0.444 | 0.119 | 0.119 |
| 31 | -3.068 | -0.388 | 0.104 | 0.104 |
| 33 | 2.862 | -0.502 | 0.092 | -0.184 |
| 35 | -2.679 | -0.082 | 0.082 | 0.082 |
| 37 | 2.515 | -0.073 | 0.073 | 0.073 |
| 39 | -2.368 | -0.359 | 0.066 | -0.131 |
| 41 | 2.230 | -0.222 | 0.060 | 0.060 |

### 7.4.10 Other ACV Specifications

```
Settling Time (to within 10% of accuracy): \leq105V: 0.08s; >105V: 0.5s.
Load Regulation:
For loads < 1M M | \leq105V, add: [(200/RLOAD) + (CLOAD* x F}\mp@subsup{}{}{2}\times0.03)] % of output
For loads <|1M\Omega| >105V, add: [(200/RLOAD) + (CLOAD* x F2 x 0.19 + ClOAD* - 3E7)] % of output
* = To calculate C COAD limit from Current compliance specification, while using 9105 lead set, allow \approx30pF for lead set.
Maximum Capacitance: 1000pF; subject to Output Current Limitations at HF.
```


### 7.5 DC Current Specifications

7.5.1 DC Current Accuracy and Resolution

| Equivalent Current Output +ve \& -ve Polarities | Accuracy <br> $\pm$ (\% of Output + Floor) <br> 1Year - Tcal $\pm 5^{\circ} \mathrm{C}[1]$ | Compliance Voltage (at 9100 terminals) |  | Absolute Resolution |
| :---: | :---: | :---: | :---: | :---: |
| $000.000 \mu \mathrm{~A}-320.000 \mu \mathrm{~A}$ | $0.014+11 \mathrm{nA}$ | 4 V | 4 V | 1 nA |
| $0.32001 \mathrm{~mA}-3.20000 \mathrm{~mA}$ | $0.014+83 n A$ | 4 V | 4 V | 10nA |
| 03.2001mA - 32.0000 mA | 0.014 + 900nA | 4 V | 4 V | 100nA |
| 032..001mA - 320.000 mA | $0.016+9.6 \mu \mathrm{~A}$ | 4 V | 4 V | $1 \mu \mathrm{~A}$ |
| 0.32001A - 3.20000A | $0.060+118 \mu \mathrm{~A}$ | 2.2 V | 2.2 V | $10 \mu \mathrm{~A}$ |
| 03.2001A - 10.5000A | $0.055+940 \mu \mathrm{~A}$ | 2.2 V | 2.1 V | $100 \mu \mathrm{~A}$ |
| 10.5001A - 20.0000A * | $0.055+4.50 \mathrm{~mA}$ | 2.2 V | 2.0 V | $100 \mu \mathrm{~A}$ |

$=$ With output 'ON', maximum duty cycle of ( $>0.525 \mathrm{FS}: \leq 0.525 \mathrm{FS}$ ) is ( $1: 4$ ).
Continuous output $>0.525 \mathrm{FS}$ will automatically reduce to $<0.525 \mathrm{FS}$ after 2 Minutes
7.5.2 Option 200: DC Current Accuracy and Resolution via Current Coils
$\left.\begin{array}{|c|c|c|}\hline \begin{array}{c}\text { Equivalent } \\ \text { Current Output } \\ \text { +ve \& -ve Polarities }\end{array} & \begin{array}{c}\text { Accuracy } \dagger \\ \pm(\% \text { of Output }+ \text { Floor) } \\ \text { 1Year -Tcal } \pm 5^{\circ} \mathrm{C}\end{array}{ }^{[1]}\end{array}\right)$
$=$ With output 'ON', maximum duty cycle of ( $>0.525$ FS : $\leq 0.525$ FS ) is ( $1: 4$ ).
Refors to output $>0.525$ FS wir automaicaly reduce to <0.52
$=$ Refers to accuracy at 9100 output terminals. With Option 200 coils connected, then at the output from the coils, add $\pm 0.2 \%$ of output from coils for uncertainty of coils.

### 7.5.3 Other DCI Specifications

| Settling Time: | to within $10 \%$ of accuracy: 0.08 s |
| :--- | :---: |
| Maximum Terminal | $0-3.2 \mathrm{~mA}: 50 \mu \mathrm{H}$ |
| Inductance: | $3.2 \mathrm{~mA}-320 \mathrm{~mA}: 30 \mu \mathrm{H}$ |
|  | $320 \mathrm{~mA}-3.2 \mathrm{~A}: 18 \mu \mathrm{H}$ |
|  | $3.2 \mathrm{~A}-10.5 \mathrm{~A}: 5.5 \mu \mathrm{H}$ |
| (With 10 turn or 50 turn output selected): | $10.5 \mathrm{~A}-20 \mathrm{~A}: 2.5 \mu \mathrm{H}$ |
|  | $3.2 \mathrm{~A}-1000 \mathrm{~A}:$ |

NOTES: [1] Tcal $=$ temperature at calibration. Factory calibration temperature $=23^{\circ} \mathrm{C}$

### 7.6 AC Current Specifications

### 7.6.1 AC Current Accuracy (Sinusoidal Waveshape)

| Current Output | Frequency Band [2] (Hz) | $\begin{gathered} \text { Accuracy } \dagger \\ \pm(\% \text { Output }+ \text { Floor }) \\ \mathbf{1} \text { Year }- \text { Tcal }[1] \pm 5^{\circ} \mathrm{C} \end{gathered}$ | Compliance Voltage (VRMS at 9100 terminals) | Compliance Voltage (VRMS at 9105 Lead End) | Total Harmonic Distortion (\% Output) | Compliance Error (A/V) for Vc>0.5VRMS | Absolute Resolution |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $000.000 \mu \mathrm{~A}-032.000 \mu \mathrm{~A}$ | $10-3 k$ $3 k-10 k$ <br> 10k-20k <br> 20k-30k | $\begin{aligned} & 0.07+900 \mathrm{nA} \\ & 0.10+1.8 \mu \mathrm{~A} \\ & 0.20+6.0 \mu \mathrm{~A} \\ & 0.25+9.0 \mu \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 0.10 \\ & 0.25 \\ & 0.40 \\ & 0.60 \end{aligned}$ | 60nA/V $600 \mathrm{nA} / \mathrm{V}$ $2.4 \mu \mathrm{~A} / \mathrm{V}$ $5.4 \mu \mathrm{~A} / \mathrm{V}$ | $\begin{aligned} & \text { 1nA } \\ & \text { 1nA } \\ & \text { 1nA } \\ & \text { 1nA } \end{aligned}$ |
| 032.001 $\mu \mathrm{A}-320.000 \mu \mathrm{~A}$ | $10-3 k$ $3 \mathrm{k}-10 \mathrm{k}$ <br> 10k-20k <br> 20k-30k | $\begin{aligned} & 0.07+300 \mathrm{nA} \\ & 0.10+600 \mathrm{nA} \\ & 0.20+2.0 \mu \mathrm{~A} \\ & 0.25+3.0 \mu \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 0.10 \\ & 0.25 \\ & 0.40 \\ & 0.60 \end{aligned}$ | $60 \mathrm{nA} / \mathrm{V}$ $600 \mathrm{nA} / \mathrm{V}$ $2.4 \mu \mathrm{~A} / \mathrm{V}$ $5.4 \mu \mathrm{~A} / \mathrm{V}$ | $\begin{aligned} & \text { 1nA } \\ & \text { 1nA } \\ & \text { nA } \\ & \text { nnA } \end{aligned}$ |
| $0.32001 \mathrm{~mA}-3.20000 \mathrm{~mA}$ | $10-3 k$ $3 k-10 k$ <br> 10k-20k <br> 20k-30k | $\begin{aligned} & 0.07+300 \mathrm{nA} \\ & 0.10+600 \mathrm{nA} \\ & 0.20+2.0 \mu \mathrm{~A} \\ & 0.25+3.0 \mu \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 0.10 \\ & 0.25 \\ & 0.40 \\ & 0.60 \end{aligned}$ | 60nA/V $600 \mathrm{nA} / \mathrm{V}$ $2.4 \mu \mathrm{~A} / \mathrm{V}$ $5.4 \mu \mathrm{~A} / \mathrm{V}$ | $\begin{aligned} & 10 \mathrm{nA} \\ & 10 \mathrm{nA} \\ & 10 \mathrm{nA} \\ & 10 \mathrm{nA} \end{aligned}$ |
| 03.2001mA - 32.0000 mA | $10-3 k$ $3 k-10 k$ <br> 10k-20k <br> 20k-30k | $\begin{gathered} 0.07+3.2 \mu \mathrm{~A} \\ 0.10+6.4 \mu \mathrm{~A} \\ 0.20+22.8 \mu \mathrm{~A} \\ 0.25+22.4 \mu \mathrm{~A} \end{gathered}$ | $\begin{aligned} & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 0.10 \\ & 0.25 \\ & 0.40 \\ & 0.60 \end{aligned}$ | $0.5 \mu \mathrm{~A} / \mathrm{V}$ $4 \mu \mathrm{~A} / \mathrm{V}$ $15 \mu \mathrm{~A} / \mathrm{V}$ $32 \mu \mathrm{~A} / \mathrm{V}$ | $\begin{aligned} & 100 \mathrm{nA} \\ & 100 \mathrm{nA} \\ & 100 \mathrm{nA} \\ & 100 \mathrm{nA} \end{aligned}$ |
| 032.001mA - 320.000 mA | $10-3 k$ $3 \mathrm{k}-10 \mathrm{k}$ <br> 10k-20k <br> 20k-30k | $\begin{aligned} & 0.08+32.0 \mu \mathrm{~A} \\ & 0.10+48.0 \mu \mathrm{~A} \\ & 0.20+64.0 \mu \mathrm{~A} \\ & 0.25+96.0 \mu \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \\ & 4 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 0.10 \\ & 0.25 \\ & 0.40 \\ & 0.60 \end{aligned}$ | $2 \mu \mathrm{~A} / \mathrm{V}$ $4 \mu \mathrm{~A} / \mathrm{V}$ $15 \mu \mathrm{~A} / \mathrm{V}$ $35 \mu \mathrm{~A} / \mathrm{V}$ | $\begin{aligned} & 1 \mu \mathrm{~A} \\ & 1 \mu \mathrm{~A} \\ & 1 \mu \mathrm{~A} \\ & 1 \mu \mathrm{~A} \end{aligned}$ |
| 0.32001A-3.20000A | $\begin{aligned} & 10-3 k \\ & 3 \mathrm{k}-10 \mathrm{k} \end{aligned}$ | $\begin{aligned} & 0.10+480 \mu \mathrm{~A} \\ & 0.25+2.56 \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & 2.5 \mathrm{~V} \\ & 2.5 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 2.4 \mathrm{~V} \\ & 2.4 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 0.20 \\ & 1.10 \end{aligned}$ | $90 \mu \mathrm{~A} / \mathrm{V}$ $600 \mu \mathrm{~A} / \mathrm{V}$ | $\begin{aligned} & 10 \mu \mathrm{~A} \\ & 10 \mu \mathrm{~A} \end{aligned}$ |
| 03.2001A - 10.5000A | $\begin{aligned} & 10-3 k \\ & 3 k-10 k \end{aligned}$ | $\begin{aligned} & 0.20+3.0 \mathrm{~mA} \\ & 0.50+10.0 \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & 2.5 \mathrm{~V} \\ & 2.2 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 2.3 \mathrm{~V} \\ & 2.0 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 0.20 \\ & 1.10 \end{aligned}$ | $\begin{aligned} & 0.3 \mathrm{~mA} / \mathrm{V} \\ & 2.1 \mathrm{~mA} / \mathrm{V} \end{aligned}$ | $\begin{aligned} & 100 \mu \mathrm{~A} \\ & 100 \mu \mathrm{~A} \end{aligned}$ |
| 10.5001A - 20.0000A * | $\begin{aligned} & 10-3 k \\ & 3 \mathrm{k}-10 \mathrm{k} \end{aligned}$ | $\begin{aligned} & 0.20+6.9 \mathrm{~mA} \\ & 0.50+23.0 \mathrm{~mA} \end{aligned}$ | $\begin{gathered} 2.5 \mathrm{~V} \\ 2.1 \mathrm{~V} \end{gathered}$ | $\stackrel{2.2 \mathrm{~V}}{1.7 \mathrm{~V}}$ | $\begin{aligned} & 0.30 \\ & 1.50 \end{aligned}$ | $\begin{aligned} & 0.3 \mathrm{~mA} / \mathrm{V} \\ & 2.1 \mathrm{~mA} / \mathrm{V} \end{aligned}$ | $\begin{aligned} & 100 \mu \mathrm{~A} \\ & 100 \mu \mathrm{~A} \end{aligned}$ |
| 03.2001A - 32.0000A | $\begin{array}{r} 10-100 \\ 100-440 \end{array}$ | $\begin{aligned} & 0.20+5.5 \mathrm{~mA} \\ & 0.78+27 \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & 2.5 \mathrm{~V} \\ & 2.5 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 2.5 \mathrm{~V} \\ & 2.5 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 0.15 \\ & 0.50 \end{aligned}$ | ---- | $\begin{aligned} & 100 \mu \mathrm{~A} \\ & 100 \mu \mathrm{~A} \end{aligned}$ |
| 032.001A - 200.000A* | $\begin{array}{r} 10-100 \\ 100-440 \end{array}$ | $\begin{aligned} & 0.21+90 \mathrm{~mA} \\ & 0.67+0.25 \mathrm{~A} \end{aligned}$ | $\begin{gathered} 2.5 \mathrm{~V} \\ 2.5 \mathrm{~V} \end{gathered}$ | $\begin{gathered} 2.3 \mathrm{~V} \\ 2.3 \mathrm{~V} \end{gathered}$ | $\begin{aligned} & 0.15 \\ & 0.50 \end{aligned}$ | ---- | $\begin{aligned} & 1 \mathrm{~mA} \\ & 1 \mathrm{~mA} \end{aligned}$ |
| 016.001A - 160.000A * 0160.01A - 1000.00A** | $\begin{aligned} & 10-100 \\ & 10-100 \end{aligned}$ | $\begin{aligned} & 0.20+28 \mathrm{~mA} \\ & 0.21+0.45 \mathrm{~A} \end{aligned}$ | $\begin{gathered} 2.5 \mathrm{~V} \\ 2.5 \mathrm{~V} \end{gathered}$ | $\begin{gathered} 2.5 \mathrm{~V} \\ 2.3 \mathrm{~V} \end{gathered}$ | $\begin{aligned} & 0.15 \\ & 0.15 \end{aligned}$ | ---- | $\begin{gathered} 1 \mathrm{~mA} \\ 10 \mathrm{~mA} \end{gathered}$ |

* $=$ With output 'ON' maximum duty Continuous output $>0.525 \mathrm{FS}$ will automatically reduce to $<0.525 \mathrm{FS}$ after 2 Minutes.
$t=$ Total uncertainty includes compliance errors for Voltage $\leq 0.5 \mathrm{VRMS}$.
$=$ Refers to accuracy at 9100 ouput terminals. With Option 20010 turn coil connected, then at the output from the coil, add $\pm 0.2 \%$ of output from coil for uncertainty of coil.
= Refers to accuracy at 9100 output terminals. With Option 20050 turn coil connected, then at the output from the coil, add $\pm 0.2 \%$ of output from coil for uncertainty of coil.
= For frequencies $<40 \mathrm{~Hz}$, compliance voltage is reduced by 0.5 V RMS
ヘ = These coils have been designed for optimum accuracy and inductance for use with the Model 9100 . With some Hall effect clamp meters the increase in inductance, due to the current clamp design, will limit the obtainable 9100 Current/Hertz profile. In some cases, 1000A cannot be reached at higher frequency.

NOTES: [1] Tcal $=$ temperature at calibration. Factory calibration temperature $=23^{\circ} \mathrm{C}$.
[2] Frequency Accuracy: 25ppm of output frequency.
7.6 AC Current Specifications (Contd.)

### 7.6.2 Amp-Hertz Profile (Sinusoidal Waveshape)


7.6.3 Frequency Spans vs Frequency Resolutions

| Absolute <br> Resolution | Span of Frequencies |
| :--- | :--- |
| 1 mHz | 010.000 Hz |
| 10 mHz | to 320.000 Hz |
| 1000 mHz | 0.01000 kHz |
| 00.0100 kHz | to 3.2 .20000 kHz |

7.6.4 AC Current Phase (Sinusoidal Waveshape) *

Output Current Phase Span with respect to Phase Lock In $= \pm 180^{\circ}$
Resolution of Output Current phase increments $=0.01^{\circ}$

| Current Output | Selected Frequency f (Hz) | TTL Signals |  | 1V to 3V RMS Sine Input $\dagger$ Output Phase Error with respect to 'Phase Lock In' |
| :---: | :---: | :---: | :---: | :---: |
|  |  | Output Phase Error with respect to 'Phase Lock In' | Output Phase Error with respect to 'Phase Lock Out' |  |
| $0.00000 \mathrm{~A}-20.0000 \mathrm{~A}$ | $\begin{aligned} & 10-40 \\ & 40-65 \\ & 65-1 k \end{aligned}$ | $\begin{gathered} \pm 0.08^{\circ} \\ \pm 0.08^{\circ} \\ \pm(0.08+0.0008 \times f)^{\circ} \end{gathered}$ | $\begin{gathered} \pm 0.08^{\circ} \\ \pm 0.08^{\circ} \\ \pm(0.08+0.0008 \mathrm{xf})^{\circ} \end{gathered}$ | $\begin{gathered} \pm 0.71^{\circ} \\ \pm 0.15^{\circ} \\ \pm(0.15+0.001 \mathrm{xf})^{\circ} \end{gathered}$ |
| 03.2000 A - 1000.00 A A | $\begin{aligned} & 10-40 \\ & 40-65 \\ & 65-1 k \end{aligned}$ | $\begin{gathered} \pm 0.23^{\circ} \\ \pm 0.23^{\circ} \\ \pm(0.23+0.003 \mathrm{xf})^{\circ} \end{gathered}$ | $\begin{gathered} \pm 0.23^{\circ} \\ \pm 0.23^{\circ} \\ \pm(0.23+0.003 \mathrm{xf})^{\circ} \end{gathered}$ | $\begin{gathered} \pm 0.8^{\circ} \\ \pm 0.3^{\circ} \\ \pm(0.3+0.0037 \mathrm{xf})^{\circ} \end{gathered}$ |

Note: An application can be employed in which the 'Slave' frequency is set to a harmonic (multiple) of the 'Master' frequency. In this case the slave frequency must not exceed 1 kHz .

* = If two or more 9100 units are being used in a 'Master and Slave' configuration, this specification applies only when both Master and Slave are set to the same frequency. Mark/Space ratio of the input must not be less than 1:4.
$\dagger=$ DC-coupled input. Do not AC-couple. Up to 10 mV p-p noise is rejected.
- = With 10 -turn or 50 -turn output selected (Option 200)

NOTES: [1] Tcal $=$ temperature at calibration. Factory calibration temperature $=23^{\circ} \mathrm{C}$. [2] Frequency Accuracy: 25ppm of output frequency.
7.6.5 AC Current Accuracy (Square-Wave)

| Frequency Band [2] (Hz) | Output Current Span |  | Accuracy $\dagger$$\pm$ (\% Output + Floor)1 Year - Tcal $[1] \pm 5^{\circ} \mathrm{C}$ | Voltage Compliance (VRMS) |
| :---: | :---: | :---: | :---: | :---: |
|  | RMS | Peak |  |  |
| 10-1k | $0 \mu \mathrm{~A}-45.08 \mu \mathrm{~A}$ | 0V - $45.25 \mu \mathrm{~A}$ | $0.21+1.8 \mu \mathrm{~A}$ | 4.0 |
| 10-1k | $45.08 \mu \mathrm{~A}-4.508 \mathrm{~mA}$ | $45.25 \mu \mathrm{~A}-4.525 \mathrm{~mA}$ | $0.21+0.6 \mu \mathrm{~A}$ | 4.0 |
| 10-1k | 4.508 mA - 45.08 mA | $4.525 \mathrm{~mA}-45.25 \mathrm{~mA}$ | $0.21+6.4 \mu \mathrm{~A}$ | 4.0 |
| 10-1k | 45.08 mA - 450.8 mA | 45.25 mA - 452.5 mA | $0.24+64 \mu \mathrm{~A}$ | 4.0 |
| 10-100 | 0.4508A-3.200A | 0.4525A-3.212A | $0.30+960 \mu \mathrm{~A}$ | 2.2 |
| 10-100 | 3.200A - 18.00A* | 3.212A-18.07A | $0.4+13.8 \mathrm{~mA}$ | 2.2 - |
| 10-65 | 4.508A - 32.00A | 4.525A-32.12A | $1.0+16.8 \mathrm{~mA}$ | 2.2 |
| 10-65 | 32.00A - 180.0A* ${ }^{*}$ | 32.12A-180.7A | $1.2+162 \mathrm{~mA}$ | 2.2 • |
| 10-65 | 22.54A-160.0A - | 22.63A-160.6A | $1.0+84 \mathrm{~mA}$ | 2.2 |
| 10-65 | 160.0A - 900.0A** | 160.6A-903.5A | $1.2+0.82 \mathrm{~A}$ | 2.2 - |

## Ratios and Factors based on

 Square-Wave Unit-Value Peak| Peak: | 1.0000 |
| :--- | :--- |
| Peak to Peak: | 2.0000 |
| RMS: | 0.9962 |
| Mean: | 0.9958 |
| Crest Factor: | 1.0038 |
| Form Factor: | 1.0004 |

$*=$ With output 'ON', maximum duty cycle of ( $>0.528 \mathrm{FS}: \leq 0.528 \mathrm{FS}$ ) is ( $1: 4$ ).
Continuous output $>0.528$ FS will automatically reduce to $<0.528$ FS after 2 Minutes
$\dagger=$ Total uncertainty includes compliance errors for Voltage $\leq 0.5 \mathrm{VRMS}$.
Above 0.5 V , add appropriate compliance error, except for Outputs marked $\vee$ and $\boldsymbol{*}$.
$\boldsymbol{\nu}$ = Refers to accuracy at 9100 output terminals. With Option 20010 turn coil connected, then at the output from the coil, add $\pm 0.2 \%$ of output from coil for uncertainty of coil.

* = Refers to accuracy at 9100 output terminals. With Option 20050 turn coil connected, then at the output from the coil, add $\pm 0.2 \%$ of output from coil for uncertainty of coil.
- = For frequencies $<40 \mathrm{~Hz}$, compliance voltage is reduced by 0.5 V RMS.
7.6.6 AC Current Accuracy (Impulse-Wave)

| $\begin{aligned} & \text { Frequency } \\ & \text { Band }{ }^{[2]} \\ & (\mathrm{Hz}) \end{aligned}$ | Output Current Span |  | Accuracy $\dagger$ | Voltage |
| :---: | :---: | :---: | :---: | :---: |
|  | RMS | Peak | $\pm$ (\% Output + Floor) <br> 1 Year - Tcal ${ }^{[1]} \pm 5^{\circ} \mathrm{C}$ | Compliance (VRMS) |
| 10-1k | 0 $\mu \mathrm{A}-23.79 \mu \mathrm{~A}$ | OV - $45.25 \mu \mathrm{~A}$ | $0.42+2.7 \mu \mathrm{~A}$ | 3.0 |
| 10-1k | $23.79 \mu \mathrm{~A}-2.379 \mathrm{~mA}$ | $45.25 \mu \mathrm{~A}-4.525 \mathrm{~mA}$ | $0.42+0.9 \mu \mathrm{~A}$ | 3.0 |
| 10-1k | $2.379 \mathrm{~mA}-23.79 \mathrm{~mA}$ | $4.525 \mathrm{~mA}-45.25 \mathrm{~mA}$ | $0.42+9.6 \mu \mathrm{~A}$ | 3.0 |
| 10-1k | 23.79 mA - 237.9 mA | 45.25 mA - 452.5 mA | $0.48+96 \mu \mathrm{~A}$ | 3.0 |
| 10-100 | 0.2379A-2.379A | 0.4525A-4.525A | $0.60+1.44 \mathrm{~mA}$ | 1.8 |
| 10-100 | 2.379A-15.00A* | 4.525A - 28.53A | $0.80+20.7 \mathrm{~mA}$ | 1.8 - |
| 10-65 | 2.379A-23.79A | 4.525A - 45.25A | $0.80+25.2 \mathrm{~mA}$ | 1.8 |
| 10-65 | 23.79A-150.0A* | 45.25A - 285.3A | $1.20+243 \mathrm{~mA}$ | 1.8 * |
| 10-65 | 11.90A-118.9A * | 22.63A-226.3A | $0.80+126 \mathrm{~mA}$ | 1.8 |
| 10-65 | 118.9A-750.0A** | 226.3A-1426A | $1.20+1.23 \mathrm{~A}$ | 1.8 * |

## Ratios and Factors based on Impulse-Wave Unit-Value Peak

| Peak: | 1.0000 |
| :--- | :--- |
| Peak to Peak: | 2.0000 |
| RMS: | 0.5270 |
| Mean: | 0.3333 |
| Crest Factor: | 1.8974 |
| Form Factor: | 1.5811 |

* = With output 'ON', maximum duty cycle of ( $>0.7 \mathrm{FS}: \leq 0.7 \mathrm{FS}$ ) is $(1: 4)$

Continuous output $>0.525$ FS will automatically reduce to $<0.525$ FS after 2 Minutes.
$\dagger=$ Total uncertainty includes compliance errors for Voltage $\leq 0.5 \mathrm{VRMS}$.
Above 0.5 V , add appropriate compliance error, except for Outputs marked $\downarrow$ and $\boldsymbol{\sim}$
v = Refers to accuracy at 9100 output terminals. With Option 20010 turn coil connected, then at the output from the coil, add $\pm 0.2 \%$ of output from coil for uncertainty of coil.
$\star=$ Refers to accuracy at 9100 output terminals. With Option 20050 turn coil connected, then at the output from the coil, add $\pm 0.2 \%$ of output from coil for uncertainty of coil.

- = For frequencies $<40 \mathrm{~Hz}$, compliance voltage is reduced by 0.5 V RMS


### 7.6 AC Current Specifications (Contd.)

7.6.7 AC Current Accuracy (Triangular-Wave)

| Frequency Band ${ }^{[2]}$ (Hz) | Output Current Span |  | $\begin{gathered} \text { Accuracy } \dagger \\ \pm \text { (\% Output }+ \text { Floor }) \\ 1 \text { Year }- \text { Tcal }[1] \pm 5^{\circ} \mathrm{C} \end{gathered}$ | Voltage Compliance (VRMS) |
| :---: | :---: | :---: | :---: | :---: |
|  | RMS | Peak |  |  |
| 10-1k | 0 $\mu \mathrm{A}-26.12 \mu \mathrm{~A}$ | 0 $\mu \mathrm{A}-45.25 \mu \mathrm{~A}$ | $0.21+1.8 \mu \mathrm{~A}$ | 3.2 |
| 10-1k | $26.12 \mu \mathrm{~A}-2.612 \mathrm{~mA}$ | $45.25 \mu \mathrm{~A}-4.525 \mathrm{~mA}$ | $0.21+0.6 \mu \mathrm{~A}$ | 3.2 |
| 10-1k | $2.612 \mathrm{~mA}-26.12 \mathrm{~mA}$ | $4.525 \mathrm{~mA}-45.25 \mathrm{~mA}$ | $0.21+6.4 \mu \mathrm{~A}$ | 3.2 |
| 10-1k | 26.12 mA - 261.2 mA | 45.25mA - 452.5 mA | $0.24+64 \mu \mathrm{~A}$ | 3.2 |
| 10-100 | 0.2612A-2.612A | 0.4525A-4.525A | $0.30+960 \mu \mathrm{~A}$ | 2.0 |
| 10-100 | 2.612A - 16.30A* | 4.525A-28.23A | $0.40+13.8 \mathrm{~mA}$ | 2.0 - |
| 10-65 | 2.612A - 26.12 A - | 4.525A - 45.25A | $0.40+16.8 \mathrm{~mA}$ | 2.0 |
| 10-65 | 26.12A - 163.0A* | 45.25A - 282.3A | $0.60+162 \mathrm{~mA}$ | 2.0 - |
| 10-65 | 13.06A - 130.6A * | 22.62A-226.2A | $0.40+84 \mathrm{~mA}$ | 2.0 |
| 10-65 | 130.6A-815.0A** | 226.2A-1411A | $0.60+0.82 \mathrm{~A}$ | 2.0 • |

Ratios and Factors based on Triangular-Wave Unit-Value Peak

| Peak: | 1.0000 |
| :--- | ---: |
| Peak to Peak: | 2.0000 |
| RMS: | $0 . .5774$ |
| Mean: | 0.5000 |
| Crest Factor: | 1.7321 |
| Form Factor: | 1.1547 |

$=$ With output 'ON', maximum duty cycle of ( $>0.644 \mathrm{FS}: \leq 0.644 \mathrm{FS}$ ) is $(1 \cdot 4)$
Continuous output $>0.644 \mathrm{FS}$ will automatically reduce to $<0.644 \mathrm{FS}$ after 2 Minutes
= Total uncertainty includes compliance errors for Voltage $\leq 0.5 \mathrm{VRMS}$
Above 0.5 V , add appropriate compliance error, except for Outputs marked $\downarrow$ and $\&$
$\checkmark$ = Refers to accuracy at 9100 output terminals. With Option 20010 turn coil connected, then at the output from the coil, add $\pm 0.2 \%$ of output from coil for uncertainty of coil.

* $=$ Refers to accuracy at 9100 output terminals. With Option 20050 turn coil connected, then at the output from the coil, add $\pm 0.2 \%$ of output from coil for uncertainty of coil.
= For frequencies $<40 \mathrm{~Hz}$, compliance voltage is reduced by 0.5 V RMS
7.6.8 AC Current Accuracy (Trapezoidal-Wave)

$\left.$| Frequency <br> Band $[2]$ <br> $(\mathrm{Hz})$ | Output Current Span <br> RMS |  | Peak | Accuracy $\dagger$ <br> $\pm(\%$ Output + Floor $)$ <br> 1 Year - Tcal $[1] \pm 5^{\circ} \mathrm{C}$ |
| :---: | :---: | :---: | :---: | :---: | | Voltage |
| :---: |
| Compliance |
| $($ VRMS $)$ | \right\rvert\,

## Ratios and Factors based on

 Trapezoidal-Wave Unit-Value Peak| Peak: | 1.0000 |
| :--- | :--- |
| Peak to Peak: | 2.0000 |
| RMS: | 0.8819 |
| Mean: | 0.8333 |
| Crest Factor: | 1.3389 |
| Form Factor: | 1.0583 |

= With output 'ON', maximum duty cycle of ( $>0.547 \mathrm{FS}: \leq 0.547 \mathrm{FS}$ ) is $(1: 4)$ Continuous output $>0.547$ FS will automatically reduce to $<0.547$ FS after 2 Minutes.
$=$ Total uncertainty includes compliance errors for Voltage $\leq 0.5 \mathrm{VRMS}$
Above 0.5 V , add appropriate compliance error, except for Outputs marked $\downarrow$ and $\boldsymbol{\circ}$

- Refers to accuracy at 9100 output terminals. With Option 20010 turn coil connected, then at the output from the coil, add $\pm 0.2 \%$ of output from coil for uncertainty of coil.
- Refers to accuracy at 9100 output terminals. With Option 20050 turn coil connected, then at the output from the coil, add $\pm 0.2 \%$ of output from coil for uncertainty of coil.
- For frequencies $<40 \mathrm{~Hz}$, compliance voltage is reduced by 0.5 V RMS


### 7.6.9 Waveshape Harmonic Analysis

(Peak values as a percentage of the Fundamental's Peak Value)

| Harmonic | Square | Impulse | Triangular | Trapezoidal |
| :---: | :---: | :---: | :---: | :---: |
| 1 | 100.00 | 100.00 | 100.00 | 100.00 |
| 3 | -33.32 | 60.71 | 11.11 | -22.22 |
| 5 | 1.98 | 14.93 | 4.000 | 4.000 |
| 7 | -14.25 | -7.616 | 2.041 | 2.041 |
| 9 | 11.07 | -6.746 | 1.235 | -2.469 |
| 11 | -9.040 | -0.826 | 0.826 | 0.826 |
| 13 | 7.626 | -0.592 | 0.592 | 0.592 |
| 15 | -6.590 | -2.428 | 0.444 | -0.889 |
| 17 | 5.795 | -1.291 | 0.346 | 0.346 |
| 19 | -5.165 | 1.034 | 0.277 | 0.277 |
| 21 | 4.654 | 1.239 | 0.227 | -0.454 |
| 23 | -4.230 | 0.189 | 0.189 | 0.189 |
| 25 | 3.872 | 0.160 | 0.160 | 0.160 |
| 27 | -3.565 | 0.750 | 0.137 | -0.274 |
| 29 | 3.300 | 0.444 | 0.119 | 0.119 |
| 31 | -3.068 | -0.388 | 0.104 | 0.104 |
| 33 | 2.862 | -0.502 | 0.092 | -0.184 |
| 35 | -2.679 | -0.082 | 0.082 | 0.082 |
| 37 | 2.515 | -0.073 | 0.073 | 0.073 |
| 39 | -2.368 | -0.359 | 0.066 | -0.131 |
| 41 | 2.230 | -0.222 | 0.060 | 0.060 |

### 7.6.10 Other ACI Specifications

| Settling Time: | to within $10 \%$ of accuracy: 0.08 s |
| :--- | ---: |
|  |  |
| Maximum Terminal | $0-3.2 \mathrm{~mA}: 50 \mu \mathrm{H}$ |
| Inductance: | $3.2 \mathrm{~mA}-320 \mathrm{~mA} \vdots 30 \mu \mathrm{H}$ |
|  | $320 \mathrm{~mA}-3.2 \mathrm{~A} \vdots$ |
|  | $3.2 \mathrm{~A}-10.5 \mathrm{~A} \vdots$ |
|  | $5.5 \mu \mathrm{H}$ |
| (With 10 turn or 50 turn output selected): | $10.5 \mathrm{~A}-20 \mathrm{~A} \vdots$ |
|  | $3.2 \mathrm{~A}-1000 \mathrm{~A}:$ |
|  |  |

NOTES: [1] Tcal $=$ temperature at calibration. Factory calibration temperature $=23^{\circ} \mathrm{C}$.
[2] Frequency Accuracy: 25ppm of output frequency.

### 7.7 Resistance Specifications

7.7.1 Resistance Accuracy and Resolution

| Resistance Output | Accuracy |  |  | Absolute Resolution |
| :---: | :---: | :---: | :---: | :---: |
|  | (Source UUTi Low) $\pm(\%$ of Output + Floor) <br> 1Year - Tcal $\pm 5^{\circ} \mathrm{C}{ }^{[1]}$ | (Source UUTi High) $\pm(\%$ of Output + Floor) <br> 1Year - Tcal $\pm 5^{\circ} \mathrm{C}{ }^{[1]}$ | (Source UUTi Super) $\pm$ (\% of Output + Floor) <br> 1Year - Tcal $\pm 5^{\circ} \mathrm{C}{ }^{[1]}$ |  |
| $00.0000 \Omega$ to $40.0000 \Omega$ | $0.025+10.0 \mathrm{~m} \Omega$ | $0.050+20.0 \mathrm{~m} \Omega$ | $0.100+50.0 \mathrm{~m} \Omega$ | $0.1 \mathrm{~m} \Omega$ |
| $040.001 \Omega$ to $400.000 \Omega$ | $0.020+20.0 \mathrm{~m} \Omega$ * | $0.015+20.0 \mathrm{~m} \Omega$ | $0.035+100 \mathrm{~m} \Omega$ | $1 \mathrm{~m} \Omega$ |
| $0.40001 \mathrm{k} \Omega$ to $4.00000 \mathrm{k} \Omega$ | $0.015+80.0 \mathrm{~m} \Omega$ | $0.015+80.0 \mathrm{~m} \Omega$ | $0.035+200 \mathrm{~m} \Omega$ | $10 \mathrm{~m} \Omega$ |
| $04.0001 \mathrm{k} \Omega$ to $40.0000 \mathrm{k} \Omega$ | $0.020+800 \mathrm{~m} \Omega$ | $0.015+800 \mathrm{~m} \Omega$ | $0.025+2.0 \Omega$ | $100 \mathrm{~m} \Omega$ |
| $040.001 \mathrm{k} \Omega$ to $400.000 \mathrm{k} \Omega$ | $0.020+8.0 \Omega$ | $0.018+8.0 \Omega$ | $0.025+20 \Omega$ | $1 \Omega$ |
| $0.40001 \mathrm{M} \Omega$ to $4.00000 \mathrm{M} \Omega$ | $0.050+100 \Omega$ | $0.020+100 \Omega$ | $0.040+200 \Omega$ | $10 \Omega$ |
| $04.0001 \mathrm{M} \Omega$ to $40.0000 \mathrm{M} \Omega$ | $0.150+2.0 \mathrm{k} \Omega$ | $0.050+2.0 \mathrm{k} \Omega$ | $0.050+2.0 \mathrm{k} \Omega$ | $100 \Omega$ |
| $040.001 \mathrm{M} \Omega$ to $400.000 \mathrm{M} \Omega$ | $0.260+40.0 \mathrm{k} \Omega$ | $0.060+40.0 \mathrm{k} \Omega$ | --- | $1 \mathrm{k} \Omega$ |

$=$ Valid for UUTi $\geq 200 \mu \mathrm{~A}$
Below $200 \mu \mathrm{~A}$ : new floor $=(200 \mu \mathrm{~A} \div$ Actual UUTi) $\times 20 \mathrm{~m} \Omega$

### 7.7.3 Source Current - Limits

| Hardware Configuration Limits <br> on Span of Output Resistance | UUTi Low | Source Current Limits <br> UUTi High | UUTi Super |
| :---: | :---: | :---: | :---: |
| $00.0000 \Omega$ to $40.0000 \Omega$ | $250 \mu \mathrm{~A}$ to 3.5 mA | 2.5 mA to 35 mA | 25 mA to 350 mA |
| $040.001 \Omega$ to $400.000 \Omega$ | $25 \mu \mathrm{~A}$ to $320 \mu \mathrm{~A}$ | $250 \mu \mathrm{~A}$ to 3.5 mA | 2.5 mA to 35 mA |
| $0.40001 \mathrm{k} \Omega$ to $4.00000 \mathrm{k} \Omega$ | $25 \mu \mathrm{~A}$ to $320 \mu \mathrm{~A}$ | $250 \mu \mathrm{~A}$ to 3.5 mA | 2.5 mA to 35 mA |
| $04.0001 \mathrm{k} \Omega$ to $40.0000 \mathrm{k} \Omega$ | $2.5 \mu \mathrm{~A}$ to $32 \mu \mathrm{~A}$ | $25 \mu \mathrm{~A}$ to $350 \mu \mathrm{~A}$ | $250 \mu \mathrm{~A}$ to 3.5 mA |
| $040.001 \mathrm{k} \Omega$ to $400.000 \mathrm{k} \Omega$ | 250 nA to $3.2 \mu \mathrm{~A}$ | $2.5 \mu \mathrm{~A}$ to $35 \mu \mathrm{~A}$ | $25 \mu \mathrm{~A}$ to $350 \mu \mathrm{~A}$ |
| $0.40001 \mathrm{M} \Omega$ to $4.00000 \mathrm{M} \Omega$ | 25 nA to 320 nA | 250 nA to $3.5 \mu \mathrm{~A}$ | $2.5 \mu \mathrm{~A}$ to $35 \mu \mathrm{~A}$ |
| $04.0001 \mathrm{M} \Omega$ to $40.0000 \mathrm{M} \Omega$ | 8 nA to 32 nA | 25 nA to 350 nA | 250 nA to $3.5 \mu \mathrm{~A}$ |
| $040.001 \mathrm{M} \Omega$ to $400.000 \mathrm{M} \Omega$ | 4 nA to 32 nA | 25 nA to 200 nA | $\mathrm{N} / \mathrm{A}$ |

7.7.4 Other Resistance Specifications


NOTES: [1] Tcal $=$ temperature at calibration. Factory calibration temperature $=23^{\circ} \mathrm{C}$

### 7.8 Conductance Specifications

### 7.8.1 Conductance Accuracy

| Conductance Output | $\begin{gathered} \text { Accuracy } \\ \pm(\% \text { Output }) \\ \text { 1Year }- \text { Tcal } \pm 5^{\circ} \mathrm{C}[1] \end{gathered}$ |  |
| :---: | :---: | :---: |
|  | UUTi Low \& High | UUTi Super |
| 2.5nS - 25.0nS | 0.40 | N/A |
| 25.0nS - 250.0nS | 0.20 | 0.45 |
| 250.0 nS - $2.5 \mu \mathrm{~S}$ | 0.12 | 0.27 |
| $2.5 \mu \mathrm{~S}-25.0 \mu \mathrm{~S}$ | 0.05 | 0.12 |
| $25.0 \mu \mathrm{~S}-250.0 \mu \mathrm{~S}$ | 0.05 | 0.12 |
| $250.0 \mu \mathrm{~S}-2.5 \mathrm{mS}$ | 0.04 | 0.09 |

7.8.2 Conductance Span vs Resolution

| Absolute <br> Resolution | Span of Values |
| :--- | :---: |
| 0.1 pS | 02.5000 nS to 25.0000 nS |
| 1 pS | 002.500 nS to 250.000 nS |
| 10 pS | $0.00250 \mu \mathrm{~S}$ to $2.50000 \mu \mathrm{~S}$ |
| 100 pS | $00.0025 \mu \mathrm{~S}$ to $25.0000 \mu \mathrm{~S}$ |
| 1 nS | $000.002 \mu \mathrm{~S}$ to $250.000 \mu \mathrm{~S}$ |
| 10 nS | 0.00001 mS to 2.50000 mS |

7.8.3 Source Current - Limits

| Hardware Configuration Limits <br> on Span of Output Conductance | UUTi Low | Current Source Limits <br> UUTi High | UUTi Super |
| :---: | :---: | :---: | :---: |
| 02.5000 nS to 25.0000 nS | 4 nA to 32 nA | 2.5 nA to 200 nA | N $/ \mathrm{A}$ |
| 025.001 nS to 250.000 nS | 8 nA to 32 nA | 25 nA to 350 nA | 250 nA to $3.5 \mu \mathrm{~A}$ |
| $0.25001 \mu \mathrm{~S}$ to $2.50000 \mu \mathrm{~S}$ | 25 nA to 320 nA | 250 nA to $3.5 \mu \mathrm{~A}$ | $2.5 \mu \mathrm{~A}$ to $35 \mu \mathrm{~A}$ |
| $02.5001 \mu \mathrm{~S}$ to $25.0000 \mu \mathrm{~S}$ | 250 nA to $3.2 \mu \mathrm{~A}$ | $2.5 \mu \mathrm{~A}$ to $35 \mu \mathrm{~A}$ | $25 \mu \mathrm{~A}$ to $350 \mu \mathrm{~A}$ |
| $025.001 \mu \mathrm{~S}$ to $250.000 \mu \mathrm{~S}$ | $2.5 \mu \mathrm{~A}$ to $32 \mu \mathrm{~A}$ | $25 \mu \mathrm{~A}$ to $350 \mu \mathrm{~A}$ | $250 \mu \mathrm{~A}$ to 3.5 mA |
| 0.25001 mS to 2.50000 mS | $25 \mu \mathrm{~A}$ to $320 \mu \mathrm{~A}$ | $250 \mu \mathrm{~A}$ to 3.5 mA | 2.5 A to 35 mA |

7.8.4 Other Conductance Specifications


NOTES: [1] Tcal $=$ temperature at calibration. Factory calibration temperature $=23^{\circ} \mathrm{C}$

### 7.9 Frequency Function Specifications

### 7.9.1 Frequency Function Accuracy

| Frequency Output | Accuracy <br> $\pm$ (ppm of Output Frequency) <br> 1Year - Tcal $\pm 5^{\circ} \mathrm{C}[1]$ <br> Standard | Accuracy <br> $\pm($ ppm of Output Frequency) <br> 5Year - Tcal $\pm 5^{\circ} \mathrm{C}$ <br> Option 100 |
| :---: | :---: | :---: |
| $0.5 \mathrm{~Hz}-10.0 \mathrm{MHz}$ | 25.0 | 0.25 |

7.9.2 High and Low Voltage Limits and Voltage Accuracy

| Frequency <br> Span | Output <br> Voltage Vo | Accuracy <br> ( $\pm$ Volts) <br> 1Year $-\mathrm{Tcal} \pm 5^{\circ} \mathrm{C}^{[1]}$ |
| :--- | :---: | :---: |
| 0.5 Hz to 2 MHz | $\mathrm{Vo} \leq 6 \mathrm{Vpk}$ | $0.06 \mathrm{~V} \dagger$ |
| 2 MHz to 10 MHz | $\mathrm{Vo} \leq 6 \mathrm{Vpk}$ | 1.0 V |
| 0.5 Hz to 1 kHz | $6 \mathrm{Vpk}<\mathrm{Vo} \leq 30 \mathrm{Vpk}$ | 0.3 V |



Fig. 7.9.1 Frequency Function Default Output Waveshape
7.9.3 Frequency Spans vs Frequency Resolution

| Absolute <br> Resolution | Span of Frequencies |  | Output Voltage <br> $\leq 6 V p k$ |  |
| :--- | :--- | :--- | :---: | :---: |
| 6 Vpk |  |  |  |  |$|$| 1 mHz | 000.500 Hz | to 320.000 Hz | $*$ |
| :--- | :--- | :--- | :--- |
| 10 mHz | 0.00050 kHz | to 1.00000 kHz | $*$ |
| 10 mHz | 1.00001 kHz | to 3.20000 kHz | $*$ |
| 100 mHz | 00.0005 kHz | to 32.0000 kHz | $*$ |
| 1 Hz | 000.001 kHz | to 320.000 kHz | $*$ |
| 10 Hz | 0.00001 MHz | to 3.20000 MHz | $*$ |
| 100 Hz | 00.0001 MHz | to 10.0000 MHz | -- |

* = Peak outputs available at stated levels.
7.9.4 Rise Times (Specified into loads $R_{L}>100 k \Omega$ in parallel with $C_{L} \leq 100 \mathrm{pF}$ )
$\begin{array}{ll}\text { For signals } \leq 6 \mathrm{Vpk}: & <40 \mathrm{~ns} . \\ \text { For signals }>6 \mathrm{Vpk}: & <1.5 \mu \mathrm{~s} .\end{array}$

NOTES: [1] Tcal $=$ temperature at calibration. Factory calibration temperature $=23^{\circ} \mathrm{C}$

### 7.10 Mark/Period Function Specifications

### 7.10.1 Pulse Width and Repetition Period Intervals Accuracy

| Output Voltage | Interval | Accuracy <br> $\pm$ (ppm of Output + Floor) <br> 1Year - Tcal $\pm 5^{\circ} \mathrm{C}{ }^{[1]}$ | Option 100 Accuracy <br> $\pm$ (ppm of Output + Floor) <br> 5Year - Tcal $\pm 5^{\circ} \mathrm{C}$ |
| :---: | :---: | :---: | :---: |
| V o $\leq 6 \mathrm{Vpk}$ | Pulse Width: $\quad 0.30 \mu \mathrm{~s}$ to 1999.99 ms Repetition Period: $\quad 0.6 \mu \mathrm{~s}$ to 2000 ms | $\begin{aligned} & 25+50 \mathrm{~ns} \\ & 25 \end{aligned}$ | $\begin{aligned} & 0.25+50 \mathrm{~ns} \\ & 0.25 \end{aligned}$ |
| $6 \mathrm{Vpk}<\mathrm{Vo} \leq 30 \mathrm{Vpk}$ | Pulse Width: $\left.\begin{array}{c}10 \mu \mathrm{~s} \text { to } 1999.99 \mathrm{~ms} \\ \text { Repetition Period: } \\ 1 \mathrm{~ms} \text { to } 2000 \mathrm{~ms}\end{array}\right]$ | $\begin{aligned} & 25+250 \mathrm{~ns} \\ & 25 \end{aligned}$ | $\begin{aligned} & 0.25+250 \mathrm{~ns} \\ & 0.25 \end{aligned}$ |

7.10.2 High and Low Voltage Limits and Voltage Accuracy

| Output <br> Voltage Vo | Accuracy <br> ( $\pm$ Volts) <br> 1Year $-\mathrm{Tcal} \pm 5^{\circ} \mathrm{C}^{[1]}$ |
| :---: | :---: |
| $\mathrm{Vo} \leq 6 \mathrm{Vpk}$ | $0.06 \mathrm{~V} \dagger$ |
| $6 \mathrm{Vpk}<\mathrm{Vo} \leq 30 \mathrm{Vpk}$ | 0.3 V |

$\dagger=$ After first 150ns.


Fig. 7.10.1 Mark/Period Function Generalized Output Waveshape Definition
7.10.3 Pulse Width Interval Spans vs Time Resolution

| Absolute <br> Resolution | $\leq 6 \mathrm{~V}$ pk |  | $>6 \mathrm{Vpk}$ |  |
| :--- | :--- | :--- | :--- | :--- |
| 100 ns | $000.3 \mu \mathrm{~s}$ | to $999.9 \mu \mathrm{~s}^{*}$ | $010.00 \mu \mathrm{~s}$ | to $990.0 \mu \mathrm{~s}^{* *}$ |
| 100 ns | 00.0003 ms | to $99.9999 \mathrm{~ms}^{*}$ | 00.0100 ms | to $99.9999 \mathrm{~ms}^{* *}$ |
| $1 \mu \mathrm{~s}$ | 000.001 ms | to 999.999 ms | 000.010 ms | to $999.999 \mathrm{~ms}^{* *}$ |
| $10 \mu \mathrm{~s}$ | 0000.01 ms | to 1999.99 ms | 0000.01 ms | to 1999.99 ms |

${ }^{*}=$ Maximum Pulse Width interval must be at least $0.3 \mu$ s less than that of the set Repetition Period.
$* *=$ Maximum Pulse Width interval must be at least $10 \mu$ s less than that of the set Repetition Period.

### 7.10.4 Repetition Period Interval Spans vs Time Resolution

| Absolute <br> Resolution | $\leq 6 \mathrm{~V} \mathrm{pk}$ |  |  | $>6 \mathrm{Vpk}$ |  |
| :--- | :--- | :--- | :--- | :--- | :---: |
| 100 ns | $000.6 \mu \mathrm{~s}$ | to $999.9 \mu \mathrm{~s}$ |  | ---- |  |
| 100 ns | 00.0006 ms | to 99.9999 ms | 01.0000 ms | to 99.9999 ms |  |
| $1 \mu \mathrm{~s}$ | 000.001 ms | to 999.999 ms | 001.000 ms | to 999.999 ms |  |
| $10 \mu \mathrm{~s}$ | 0000.01 ms | to 2000.00 ms | 0001.00 ms | to 2000.00 ms |  |

7.10.5 Rise Times (Specified into loads $R_{L}>100 k \Omega$ in parallel with $C_{L} \leq 100 \mathrm{pF}$ )
For signals $\leq 6 \mathrm{Vpk}$ :
$<40 \mathrm{~ns}$
For signals $>6 \mathrm{Vpk}: \quad<1.5 \mu \mathrm{~s}$.

NOTES
[1] Tcal $=$ temperature at calibration. Factory calibration temperature $=23^{\circ} \mathrm{C}$

### 7.11 \% Duty Cycle Function Specifications

### 7.11.1 Introduction

Duty Cycle is a derived (relative) quantity which describes the Pulse Width / Repetition Period ratio of a pulsed waveform. In the 9100 , it is expressed as a percentage. The values of Pulse Width and Repetition Period will change with frequency, while maintaining the same percentage ratio.

Hardware limitations drive the \% Duty Cycle to a limit only when the Pulse Width and Repetition Period intervals reach their individual limits at particular frequencies. This means that any accuracy specification must be expressed in terms of constituent time intervals.

### 7.11.2 '\% Duty' Value: Screen Setting Limits

00.05\% $\leq$ \% Duty $\leq 99.95 \%$
7.11.3 Repetition Period Interval Accuracy

| Output Voltage | Interval | Accuracy $\pm$ (ppm of Output) 1Year - Tcal $\pm 5^{\circ}{ }^{\circ}{ }^{(1)}$ | Option 100 Accuracy <br> $\pm$ (ppm of Output) <br> 5Year - Tcal $\pm 5^{\circ} \mathrm{C}^{[1]}$ |
| :---: | :---: | :---: | :---: |
| V o $\leq 6 \mathrm{Vpk}$ | $100 \mu \mathrm{~s}$ to 2000 ms | 25 | 0.25 |
| $6 \mathrm{Vpk}<\mathrm{Vo} \leq 30 \mathrm{Vpk}$ | 1 ms to 2000 ms | 25 | 0.25 |

7.11.4 Duty Cycle Accuracy

| Output Voltage | Total Accuracy <br> 1 Year $-\mathrm{Tcal} \pm 5^{\circ} \mathrm{C}{ }^{[1]}$ |
| :---: | :---: |
| Vo $\leq 6 \mathrm{Vpk}$ | 50 ns |
| $6 \mathrm{Vpk}<\mathrm{Vo} \leq 30 \mathrm{Vpk} \ddagger$ | 250 ns |

7.11.5 High and Low Voltage Limits and Voltage Accuracy

| Output Voltage Vo | Accuracy ( $\pm$ Volts) <br> 1Year - Tcal $\pm 5^{\circ}{ }^{[11}$ |
| :---: | :---: |
| $\mathrm{Vo} \leq 6 \mathrm{Vpk}$ | 0.06 V † |
| $6 \mathrm{Vpk}<\mathrm{Vo} \leq 30 \mathrm{Vpk}$ | 0.3 V |



Fig. 7.11.1 \% Duty Cycle Function Generalized Output Waveshape Definition

NOTES: [1] Tcal $=$ temperature at calibration. Factory calibration temperature $=23^{\circ} \mathrm{C}$.

### 7.11 \% Duty Cycle Function Specifications (Contd.)

### 7.11.6 Repetition Period Interval Spans vs Time Resolution

| Absolute <br> Resolution | S6Vpk |  | >6Vpk |  |
| :--- | :--- | :--- | :--- | :--- |
| 100 ns | $100.0 \mu \mathrm{~s}$ | to $999.9 \mu \mathrm{~s}$ |  | ---- |
| 100 ns | 00.1000 ms | to 99.9999 ms | 01.0000 ms | to 99.9999 ms |
| $1 \mu \mathrm{~s}$ | 000.001 ms | to 999.999 ms | 001.000 ms | to 999.999 ms |
| $10 \mu \mathrm{~s}$ | 0000.01 ms | to 2000.00 ms | 0001.00 ms | to 2000.00 ms |

7.11.7 Rise Times (Specified into loads $R_{L}>100 \mathrm{k} \Omega$ in parallel with $C_{L} \leq 100 \mathrm{pF}$ )

```
For signals }\leq6\textrm{Vpk}:\quad<40\textrm{ns}
For signals > 6Vpk: <1.5\mus.
```


### 7.12 Auxiliary Functions - Specifications

The Functions listed below are described as 'Auxiliary Functions' because they do not have their own individual front panel hard keys, but instead are accessed via the front-panel 'Aux' hard key, by screen selection from the 'Auxiliary Functions' menu.

Their specifications appear in the following sub-sections:
7.13 ........ Capacitance Function Specifications
7.14 ........ Thermocouple Temperature Function Specifications
7.15 ........ RTD Temperature Function Specifications
7.16 ........ Logic Pulses Function Specifications
7.17 ....... Logic Levels Function Specifications

### 7.13 Capacitance Specifications

### 7.13.1 Capacitance Accuracy

| Capacitance Output | Accuracy * |  |  |  | Absolute Resolution |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Source UUTi Low <br> $\pm$ (\% of Output + Floor) 1 Year - Tcal $\pm 5^{\circ} \mathrm{C}{ }^{[1]}$ |  | Source UUTi Super <br> $\pm$ (\% of Output + Floor) 1Year - Tcal $\pm 5^{\circ} \mathrm{C}{ }^{[1]}$ |  |  |
| 0.5000 nF to 4.0000 nF 4.0001 nF to 40.000 nF 40.001 nF to 400.00 nF 400.01 nF to $4.0000 \mu \mathrm{~F}$ $4.0001 \mu \mathrm{~F}$ to $40.000 \mu \mathrm{~F}$ $40.001 \mu \mathrm{~F}$ to $400.00 \mu \mathrm{~F}$ $400.01 \mu \mathrm{~F}$ to 4.0000 mF 4.0001 mF to 40.000 mF | $\begin{aligned} & 0.3+15 \mathrm{pF} \\ & 0.3+30 \mathrm{pF} \\ & 0.3+160 \mathrm{pF} \\ & 0.4+1.6 \mathrm{nF} \\ & 0.5+16.0 \mathrm{nF} \\ & 0.5+160 \mathrm{nF} \\ & 0.5+1.6 \mu \mathrm{~F} \\ & 1.0+60 \mu \mathrm{~F} \end{aligned}$ | $\begin{aligned} & 0.6+30.0 \mathrm{pF} \\ & 0.6+60.0 \mathrm{pF} \\ & 0.6+320 \mathrm{pF} \\ & 0.8+3.2 \mathrm{nF} \\ & 1.0+32.0 \mathrm{nF} \\ & 1.0+320 \mathrm{nF} \\ & 1.0+3.2 \mu \mathrm{~F} \\ & 2.0+120 \mu \mathrm{~F} \end{aligned}$ | $\begin{gathered} \text {-------- } \\ ------- \\ \text {----- } \\ 0.75+160 \mathrm{nF} \\ 0.75+1.6 \mu \mathrm{~F} \\ 1.0+60 \mu \mathrm{~F} \end{gathered}$ | $\begin{gathered} \text {-------- } \\ ----- \\ ------ \\ 1.0+320 \mathrm{nF} \\ 1.0+3.2 \mu \mathrm{~F} \\ 2.0+120 \mu \mathrm{~F} \end{gathered}$ | $\begin{gathered} 0.1 \mathrm{pF} \\ 1 \mathrm{pF} \\ 10 \mathrm{pF} \\ 100 \mathrm{pF} \\ 1 \mathrm{nF} \\ 10 \mathrm{nF} \\ 100 \mathrm{nF} \\ 1 \mu \mathrm{~F} \end{gathered}$ |

$=$ Accuracy specifications apply both at the 9100 output terminals, and at the output leads of the Model 9105 leadset.
7.13.2 Measurement and Discharge Current

| Capacitance Output | Source UUTi Low <br> Measurement <br> Current Range |  | Maximum <br> Discharge Current | Source UUTi Super <br> Measurement <br> Marrent Range |
| :---: | :---: | :---: | :---: | :---: |
| Cuscharge Current |  |  |  |  |

### 7.13.3 Other Capacitance Specifications

| Maximum Measurement Voltage: | $\pm 3.5 \mathrm{~V}$ (except $40 \mu \mathrm{~F}$ range which is limited to $\pm 2.5 \mathrm{~V}$ ). |
| :--- | :--- |
| Settling Time: | to within $10 \%$ of accuracy: <0.08s |
| 4-wire Lead Compensation: | Max total lead resistance: $10 \Omega$ |

NOTES: [1] Tcal $=$ temperature at calibration. Factory calibration temperature $=23^{\circ} \mathrm{C}$

### 7.14 Thermocouple Temperature Specifications

7.14.1 Temperature Accuracy (Temperature scales selectable between IPTS-68 and ITS-90)

| Thermo Couple Type | Temperature Output (Screen Resolution Shown) | $\begin{gathered} \text { Accuracy }{ }^{*} \dagger \ddagger \\ \left( \pm^{\circ} \mathrm{C}\right) \\ \text { 1 Year }- \text { Tcal } \pm 5^{\circ} \mathrm{C} \end{gathered}$ |
| :---: | :---: | :---: |
| B | $+0500.0^{\circ} \mathrm{C}-+0800.0^{\circ} \mathrm{C}$ | 0.55 |
|  | $+0800.0{ }^{\circ} \mathrm{C}-+1000.0^{\circ} \mathrm{C}$ | 0.41 |
|  | $+1000.0^{\circ} \mathrm{C}-+1400.0^{\circ} \mathrm{C}$ | 0.34 |
|  | $+1400.0^{\circ} \mathrm{C}-+1820.0^{\circ} \mathrm{C}$ | 0.37 |
| c | $0000.0^{\circ} \mathrm{C}-+0600.0^{\circ} \mathrm{C}$ | 0.29 |
|  | $+0600.0^{\circ} \mathrm{C}-+1000.0^{\circ} \mathrm{C}$ | 0.27 |
|  | $+1000.0^{\circ} \mathrm{C}-+1800.0^{\circ} \mathrm{C}$ | 0.40 |
|  | $+1800.0^{\circ} \mathrm{C}-+2320.0^{\circ} \mathrm{C}$ | 0.41 |
| E | $-0250.0^{\circ} \mathrm{C}--0200.0^{\circ} \mathrm{C}$ | 0.45 |
|  | $-0200.0^{\circ} \mathrm{C}-{ }^{-0100.0}{ }^{\circ} \mathrm{C}$ | 0.22 |
|  | $-0100.0{ }^{\circ} \mathrm{C}-+0100.0^{\circ} \mathrm{C}$ | 0.17 |
|  | $+0100.0^{\circ} \mathrm{C}-+1000.0^{\circ} \mathrm{C}$ | 0.21 |
| J | $-0210.0{ }^{\circ} \mathrm{C}-0100.0{ }^{\circ} \mathrm{C}$ | 0.25 |
|  | $-0100.0^{\circ} \mathrm{C}-+0800.0^{\circ} \mathrm{C}$ | 0.19 |
|  | $+0800.0^{\circ} \mathrm{C}-+1000.0^{\circ} \mathrm{C}$ | 0.21 |
|  | $+1000.0^{\circ} \mathrm{C}-+1200.0^{\circ} \mathrm{C}$ | 0.23 |
| K | $-0250.0^{\circ} \mathrm{C}--0200.0^{\circ} \mathrm{C}$ | 0.57 |
|  | $-0200.0^{\circ} \mathrm{C}--0100.0{ }^{\circ} \mathrm{C}$ | 0.27 |
|  | $-0100.0^{\circ} \mathrm{C}-+0100.0^{\circ} \mathrm{C}$ | 0.19 |
|  | $+0100.0^{\circ} \mathrm{C}-+0600.0^{\circ} \mathrm{C}$ | 0.23 |
|  | $+0600.0^{\circ} \mathrm{C}-+1372.0^{\circ} \mathrm{C}$ | 0.27 |
| L | $-0200.0^{\circ} \mathrm{C}--0050.0{ }^{\circ} \mathrm{C}$ | 0.26 |
|  | $-0050.0{ }^{\circ} \mathrm{C}-+0200.0^{\circ} \mathrm{C}$ | 0.18 |
|  | $+0200.0^{\circ} \mathrm{C}-+0700.0^{\circ} \mathrm{C}$ | 0.20 |
|  | $+0700.0^{\circ} \mathrm{C}-+0900.0^{\circ} \mathrm{C}$ | 0.23 |
| N | $-0200.0^{\circ} \mathrm{C}-{ }^{-0100.0}{ }^{\circ} \mathrm{C}$ | 0.33 |
|  | $-0100.0^{\circ} \mathrm{C}-+0900.0^{\circ} \mathrm{C}$ | 0.23 |
|  | $+0900.0^{\circ} \mathrm{C}-+1100.0^{\circ} \mathrm{C}$ | 0.22 |
|  | $+1100.0^{\circ} \mathrm{C}-+1300.0^{\circ} \mathrm{C}$ | 0.24 |
| R. | $0000.0{ }^{\circ} \mathrm{C}-+0100.0{ }^{\circ} \mathrm{C}$ | 0.52 |
|  | $+0100.0^{\circ} \mathrm{C}-+0200.0^{\circ} \mathrm{C}$ | 0.40 |
|  | $+0200.0^{\circ} \mathrm{C}-+1600.0^{\circ} \mathrm{C}$ | 0.35 |
|  | $+1600.0^{\circ} \mathrm{C}-+1767.0^{\circ} \mathrm{C}$ | 0.28 |
| s. | $0000.0{ }^{\circ} \mathrm{C}-+0200.0^{\circ} \mathrm{C}$ | 0.49 |
|  | $+0200.0^{\circ} \mathrm{C}-+1000.0^{\circ} \mathrm{C}$ | 0.37 |
|  | $+1000.0^{\circ} \mathrm{C}-+1400.0^{\circ} \mathrm{C}$ | 0.35 |
|  | $+1400.0^{\circ} \mathrm{C}-+1767.0^{\circ} \mathrm{C}$ | 0.36 |
| T | ${ }^{-0250.0}{ }^{\circ} \mathrm{C}-0200.0^{\circ} \mathrm{C}$ | 0.59 |
|  | ${ }^{-0200.00}{ }^{\circ} \mathrm{C}-0100.00^{\circ} \mathrm{C}$ | 0.27 |
|  | $-0100.0^{\circ} \mathrm{C}-0000.0^{\circ} \mathrm{C}$ | 0.22 |
|  | $0000.0^{\circ} \mathrm{C}-+0400.0^{\circ} \mathrm{C}$ | 0.17 |

NOTE: To calculate the Model 9100's accuracy in ${ }^{\circ} \mathrm{F}$ (Fahrenheit) or K (Kelvin) proceed as folows:-

1. Convert the temperature in ${ }^{\circ} \mathrm{F}$ or K to ${ }^{\circ} \mathrm{C}$ using one of the following formulae as appropriate:

$$
\begin{aligned}
&{ }^{\circ} \mathrm{C}=\mathrm{K}-273 \\
&{ }^{\circ} \mathrm{C}=\frac{\left({ }^{\circ} \mathrm{F}-32\right) \times 5}{9}
\end{aligned}
$$

2. Read the Model 9100 's accuracy $\left( \pm \Delta_{\circ}\right.$ c) at this ${ }^{\circ} \mathrm{C}$ temperature from the accuracy table.
3. Convert $\Delta^{\circ} \mathrm{C}$ back to $\Delta^{\circ} \mathrm{F}$ or $\Delta_{K}$ using one of the following formulae as appropriate:

$$
\begin{aligned}
& \Delta K=\Delta^{\circ} \mathrm{C} \\
& \Delta^{\circ} \mathrm{F}=\frac{\Delta^{\circ} \mathrm{C} \times 9}{5}
\end{aligned}
$$

## Example:

To calculate accuracy in ${ }^{\circ} \mathrm{F}\left(\Delta^{\circ} \mathrm{F}\right)$ of K -Type output at $1994^{\circ} \mathrm{F}$

1. ${ }^{\circ} \mathrm{C}=\frac{(1994-32) \times 5}{9}=1090{ }^{\circ} \mathrm{C}$
2. $\Delta{ }^{\circ} \mathrm{C}$ at $1090^{\circ} \mathrm{C}= \pm 0.27^{\circ} \mathrm{C}$
3. $\Delta^{\circ} \mathrm{F}=\frac{0.27 \times 9}{5}= \pm 0.486^{\circ} \mathrm{F}$

### 7.14.2 Other Thermocouple Output Specifications

| Settling Time: | to within $10 \%$ of accuracy: 0.08 s |
| :--- | :--- | :--- |
| Load Regulation: <br> Maximum <br> Capacitance: | $\left.1000 / R_{\text {LOAD }}\right) \%$ of output |$\quad$.

* = Accuracy figures include CJC error.
t $=$ Accuracy figures include Compensated output determined from pre-defined tables based on
$\dagger=\begin{aligned} & \text { Compensated output determined from pre-defined tables based on: } \\ & \quad \text { PTS-68 Reference Table NIST Monograph } 125 \text { for Types: B, E, J, K, R, S and T. }\end{aligned}$ ITS-90 Reference Table NIST Monograph 175 for Types: B, E, J, K, N, R, S and T. IPTS-68 Reference Table DIN 43710 for Type L.
ITS-90 Reference Table DIN 43710 for Type
= For loads $<1 \mathrm{M} \Omega$ add load regulation error
- Types R \& S adjusted above $1700^{\circ} \mathrm{C}$ for IPTS-68 as per NIST monograph 175.

NOTES: [1] Tcal $=$ temperature at calibration. Factory calibration temperature $=23^{\circ} \mathrm{C}$

### 7.15 RTD Temperature Specifications

7.15.1 RTD Temperature Accuracy *

To calculate accuracy in units of ${ }^{\circ} \mathrm{F}$ (Fahrenheit) and K (Kelvin), see the note in sub-sect. 7.14 (Thermocouple Specifications).

| Temperature Output | $\begin{gathered} \text { Accuracy }{ }^{*}: \pm(\% \text { of Output }+ \text { Floor }) \\ \text { 1Year - Tcal } \pm 5^{\circ} \mathrm{C}[1] \end{gathered}$ |  |  |
| :---: | :---: | :---: | :---: |
|  | $\begin{gathered} \text { Resistance at } 0^{\circ} \mathrm{C}= \\ 10 \Omega-60 \Omega \end{gathered}$ | $\begin{gathered} \text { Resistance at } 0^{\circ} \mathrm{C}= \\ 60 \Omega-1 \mathrm{k} \Omega \end{gathered}$ | $\begin{gathered} \text { Resistance at } 0^{\circ} \mathrm{C}= \\ 1 \mathrm{k} \Omega-2 \mathrm{k} \Omega \end{gathered}$ |
| $-200^{\circ} \mathrm{C}$ to $-100^{\circ} \mathrm{C}$ | $0.00+0.225^{\circ} \mathrm{C}$ | $0.00+0.15^{\circ} \mathrm{C}$ | $0.00+0.12^{\circ} \mathrm{C}$ |
| $-100^{\circ} \mathrm{C}$ to $+100^{\circ} \mathrm{C}$ | $0.00+0.15^{\circ} \mathrm{C}$ | $0.00+0.10^{\circ} \mathrm{C}$ | $0.00+0.08^{\circ} \mathrm{C}$ |
| $+100^{\circ} \mathrm{C}$ to $+630^{\circ} \mathrm{C}$ | $0.00+0.30^{\circ} \mathrm{C}$ | $0.00+0.20^{\circ} \mathrm{C}$ | $0.00+0.16^{\circ} \mathrm{C}$ |
| $+630^{\circ} \mathrm{C}$ to $+850^{\circ} \mathrm{C}$ | $0.00+0.45^{\circ} \mathrm{C}$ | $0.00+0.30^{\circ} \mathrm{C}$ | $0.00+0.24^{\circ} \mathrm{C}$ |

= Accuracy figures apply to Output Temperature vs Resistance curves PT385 or PT392
and to Temperature Scales IPTS-68 or ITS-90 as selected by the user:
PT385, IPTS-68 as per IEC751.
PT385, ITS-90 as per IEC751 amendment 2.
PT392, ITS-90 as per NIST monograph 175 corrections (90-68).
7.15.2 Spans of UUT Source Currents

| Hardware Configuration Limits <br> on Span of Output Resistance |  | UUTi Low | UUTi High | UUTi Super |
| :--- | :--- | :---: | :---: | :---: |
| $00.0000 \Omega \quad$ to $40.0000 \Omega$ | $250 \mu \mathrm{~A}$ to 3.5 mA | 2.5 mA to 35 mA | 25 mA to 350 mA |  |
| $040.001 \Omega$ | to $400.000 \Omega$ | $25 \mu \mathrm{~A}$ to $320 \mu \mathrm{~A}$ | $250 \mu \mathrm{~A}$ to 3.5 mA | 2.5 mA to 35 mA |
| $0.40001 \mathrm{k} \Omega$ | to $4.00000 \mathrm{k} \Omega$ | $25 \mu \mathrm{~A}$ to $320 \mu \mathrm{~A}$ | $250 \mu \mathrm{~A}$ to 3.5 mA | 2.5 mA to 35 mA |
| $04.0001 \mathrm{k} \Omega$ | to $10.0000 \mathrm{k} \Omega \dagger$ | $2.5 \mu \mathrm{~A}$ to $32 \mu \mathrm{~A}$ | $25 \mu \mathrm{~A}$ to $350 \mu \mathrm{~A}$ | $250 \mu \mathrm{~A}$ to 3.5 mA |

$\dagger$ = Resistance span used when the nominal operating point of the detector is raised, to give resistance values above $4 \mathrm{k} \Omega$ for certain temperature readings.

### 7.15.3 Other RTD Temperature Specifications

| Maximum Measurement Voltage: | $10 \mathrm{~V} ; \quad \mathrm{I}_{\text {measure }} \times \mathrm{R}_{\text {actual }}: \leq 10 \mathrm{~V}$ |
| :--- | :--- |
| Settling Time: | to within $10 \%$ of accuracy: <0.08s |
| 4-wire Lead Compensation: | Max total lead resistance : $50 \Omega$ <br> Nominal lead resistance rejection: $10000: 1$ |

NOTES: [1] Tcal $=$ temperature at calibration. Factory calibration temperature $=23^{\circ} \mathrm{C}$.

### 7.16 Logic-Pulses Function Specifications

### 7.16.1 Pulse Width and Repetition Period Intervals Accuracy

| Interval | Accuracy <br> $\pm($ ppm of Output + Floor $)$ <br> 1Year - Tcal $\pm 5^{\circ} \mathrm{C}$ | Option 100 Accuracy <br> $\pm(\mathrm{ppm}$ of Output + Floor $)$ <br> 5 Year - Tcal $\pm 5^{\circ} \mathrm{C}$ |
| :--- | :---: | :---: |
| Pulse Width: | $0.30 \mu$ s to 1999.99 ms | $25+10.0 \mathrm{~ns}$ |
| Repetition Period: $\quad 0.6 \mu$ s to 2000.00 ms | 25 | $0.25+10.0 \mathrm{~ns}$ |

7.16.2 Fixed High/Low Levels \& Voltage - Accuracy

| Selected <br> Logic | Signal <br> Level | Voltage | Accuracy <br> ( $\pm$ Volts) <br> 1Year - Tcal $\pm 5^{\circ} \mathrm{C}{ }^{[1]}$ |
| :---: | :---: | :---: | :---: |
| TTL | High | +5.00 V | 0.06 |
| CMOS | Low | 0.00 V | 0.06 |
|  | High | +5.00 V | 0.06 |
| ECL | Low | 0.00 V | 0.06 |
|  | High | -0.90 V | 0.06 |
|  | Low | -1.75 V | 0.06 |



Fig. 4.16.1 Logic-Pulses Function Generalized Output Waveshape Definition
7.16.3 'Pulse Width' Interval vs Resolution

| Absolute <br> Resolution | Pulse Width |  |
| :--- | :--- | :--- |
| 100 ns | $000.3 \mu \mathrm{~s}$ | to $999.9 \mu \mathrm{~s}^{*}$ |
| 100 s | 00.0003 ms | to $99.9999 \mathrm{~ms}^{*}$ |
| $1 \mu \mathrm{~s}$ | 000.001 ms | to 999.999 ms |
| $10 \mu \mathrm{~s}$ | 0000.01 ms | to 1999.99 ms |

7.16.4 'Repetition Period' Interval vs Resolution

| Absolute <br> Resolution | Repetition Period |  |
| :--- | :--- | :--- |
| 100 ns | $000.6 \mu \mathrm{~s}$ | to $999.9 \mu \mathrm{~s}$ |
| 100 ns | 00.0006 ms | to 99.9999 ms |
| $1 \mu \mathrm{~s}$ | 000.001 ms | to 999.999 ms |
| $10 \mu \mathrm{~s}$ | 0000.01 ms | to 2000.00 ms |

$0.3 \mu$ s less than that of the set Repetition Perio
$0.3 \mu$ less than that of the set Repetition Period

## 7．17 Logic－Levels Function Specifications

## 7．17．1 Logic－Levels Accuracy

The accuracy of each DC signal voltage is the same as that of the equivalent voltage in DC Voltage Function（Sub－section 7．3）．

7．17．2 Logic－Levels DC Signal Voltage Boundaries

| Logic Type | Signal Level | Screen Indication | Default Value <br> （＇H＇or＇L＇） | Boundaries | Adjustment Limits |
| :---: | :---: | :---: | :---: | :---: | :---: |
| TTL | High Intermediate Low | $\begin{gathered} \text { HIGH LVL } \\ \text {-ーーーー } \\ \text { LOW LVL } \end{gathered}$ | $\begin{gathered} +5.00 \mathrm{~V} \\ --- \\ 0.00 \mathrm{~V} \end{gathered}$ | $\begin{aligned} \mathrm{V} & \geqslant+2.00 \mathrm{~V} \\ +0.8 \mathrm{~V} & <\mathrm{V}<+2.00 \mathrm{~V} \\ \mathrm{~V} & \leqslant 0.8 \mathrm{~V} \end{aligned}$ | $\begin{gathered} +5.50 \mathrm{~V} \\ --- \\ 0.00 \mathrm{~V} \end{gathered}$ |
| CMOS | High Intermediate Low | $\begin{gathered} \text { HIGH LVL } \\ \text {-ーーーー } \\ \text { LOW LVL } \end{gathered}$ | $\begin{gathered} +5.00 \mathrm{~V} \\ --- \\ 0.00 \mathrm{~V} \end{gathered}$ | $\begin{aligned} \mathrm{V} & \geqslant+3.50 \mathrm{~V} \\ +1.5 \mathrm{~V} & <\mathrm{V}<+3.50 \mathrm{~V} \\ \mathrm{~V} & \leqslant 1.5 \mathrm{~V} \end{aligned}$ | $\begin{gathered} +6.00 \mathrm{~V} \\ --- \\ 0.00 \mathrm{~V} \end{gathered}$ |
| ECL | High Intermediate Low | $\begin{gathered} \text { HIGH LVL } \\ -ー-ー- \\ \text { LOW LVL } \end{gathered}$ | $\begin{gathered} -0.9 \mathrm{~V} \\ --- \\ -1.75 \mathrm{~V} \end{gathered}$ | $\begin{aligned} \mathrm{V} & \geqslant-1.11 \mathrm{~V} \\ -1.48 \mathrm{~V} & <\mathrm{V}<-1.11 \mathrm{~V} \\ \mathrm{~V} & \leqslant-1.48 \mathrm{~V} \end{aligned}$ | $\begin{gathered} 0.00 \mathrm{~V} \\ --- \\ -5.20 \mathrm{~V} \end{gathered}$ |

### 7.18 Insulation/Continuity Specifications

7.18.1 Insulation Resistance Accuracy and Resolution (Super I)

| Resistance Output | Accuracy <br> $\pm \%$ of Output <br> 1Year - Tcal $\pm 5^{\circ} \mathrm{C}[1]$ | Absolute <br> Resolution | Source Current <br> Limits |
| :---: | :---: | :---: | :---: |
| $100.0 \mathrm{k} \Omega$ to $299.9 \mathrm{k} \Omega$ | $0.1 \%$ | $100 \Omega$ | $200 \mu \mathrm{~A} \mathrm{to} 10 \mathrm{~mA}$ |
| $300.0 \mathrm{k} \Omega$ to $2.999 \mathrm{M} \Omega$ | $0.1 \%$ | $1 \mathrm{k} \Omega$ | $90 \mu \mathrm{~A}$ to 4 mA |
| $3.000 \mathrm{M} \Omega$ to $29.99 \mathrm{M} \Omega$ | $0.3 \%$ | $9 \mu \mathrm{k} \Omega$ | 900 nA to $40 \mu \mathrm{~A}$ |
| $30.00 \mathrm{M} \Omega$ to $299.9 \mathrm{M} \Omega$ | $0.5 \%$ | $100 \mathrm{k} \Omega$ | 90 nA to $4 \mu \mathrm{~A}$ |
| $300.0 \mathrm{M} \Omega$ to $2.000 \mathrm{G} \Omega$ | $0.7 \%$ | $1 \mathrm{M} \Omega$ |  |

7.18.2 Other Insulation Resistance Specifications

| Maximum Measurement Voltage: | $1350 \mathrm{VDC}: ~ I \times R<1350 \mathrm{~V}$ |  |
| :--- | :--- | :--- |
|  |  |  |
| Voltage Measurement: | Range: | 0 V to 1350 V |
|  | Accuracy: | $\pm(0.6 \%$ of Output $+1 \mathrm{~V})$ |
| Current Measurement: | Range: $1 \mu \mathrm{~A}$ to 2.3 mA <br>  Accuracy: <br>  $\pm 1.5 \%$ |  |

### 7.18 Insulation/Continuity Specifications (Contd.)

7.18.3 Continuity Resistance Accuracy and Resolution (4-wire connection)

| Resistance Output | Accuracy <br> $\pm(\%$ of Output + Floor) <br> 1Year - Tcal $\pm 5^{\circ} \mathrm{C}[1]$ | Absolute <br> Resolution |
| :---: | :---: | :---: |
| $00.0000 \Omega$ to $40.0000 \Omega$ | $0.1+50 \mathrm{~m} \Omega$ | $0.1 \mathrm{~m} \Omega$ |
| $040.001 \Omega$ to $400.000 \Omega$ | $0.035+100 \mathrm{~m} \Omega$ | $1 \mathrm{~m} \Omega$ |
| $0.40001 \mathrm{k} \Omega$ to $4.00000 \mathrm{k} \Omega$ | $0.035+200 \mathrm{~m} \Omega$ | $10 \mathrm{~m} \Omega$ |

7.18.4 Continuity Resistance Source Current - Limits

| Hardware Configuration Limits <br> on Span of Output Resistance | Source Current Limits |
| :---: | :---: |
| $00.0000 \Omega$ to $40.0000 \Omega$ | 25 mA to 350 mA |
| $040.001 \Omega$ to $400.000 \Omega$ | 5 mA to 70 mA |
| $0.40001 \mathrm{k} \Omega$ to $4.00000 \mathrm{k} \Omega$ | $500 \mu \mathrm{~A}$ to 7 mA |

7.18.5 Other Continuity Resistance Specifications

| Maximum Measurement Voltage: | 10 V |  |
| :--- | :--- | :--- |
| Current Measurement: | Range: <br> Accuracy: | $100 \mu \mathrm{~A}$ to 350 mA <br> $\pm 1 \%$ |

### 7.19 Power Specifications

The following specifications refer to the Voltage and Current outputs available from the Auxiliary channel - i.e. the I+ and I- outputs of the Model 9100 when the Power function is active. They should not be confused with the normal Voltage and Current output specifications.

Where no parameter or caveat is stated, the specification is as 9100 .

### 7.19.1 Auxiliary DC Voltage Accuracy

| Output Voltage <br> +ve or -ve | Accuracy <br> $\pm(\%$ Output + Floor) $)$ | Compliance Current <br> $\mathrm{mA}(\mathrm{O} /$ P Impedance) |
| :---: | :---: | :---: |
| 00.00 mV to 32.00 mV | $0.012 \%+3 \mu \mathrm{~V}$ | $10 \Omega$ |
| 32.00 mV to 320.0 mV | $0.006 \%+5 \mu \mathrm{~V}$ | $<20 \mathrm{~mA}$ |
| 0.320 V to 3.200 V | $0.006 \%+41.6 \mu \mathrm{~V}$ | $<20 \mathrm{~mA}$ |
| 3.200 V to 7.500 V | $0.030 \%+90 \mu \mathrm{~V}$ | $<20 \mathrm{~mA}$ |

### 7.19.2 Auxiliary DC Voltage (Representing DC Current Output) Accuracy

| Output Current | Accuracy <br> $\pm(\%$ Output + Floor) | Compliance Current <br> mA |
| :---: | :---: | :---: |
| 0.00 to $32.00 \mathrm{~A} @ \geq 1 \mathrm{mV} / \mathrm{Amp}$ | $0.012 \%+0.003 \mathrm{~A}$ | $10 \Omega$ |
| 32.0 to $320.0 \mathrm{~A} @ \geq 1 \mathrm{mV} / \mathrm{Amp}$ | $0.006 \%+0.005 \mathrm{~A}$ | $<20 \mathrm{~mA}$ |
| 320.0 A to $3.2 \mathrm{kA} @ \geq 1 \mathrm{mV} / \mathrm{Amp}$ | $0.006 \%+0.042 \mathrm{~A}$ | $<20 \mathrm{~mA}$ |
| 0 to $160 \mathrm{~A} @ 0.2 \mathrm{mV}$ to $1 \mathrm{mV} / \mathrm{Amp}$ | $0.006 \%+0.021 \mathrm{~A}$ | $<20 \mathrm{~mA}$ |
| 160.1 A to $3.2 \mathrm{kA} @ 0.2 \mathrm{mV}$ to $1 \mathrm{mV} / \mathrm{Amp}$ | $0.006 \%+0.21 \mathrm{~A}$ | $<20 \mathrm{~mA}$ |
| $>3.2 \mathrm{kA}$ | $0.03 \%+0.42 \mathrm{~A}$ | $<20 \mathrm{~mA}$ |

NOTES: Improved specs are available at intermediate points depending on scaling factor
Auxiliary DC Voltage is primarily a simulation of the output of a resistive shunt, and for Power is therefore expressed as being equivalent to Amps.
7.19.3 Auxiliary AC Voltage Accuracy (Sinusoidal Waveshape)

| Output Voltage | Frequency <br> Band | Accuracy <br> $\pm$ (\% Output + Floor) | Compliance Current <br> mA (O/P Impedance) |
| :---: | :---: | :---: | :---: |
| 0.32 mV to 3.20 mV | $10-3 \mathrm{~K}$ | $0.12 \%+10 \mu \mathrm{~V}$ | $10 \Omega$ |
| 3.21 to 32.00 mV | $10-3 \mathrm{~K}$ | $0.12 \%+10 \mu \mathrm{~V}$ | $10 \Omega$ |
| 32.0 mV to 320.0 mV | $10-3 \mathrm{~K}$ | $0.04 \%+19.2 \mu \mathrm{~V}$ | $<20 \mathrm{~mA}$ |
| 0.320 V to 3.200 V | $10-3 \mathrm{~K}$ | $0.04 \%+192 \mu \mathrm{~V}$ | $<20 \mathrm{~mA}$ |
| 3.200 V to 7.500 V | $10-3 \mathrm{~K}$ | $0.06 \%+400 \mu \mathrm{~V}$ | $<7 \mathrm{~mA} @ 7 \mathrm{~V}$ |

NOTES: Also directly available as a voltage harmonic output. When used as a harmonic with $n>1$, add $0.04 \%$ to percentage of output specifications The lowest AC range functions down to zero, but the floor spec is doubled below 0.32 mV .
7.19.4 Auxiliary AC Voltage (Representing AC Current Output) Accuracy

| Output Current | Frequency <br> Band | Accuracy <br> $\pm(\%$ Output + Floor) | Compliance Current <br> $\mathrm{mA}(O / \mathrm{P}$ Impedance) |
| :---: | :---: | :---: | :---: |
| 0.32 A to 3.20 A | $10-3 \mathrm{~K}$ | $0.12 \%+0.01 \mathrm{~A}$ | $10 \Omega$ |
| 3.21 A to 32.0 A | $10-3 \mathrm{~K}$ | $0.12 \%+0.01 \mathrm{~A}$ | $10 \Omega$ |
| 32.1 to $320.0 \mathrm{~A} @ \geq 1 \mathrm{mV} / \mathrm{Amp}$ | $10-3 \mathrm{~K}$ | $0.04 \%+0.02 \mathrm{~A}$ | $<20 \mathrm{~mA}$ |
| 32 A to $3.2 \mathrm{KA} @ \geq 1 \mathrm{mV} / \mathrm{Amp}$ | $10-3 \mathrm{~K}$ | $0.04 \%+0.2 \mathrm{~A}$ | $<20 \mathrm{~mA}$ |
| 0 to $160.0 \mathrm{~A} @ 0.2 \mathrm{mV}$ to $1 \mathrm{mV} / \mathrm{Amp}$ | $10-3 \mathrm{~K}$ | $0.04 \%+0.1 \mathrm{~A}$ | $<20 \mathrm{~mA}$ |
| 160 A to $3.2 \mathrm{kA} @ 0.2 \mathrm{mV}$ to $1 \mathrm{mV} / \mathrm{Amp}$ | $10-3 \mathrm{~K}$ | $0.04 \%+1 \mathrm{~A}$ | $<20 \mathrm{~mA}$ |
| $>3.2 \mathrm{kA}$ | $10-3 \mathrm{~K}$ | $0.06 \%+2 \mathrm{~A}$ | $<7 \mathrm{~mA} @ 7 \mathrm{~V}$ |

NOTES: Improved specs are available at intermediate points depending on scaling factor.
Auxiliary AC voltage is available as a simulation of the output of a resistive shunt, and can therefore be expressed as being equivalent to Amps. Also directly available as a voltage harmonic output. When used as a harmonic with $n>1$, add $0.04 \%$ to percentage of output specifications.

### 7.19.5 Other Voltage Waveshapes

All subject to $65 \mathrm{~Hz} / 1 \mathrm{kHz}$ maximum as defined in main Model 9100 specification tables.
Note that all waveshapes are specified to 4.525 pk only ( 4 ranges; equivalent to the 3.2 V sinewave range peak)
Functionality above this limit is available but unspecified.
The 4.525 mV pk range is allowed to function down to zero.
Specifications as main 9100 ranges.

### 7.19.6 DC Current Accuracy

| Output Current | Accuracy <br> $\pm(\%$ Output + Floor $)$ |
| :---: | :---: |
| 0 to 320.0 mA | $0.016+9.6 \mu \mathrm{~A}$ |
| 0.320 A to 3.200 A | $0.06+118 \mu \mathrm{~A}$ |
| 3.20 A to 10.50 A | $0.055+940 \mu \mathrm{~A}$ |
| 10.50 A to 20.00 A | $0.055+4.5 \mathrm{~mA}$ |
| 3.200 to $32.00 \mathrm{~A}, 10 \mathrm{t}$ coil | $0.26+1.18 \mathrm{~mA}$ |
| 32.00 to $200.0 \mathrm{~A}, 10 \mathrm{t}$ coil | $0.255+45 \mathrm{~mA}$ |
| 16.00 to $160.0 \mathrm{~A}, 50 \mathrm{t}$ coil | $0.26+5.9 \mathrm{~mA}$ |
| 160.0 to $1000 \mathrm{~A}, 50 \mathrm{t}$ coil | $0.255+225 \mathrm{~mA}$ |

7.19.7 AC Current Accuracy (sine)

| Output Current | Frequency <br> Band | Accuracy <br> $\pm(\%$ Output + Floor $)$ |
| :---: | :---: | :---: |
| 0 to 320.0 mA | $10-1 \mathrm{k}$ | $0.08+32 \mu \mathrm{~A}$ |
| 0.320 to 3.200 A | $10-1 \mathrm{k}$ | $0.08+480 \mu \mathrm{~A}$ |
| 3.200 to 10.500 A | $10-100$ | $0.11+3 \mathrm{~mA}$ |
| 10.50 to 20.00 A | $100-1 \mathrm{k}$ | $0.15+3 \mathrm{~mA}$ |
|  | $10-100$ | $0.11+6.9 \mathrm{~mA}$ |
| 3.20 to $32.00 \mathrm{~A}, 10 \mathrm{t}$ coil | $100-1 \mathrm{k}$ | $0.15+6.9 \mathrm{~mA}$ |
|  | $10-100$ | $0.40+9.7 \mathrm{~mA}$ |
| 32.0 to $200.0 \mathrm{~A}, 10 \mathrm{t}$ coil | $100-440$ | $0.98+27 \mathrm{~mA}$ |
| 16.0 to $160.0 \mathrm{~A}, 50 \mathrm{t}$ coil | $100-440$ | $0.40+90 \mathrm{~mA}$ |
| 160.1 to $1000 \mathrm{~A}, 50 \mathrm{t}$ coil | $10-100$ | $0.87+250 \mathrm{~mA}$ |
| $10-100$ | $0.42+48 \mathrm{~mA}$ |  |

Note that above specs are subject to maximums as specified in the Amp.Hz profile.
Performance above 1 kHz not specified to user; nominally Gain is as 9100 and Floors as above.
All other specifications as 9100 except that the $0.2 \%$ adder for the Option 200 coils has been included in the table above.
Also directly available as a voltage harmonic output. When used as a harmonic with $n>1$, add $0.04 \%$ to percentage of output specifications.

### 7.19.8 Other Current Waveshapes

All subject to maximum frequencies as per the main 9100 specification tables.
Ranges available start at the 45.25 mA to 452.5 mA pk range.
This is allowed to function down to zero.
Performance as in main 9100 specifications.

### 7.19.9 Phase Accuracy (Sinusoidal Waveshape)

| Voltage Output | Frequency <br> Band (Hz) | Output Phase <br> Uncertainty (degrees) |
| :---: | :---: | :---: |
| 0.30000 V to 105.000 V | $10-65$ | $0.07^{\circ}$ |
| 105.001 V to $750.000 \mathrm{~V}{ }^{[1]}$ |  <br> $65-1 \mathrm{k}$ <br> $45-65$ <br> $65-1 \mathrm{k}$ | $0.07+0.001 \times(\mathrm{f}-65)^{\circ}$ |
|  | $0.16+0.0037 \times(\mathrm{f}-65)^{\circ}$ |  |


| Current Output | Frequency Band (Hz) | $\begin{array}{\|c\|} \text { Output Phase } \\ \text { Uncertainty (degrees) } \end{array}$ |
| :---: | :---: | :---: |
| 0.00000A to 20.0000 A | 10-65 | $0.08{ }^{\circ}$ |
|  | 65-1k | $0.08+0.0008 \times(\mathrm{f}-65)^{\circ}$ |
|  |  | 0.23 |
| 03.2000A to $1000.00 \mathrm{~A}{ }^{[3]}$ | $\begin{aligned} & 10-65 \\ & 65-444 \end{aligned}$ | $\begin{gathered} 0.23^{\circ} \\ 0.23+0.003 \times(f-65)^{\circ} \end{gathered}$ |


| Auxiliary Channel Voltage Output | Frequency <br> Band (Hz) | Output Phase <br> Uncertainty (degrees) |
| :---: | :---: | :---: |
| 0.32 mV to 7.500 A | $10-65$ <br> $65-1 \mathrm{k}$ <br> $>1 \mathrm{k}$ | $0.077^{\circ}$ <br> $0.0 .001 \times(\mathrm{f}-65)^{\circ}$ |

NOTES: [1] Maximum load current: 2mA. Maximum load capacitance: 200pF
[2] To obtain the Output Phase Uncertainty with respect to PHASE LOCK OUT or PHASE LOCK IN when operating in POWER mode, add $0.07^{\circ}$
[3] With the 10 -turn or 50 -turn coil output selected (Option 200).

### 7.19.10 Calculating Power Uncertainty

The Power Uncertainty is based on the root sum square (rss) of the following three uncertainties (expressed in \%):

1. Voltage (Main) Channel Amplitude Uncertainty
2. Current (Auxiliary) Channel Amplitude Uncertainty
3. Amplitude Uncertainty due to Phase Error

$$
\text { Power Uncertainty }=\sqrt{\mathrm{U}_{\text {Voltage }}^{2}+\mathrm{U}_{\text {Current }}^{2}+\mathrm{U}_{\text {Phase }}^{2}}
$$

The following examples demonstrate how to calculate the power uncertainty at a specific calibration point.
(Note: All specifications used are 1 year specifications).

## Example 1:

Calibrator Output 100V, 3A (at 60 Hz ) Power Factor $1.0\left(\emptyset=0^{\circ}\right)$.

1. Voltage Amplitude Uncertainty (From Section 7.4.1)
2. Current Amplitude Uncertainty (From Section 7.19.7)

3A Specification: $\quad$|  | $=0.08 \%$ Rdg | $+\quad 480 \mu \mathrm{~A}($ Floor $)$ |  |
| ---: | :--- | :--- | :--- |
|  | $=0.08 \%$ | + | $(480 \mu \mathrm{~A} / 3 \mathrm{~A}) \times 100$ |
|  | $=0.08 \%$ | + | $0.016 \%$ |
|  | $=0.096 \%$ |  |  |

3. Amplitude Uncertainty due to Phase Error (From Section 7.19.9)

| Specifications: | Voltage Channel Phase Uncertainty | $0.07^{\circ}$ |
| :--- | :--- | :--- |
|  | Current Channel Phase Uncertainty | $0.08^{\circ}$ |

Combined Phase Uncertainty

| $\emptyset_{\text {ERROR }}$ | $=0.07^{\circ}+0.08^{\circ}$ |
| :--- | :--- |
|  | $=0.15^{\circ}$ |

The equation yielding the actual amplitude uses the term $\operatorname{Cos}\left(\varnothing+\emptyset_{\text {ERROR }}\right)$. The equation yielding the error free amplitude uses the term $\operatorname{Cos}(\varnothing)$. These have to be combined to yield a percentage error.


The Total Power Uncertainty is therefore the rss of the individual contributions :

$$
\begin{aligned}
& =\sqrt{(0.0463)^{2}+(0.096)^{2}+(0.0003427)^{2}} \\
& =0.107 \%
\end{aligned}
$$

## Example 2:

Calibrator Output $100 \mathrm{~V}, 3 \mathrm{~A}$ (at 400 Hz ) Power Factor $0.5\left(\emptyset=60^{\circ}\right)$.

1. Voltage Amplitude Uncertainty (From Section 7.4.1)

| 100V Specification : | $=0.04 \% \mathrm{Rdg}+$ | 6.3 mV (Floor) |  |
| ---: | :--- | :--- | :--- |
|  | $=0.04 \%$ | + | $(6.3 \mathrm{mV} / 100 \mathrm{~V}) \times 100$ |
|  | $=0.04 \%$ | + | $0.0063 \%$ |
|  | $=0.0463 \%$ |  |  |

2. Current Amplitude Uncertainty (From Section 7.19.7)

| 3 A Specification: | $=0.08 \% \mathrm{Rdg}$ | + | $480 \mu \mathrm{~A}$ (Floor) |
| ---: | :--- | :--- | :--- |
|  | $=0.08 \%$ | + | $(480 \mu \mathrm{~A} / 3 \mathrm{~A}) \times 100$ |
|  | $=0.08 \%$ | + | $0.016 \%$ |
|  | $=0.096 \%$ |  |  |

3. Amplitude Uncertainty due to Phase Uncertainty (From Section 7.19.9)


Again, the equation yielding the actual amplitude uses the term $\operatorname{Cos}\left(\varnothing+\emptyset_{\text {ERROR }}\right)$. These have to be combined to yield a percentage error

$$
\begin{aligned}
\text { Amplitude uncertainty } & =100 \times\left[1-\frac{\operatorname{Cos}\left(\emptyset+\emptyset_{\mathrm{ERROR}}\right)}{\operatorname{Cos} \emptyset}\right] \\
& =100 \times\left[1-\frac{\operatorname{Cos}(60+0.753)}{\operatorname{Cos} 60}\right] \\
& =100 \times\left[1-\frac{0.488575}{0.5}\right]
\end{aligned}
$$

$=2.285 \%$

The Total Power Uncertainty is therefore the rss of the individual contributions :

$$
\begin{aligned}
& =\sqrt{(0.0463)^{2}+(0.096)^{2}+(2.285)^{2}} \\
& =2.287 \%
\end{aligned}
$$

It is clear that at lower power factors the contribution from the Phase Uncertainty dominates. This demonstrates why most calibrations are performed at Unity Power Factor ( $0^{\circ}$ phase difference between channels). The following table illustrates the amplitude uncertainties introduced due to a phase difference. The user can optimise the total power uncertainty by calibrating at higher power factors.

| Corresponding <br> Power Factor | Channel Phase <br> Difference | Amplitude Uncertainty due <br> to Phase |  |
| :---: | :---: | :---: | :---: |
|  |  | Voltage <105V <br> Current <20A | Voltage >105V <br> Current <20A |
| 1 | $0^{\circ}$ | $0.0003 \%$ | $0.0009 \%$ |
| 0.95 | $18.19^{\circ}$ | $0.0864 \%$ | $0.1385 \%$ |
| 0.90 | $25.84^{\circ}$ | $0.1271 \%$ | $0.2037 \%$ |
| 0.86 | $30.00^{\circ}$ | $0.1515 \%$ | $0.2427 \%$ |
| 0.80 | $36.87^{\circ}$ | $0.1967 \%$ | $0.3150 \%$ |
| 0.70 | $45.57^{\circ}$ | $0.2674 \%$ | $0.4282 \%$ |
| 0.60 | $53.13^{\circ}$ | $0.3494 \%$ | $0.5594 \%$ |
| 0.50 | $60.00^{\circ}$ | $0.4538 \%$ | $0.7264 \%$ |
| 0.25 | $75.52^{\circ}$ | $1.0141 \%$ | $1.6229 \%$ |

* For Calibrator output $<65 \mathrm{~Hz}$

Final Width $=215 \mathrm{~mm}$

## Section 8 Model 9100 - Routine Maintenance and Test

## 8.1 <br> About Section 8

Section 8 gives first-level procedures for maintaining a Model 9100, performing the Selftest operations and dealing with their results. We shall recommend maintenance intervals, methods and parts, and detail the routine maintenance procedures. Section 8 is divided into the following sub-sections:
8.2 Routine Maintenance and Repair
8.2.1 General Cleaning
8.2.2 Air Intake Filter - Description and Maintenance Intervals
8.2.2.1 Removing the Instrument Top Cover
8.2.2.2 Calibration Seal - Caution!
8.2.2.3 Removing the Filter Element
8.2.2.4 Cleaning the Filter Element
8.2.2.5 Refitting the Filter Element
8.2.2.6 Refitting the Top Cover
8.2.2.7 Replacement Parts
8.2.3 Firmware Upgrade - Procedure 8.2.3.1 Introduction
8.2.3.2 Procedure
8.2.4 Fuse Replacement - Procedure
8.2.4.1 Introduction
8.2.4.2 Replacement Fuses
8.2.4.3 Diagnosing Blown Output Fuses
8.2.4.4 Replacing Hi and Lo Terminal Fuses
8.2.4.5 Replacing $\mathrm{I}+$ and I - Terminal Fuses
8.3 Model 9100 Test and Selftest
8.3.1 Types of Test
8.3.1.1 Entry to Test Mode.
8.3.2 Fast/Full Selftest
8.3.2.1 Aborting the Selftest.
8.3.2.2 Selftest Runs to Completion.
8.3.2.3 Viewing the Test Results.
8.3.2.4 Printing the Test Results.
8.3.3 Selftest at Power-on.
8.3.4 Interface Test.
8.3.4.1 Access to Interface Tests.
8.3.4.2 Display Memory Checks.
8.3.4.3 Keyboard Checks.
8.3.4.4 Display Checks.
8.3.4.5 Memory Card Checks.
8.3.4.6 Serial Mouse Checks.
8.3.4.7 Printer Checks.
8.4 Printing Selftest Results.
8.4.1 Parallel Port J103.
8.4.2 Printing Setup.
8.4.2.1 Printer Type.
8.4.2.2 Data Formatting.
8.4.3 Results Printout.

Appendix A: Error Reporting Subsystem.

## 8.2 <br> Routine Maintenance

### 8.2.1 <br> General Cleaning

The instrument surfaces should be kept clean, as the front panel controls are likely to be in continuous use within a working environment. Clean when required.
Remove dust from the top cover using a soft brush (do not use a cloth unless it it lintfree). Keep the controls clean using a soft, lint-free cloth, dampened with a non-toxic, non-corrosive detergent. The display screen should be cleaned using a soft, lint-free cloth, dampened with an anti-static cleanser; avoid extreme pressure on the face of the screen and do not spray the screen directly.

### 8.2.2 Air Intake Filter

N.B. Do not remove any covers without first disconnecting the line power lead.

The internal airflow is powered by an axial fan which blows cooling air through a heatsink to be exhausted on the left side via a cover grille. Replacement air is drawn into the instrument through holes in the right side of the top cover, then through a 20ppi (pores per inch) reticulated filter. This filter is accessed by removing the top cover.

Once the cover is removed, an expanded metal grille can be seen, welded to the right side of the chassis assembly, covering two rectangular apertures into the main and rear cavities. The reticulated filter is located over this grille and attached through it to the chassis assembly, by five black nylon snap rivets.
The filter should not be allowed to become clogged with dust and dirt, as this will restrict he designed airflow through the instrument. Dust can be removed using a small vacuum cleaner to create a reverse airflow, but this will not clean off grease and other dirt which will accumulate over time.
It is recommended that the filter element should be inspected and cleaned by vacuuming at intervals of no more than 90 days, and should be removed for cleaning at least once per year, immediately prior to routine calibration of the unit.

### 8.2.2.1 Removing the Top Cover

The side edges of the top cover are located in slots in both side extrusions, and secured to the rear panel by two screws. A solid plastic block protects each of the rear corners.
To access the filter element, remove the top cover as follows:

1. Release the four screws securing the two rear-corner blocks and remove the blocks.
2. Release the two screws securing the top cover to the rear panel.
3. Pull the top cover to the rear to clear the front bezel, then lift off to the rear.

### 8.2.2.2

## Calibration Seal

Caution!
With the cover removed, a 'Calibration seal' can be seen covering a countersunk screwhead on the left side of the chassis assembly, at the top. This is one of the securing screws for the top guard shield. The seal is set in position following a calibration of the instrument, so that removal of the guard shield can be detected.
The calibration seal must NOT be broken unless the guard shield is to be removed for Authorized work inside the chassis assembly. Removal of the guard shield will compromise the traceable calibration of the instrument, and a full recalibration of the 9100 will be required.

### 8.2.2.3 Removing the Filter Element

The filter is removed as follows:
Carefully lever out the center pin of each of the five black nylon snap rivets and pull out the snap latches. Lift off the filter element.

### 8.2.2.4 Cleaning the Filter Element

Once the filter is removed, wash it in warm water and household detergent, rinse thoroughly and allow to dry.

### 8.2.2.5 Refitting the Filter Element

1. Hold the filter element in position over the expanded metal grille so that it overlaps both main and rear apertures, and the five securing holes. Separate the latch and center pin of a black nylon snap rivet, and push the latch through the filter into the center securing hole in the top row. Fit the center pin into the latch and push fully home, so that the pin opens the splits in the rear of the latch.
2. Slightly stretch the filter element into the correct position; fit and secure the other four snap rivets.

### 8.2.2.6 Refitting the Top Cover

Carefully refit the top cover into the slots in the side extrusions, with the front edge immmediately behind the front bezel; push forward to locate inside the bezel, and secure to the rear panel using the two screws. Refit and secure the corner blocks.

### 8.2.2.7 Replacement Parts

Should the filter or snap rivets become damaged by removal or refitting, the following parts can be ordered through your Fluke Sales and Service Center:

| Part No. Description | Manufacturer | Type | Quantity |  |
| :--- | :--- | :--- | :--- | :---: |
| 451004 | 20ppi Reticulated Foam Filter | ---- | --- | 1 |
| 617020 | Snap Rivet, Black Nylon | Richco. | SR4050B | 5 |

### 8.2.3 Firmware Upgrade <br> 8.2.3.1 Introduction

The Model 9100 firmware can be upgraded using a 'Personal Computer Memory Card Interface Adaptor' (PCMCIA). To do this, the Model 9100 has been fitted with FLASH memory chips to provide the update capability.

If an upgrade is required for your Model 9100 unit(s), your Service Center will inform you and provide the appropriate PCMCIA card.
This Sub-Section describes the routine procedure for upgrading the firmware. Note that the Full Self Test appears twice in the procedure: before and after carrying out the upgrade. This is included on two occasions to determine whether any difficulties were present before the upgrade, or whether they have arisen as a result of the upgrade.

### 8.2.3.2 Procedure

1. Full Self Test (Refer to paras 8.3.1 \& 8.3.2):

Execute a Full Self Test and record any errors. If printing facilities are available, select the PRINT option to obtain a hard copy of the results.
2. Prepare the 9100 :
a. Switch 9100 Power OFF.
b. Locate the FACTORY SET switches on the 9100 rear panel:

i. Remove the switch cover by releasing its retaining screw.

ii. Set Switch 6 to the ENABLE position (up) Do not disturb any of the other switches.


## 3. Insert the PCMCIA Card:

a. Locate the 'PROCEDURE MEMORY CARD' slot in the 9100 front panel.
b. Insert the PCMCIA card into the 'PROCEDURE MEMORY CARD' slot, exerting just enough pressure to push out the black button by the side of the slot.
4. Re-Program the Firmware:
a. Switch 9100 Power ON.
b. Observe the following growth pattern on the 9100 LCD display:


The process takes approximately 1 minute 10 seconds to complete. When complete, a repetitive, pulsed audible tone will be heard.
If for any reason a continuous audible tone is heard, the update has not been successful. Note the current state of the growth pattern on the display, and relay this information back to the Service Center.
5. Recover the Operational State of the 9100 :
a. Switch 9100 Power OFF.
b. Return Switch 6 to the DISABLE position. Do not disturb any of the other switches.
c. Replace and secure the switch cover.
d. Remove the PCMCIA card, switch the 9100 Power ON and wait for approximately 1 minute until the Power-On Selftest is complete.
e. On the right of the 9100 front panel, press the Mode key.
f. At the bottom of the 9100 LCD display, press the soft CONFIG key, and check that the firmware issue, shown on the screen, matches that on the PCMCIA card.
g. Transfer back to the Mode Selection screen by pressing the Mode key.
6. Full Self Test (Refer to paras 8.3.1 \& 8.3.2):
a. Execute a Full Self Test and record any errors. If printing facilities are available, select the PRINT option to obtain a hard copy of the results (refer also to paras 8.4).
b. Note any differences between the self tests at items 1 and 6 .
c. Report the results of the upgrade procedure back to the Service Center.

The Model 9100 firmware upgrade is now complete. Please return your PCMCIA to the Service Center.

### 8.2.4 Output Fuse Replacement Warning! Fuse replacement should be carried out by a suitable skilled and competent person. 8.2.4.1 Introduction

The Model 9100 outputs are protected by internal fuses.
Access to five fuses is provided:

- The Hi and Lo Terminal lines are protected by two fuses, concealed behind a small cover underneath the instrument.
- The I+ and I- Terminal lines are protected by three fuses which protrude through the top guard shield under the top cover.

The following paragraphs deal with diagnosing blown output fuses, access and procedures for replacement.

### 8.2.4.2 Replacement Fuses

The following fuses can be ordered through your Fluke Sales and Service Center:

| Function | Part No. | Description | IEC Designation | Manufacturer | Type |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Hi Terminal Fuse | 920293 | 500mA 250V TR5 (F) | F0.5AL | Wickmann | $19370-500$ |
| Lo Terminal Fuse | 920293 | 500 mA 250 V TR5 (F) | F0.5AL | Wickmann | $19370-500$ |
| I- Terminal Fuse (Low Currents) | 920208 | 1A 250V 20mm (F) | F1AL | Belling Lee | L1427B/1A |
| I+ Terminal Fuse (Low Currents) | 920294 | 500 mA 250 V 20 mm (F) | F0.5AL | Schurter | 0034.1513 |
| I+ Terminal Fuse (High Currents) | 920295 | 4A 250V 20mm (F) | F4AL | Schurter | 0034.1522 |

### 8.2.4.3 Diagnosing Blown Output Fuses

## 1. Hi and Lo Terminal Fuses

These fuses are placed in the Hi and Lo output lines, between the final output switching relays and the terminals. Suspect that these fuses have blown, if the output from the terminals is grossly incorrect, but the Self Test indicates no fault.

## 2. I+ and I- Terminal Low Current Fuses

(when operating in AC or DC Current function, except for the 3A and 20A Spans)
These fuses are placed in the output lines for I+ and I-, except when the 3A and 20A Spans are in use. The positions are shown on the top inside cover. If either has blown, the over-compliance error message will be generated.

## 3. I+ Terminal High Current Fuse

(when operating in AC or DC Current function, working in the 3A Span)
This fuse is placed in the output line for $\mathrm{I}+$, only when the 3 A Span is in use. The position is shown on the top inside cover. If it has blown, the over-compliance error message will be generated.

## 4. In General:

Sometimes a blown fuse can cause a 'Fatal Error' (refer to Appendix A to this Section 8).
The internal fuses are unlikely to be blown as a result of an internal fault. The most likely cause of failure is the inadvertent application of power from an external source.
The 20A Span is driven from a separate heavily-protected output stage, and the output is not fused.

### 8.2.4.4 <br> Replacing Hi and Lo Terminal Fuses

1. Access
a. Switch 9100 Power OFF and disconnect the line power lead.
b. Lift the left side of the 9100 to stand on its right side. Rotate the instrument to give good access to the small panel (Fig. 8.2.1) on the underside:


Fig. 8.2.1 Fuse Cover Access
i. Pull the tilt stand out for better access.
ii. Unscrew four M3 x 6 Pozi-Countersunk screws to release the panel.
2. Fuse Removal
a. Ensure that 9100 Power is still OFF.
b. Locate the two fuse caps (Fig. 8.2.2) in the recess:
i. Unscrew the relevant fuse cap(s).
ii. Remove the fuse(s) by pulling carefully on the cylindrical fuse body.
3. Fuse Testing
a. Check each removed fuse for continuity and correct type.
b. Decide whether the fuse is to be re-fitted or replaced.


## 4. Fuse Fitting

WARNING
MAKE SURE THAT ONLY FUSES WITH THE REQUIRED RATED CURRENT AND OF THE SPECIFIED TYPE ARE USED FOR REPLACEMENT.
THE FUSE-HOLDERS ARE NOT TO BE SHORTCIRCUITED. THIS PRACTICE WILL RENDER THE WARRANTY VOID.
a. Ensure that 9100 Power is still OFF.
b. Locate the two fuse holders in the recess:
i. Fit each fuse by inserting its two pins into the holder holes, then carefully push the fuse body home.
ii. Screw on the relevant fuse cap(s).

### 8.2.4.5 <br> Replacing I+ and I- Terminal Fuses

1. Access
a. Switch 9100 Power OFF and disconnect the line power lead.
b. Remove the Top Cover

The side edges of the top cover are located in slots in both side extrusions, and secured to the rear panel by two screws. A solid plastic block protects each of the rear corners.
To access the I+ and I- Terminal Fuses, remove the top cover as follows:
i. Release the four screws securing the two rear-corner blocks and remove the blocks.
ii. Release the two screws securing the top cover to the rear panel.
iii. Pull the top cover to the rear to clear the front bezel, then lift off to the rear.
c. Calibration Seal

Caution!
With the cover removed, a 'Calibration seal' can be seen covering a countersunk screwhead on the left side of the chassis assembly, at the top. This is one of the securing screws for the top guard shield. The seal is set in position following a calibration of the instrument, so that removal of the guard shield can be detected.
The calibration seal must NOT be broken unless the guard shield is to be removed for Authorized work inside the chassis assembly. Removal of the guard shield will compromise the traceable calibration of the instrument, and a full recalibration of the 9100 will be required.
d. Locate the Fuses

The fuses are located at the left front of the top guard shield, beneath the ribbon cable which links to the Interconnection PCB on the rear panel, and protruding through grommets in the guard shield (Fig 8.2.3).


Fig. 8.2.3 Location of I+ and I- Terminal Fuses

## 2. Disconnect the Ribbon Cable

a. Ensure that 9100 Power is still OFF.
b. Locate the ribbon cable connector and latch levers on the Interconnection PCB attached to the rear panel:
i. Carefully push both latch levers outwards at the same time. This will ease the connector out of its housing.
ii. Release the connector and pull the ribbon cable towards the front of the instrument to reveal the fuse holders beneath
3. Fuse Removal
a. Ensure that 9100 Power is still OFF.
b. Locate the three bayonet fuse caps (Fig. 8.2.3):
i. Release the relevant fuse cap(s) by pushing down, turning counter-clockwise.
ii. Remove the fuse(s) by pulling carefully.
4. Fuse Testing
a. Check each removed fuse for continuity and correct type.
b. Decide whether the fuse is to be re-fitted or replaced.

## 5. Fuse Fitting

## WARNING

MAKE SURE THAT ONLY FUSES WITH THE REQUIRED
RATED CURRENT AND OF THE SPECIFIED TYPE ARE
USED FOR REPLACEMENT.
THE FUSE-HOLDERS ARE NOT TO BE SHORTCIRCUITED. THIS PRACTICE WILL RENDER THE

## WARRANTY VOID.

a. Ensure that 9100 Power is still OFF.
b. Locate the three bayonet fuse holders (Fig. 8.2.3):
i. Fit each correct fuse by inserting it into the holder, and carefully push the fuse home
ii. Secure the relevant fuse cap(s) by pushing down and turning clockwise

## 6. Reconnect the Ribbon Cable

a. Ensure that 9100 Power is still OFF.
b. Locate the ribbon cable connector across the top of the instrument, and into its housing on the Interconnection PCB attached to the rear panel:
i. Carefully push the connector into its housing. This will cause the latch levers to move together and latch as the connector is driven fully home.
ii. Finally, push the latch levers together to ensure that both latches are fully home, with the connector correctly housed.
7. Refitting the Top Cover

Carefully refit the top cover into the slots in the side extrusions, with the front edge immmediately behind the front bezel; push forward to locate inside the bezel, and secure to the rear panel using the two screws. Refit and secure the corner blocks.

## 8.3 <br> Model 9100 Test and Selftest

8.3.1

Types of Test
There are two main types of selftest, 'Fast' and 'Full'. The Fast selftest is also performed automatically at power-on. In addition, the interface for front panel operation can be selectively tested, covering such areas as display memory integrity, keyboard operation, the display itself, integrity and formatting of static RAM memory cards for Procedure mode, the correct operation of a connected serial mouse, and the correct operation of a connected printer. These tests are detailed in the following paragraphs:

### 8.3.1.1 Entry to Test Mode

Test mode is selected from the Mode Selection menu, which is displayed by pressing the front panel 'Mode' key, highlighted in Fig 8.3.1, below:


Fig. 8.3.1 'Mode' Key

### 8.3.1.1 Entry to Test Mode (Contd.)

The Mode key sets up a special menu display, offering selection from five primary modes. This menu can be exited only by pressing one of the five screen keys.

## Mode Selection

Select required mode using softkeys.


TEST
This key enters Test mode, displaying the following screen:

## Selftest

Select required test using softkeys.


FAST runs a FAST selftest.
FULL runs a FULL selftest.
INTERFACE allows checks of the display and display memory, the front panel keyboard, the (Procedure mode) memory card slots, the mouse, and the printer interfaces.

### 8.3.2 Fast/Full Selftest

Both Fast and Full selftests follow the same format. By pressing the FAST or FULL screen key on the 'Select required test' menu screen, the 9100 runs the selected selftest. The first screen shows the pathway under test and the number of tests remaining, for the selected selftest:

## Selftest

Running FAST test.
Testing pathway no. $X \times X . X X X$
Tests remaining: XX

## Selftest.

Running FULL test. Testing pathway no. $X \times X$. $X X X$ Tests remaining: $X X$

### 8.3.2.1 Aborting the Selftest

ABORT stops the selftest and displays the appropriate 'ABORTED' screen:

## Selftest.

Test ABORTED with no failures.

## Selftest.

Test ABORTED with failures.
Number of failures: $X X$
Use the softkeys to view the results.

| TOOAYS DATE | TMME |  |  | VIEW |
| :---: | :---: | :---: | :--- | :--- |
| EXIT | PRINT |  | FAILS |  |

If there were no failures up to the point of aborting, this is shown on the screen.
EXIT returns to the 'Select selftest' menu screen.
PRINT prints out the results of the test, up to the point of aborting.
Refer to Sub-section 8.4.
If failures were encountered up to the point of aborting, EXIT and PRINT are available. Also, the number of failures is shown on the screen, and an extra selection will be available:

VIEW FAILS sets up a special screen for detailing the parameters of the failures encountered (described later in Paras 8.3.2.3).

### 8.3.2.2 Selftest Runs to Completion

If the selftest is not aborted, it will run to completion, and if the test is successful with no failures, the following screen will appear for either Fast and Full test:

## Selftest.

Test completed with no failures.

If failures were encountered during the test, the 9100 will display the following screen:

## Selftest.

Selected test has FAILED.
Number of failures: XX
Use the softkeys to view the results.


EXIT returns to the 'Select selftest' menu screen.
PRINT prints out the results of the test, whether Full or Fast. Refer to Sub-section 8.4

If failures were encountered, EXIT and PRINT remain available. Also, the number of failures is shown on the screen, and an extra selection will be available:

VIEW FAILS sets up a special screen for detailing the parameters of the failures encountered (described later in Paras 8.3.2.3).

### 8.3.2.3 Viewing the Test Results

By pressing the VIEW FAILS screen key, each of the failed tests can be viewed in turn, on a screen which shows the test number (pathway), averaged measured value, upper and lower limits, and the values of the two measurements which were used to derive the 'Measured value'. A brief description of the test is also given.

The screen for viewing the test results is shown below. This can also be used when a est has been aborted.

## Selftest. <br> Test no. XXX.XXX FAIL. <br> Measured value: $\times \times \times \times \times \times \times$ <br> $\begin{array}{ll}\text { Upper Limit: } & \times \times \times \times \times \times \times \\ \text { Lower Limit: } & \times \times \times \times \times \times \times\end{array}$ <br> Measurement A: $\times \times \times \times \times \times \times$ <br> Measurement $B: \times \times X \times \times \times \times$ <br> (Description of test) <br> DAAYS DATE TIIE <br> EXIT PRINT <br> FAILURE

N.B. If the cause of failure is not immediately obvious, and it is intended to consult your Fluke Service Center, please ensure that you either: copy the details from the screen for all the reported failures, or: print out the results. No second viewing of the same failure is allowed, although all the test results remain available for printing.

## NEXT FAILURE

Once the details of the first failure have been noted, the next failure in the list can be viewed by pressing the NEXT FAILURE screen key. Only one pass through the list of failures is allowed. Once the last failure in the list is on the screen, and the NEXT FAILURE screen key is pressed, the following error message will appear in the top right of the screen:

```
No more failures
Nomor
```

Pressing the NEXT FAILURE screen key will have no further effect. The user must either exit back to the 'Select selftest' screen, or print out the results.

### 8.3.2.4 Printing the Test Results

The PRINT screen key is present on all screens after the test has run to completion or has been aborted. Pressing the PRINT key will print out all the available results.

Printing will only be possible if a suitable printer is set up, connected and on line. Refer to Sub-section 8.4.

### 8.3.3 Selftest at Power-On

N.B. Certain catastrophic 'Fatal System Errors' may cause the display to flash on and off, at the point of setting power on. In this case, immediately switch Power Off and report the fault to your Service Center.
The first normal action at power on is to show the Fluke logo, and then the 9100 will run a fast selftest. The user is requested to wait until the selftest is finished:

## FLபKE

## Please wait approx. 1 minute while

internal checks are performed.

If no failures are found, the 9100 will revert to the default power-up mode, which is either Manual mode or Procedure mode.
If failures are encountered (including other 'Fatal System Errors' — refer to Appendix A to this Section 8), the 9100 will lapse into Test mode at the following stage:

## Selftest.

Selected test has FAILED. Number of failures: XX

Use the softkeys to view the results.
tooars date
EXIT PRINT
TIME
TMME
VIEW
FAILS
FAILS
Subsequent action to view the failures and print the results follows as for a Fast selftest which has run to completion (refer to paras 8.3.2.2/3).
EXIT will return to the 'Select selftest' menu screen, where, to return to the 'Mode Selection' menu screen, merely press the front panel Mode key.

PRINT can be used to print out the results of the power-on Fast test.
Refer also to Sub-section 8.4.

### 8.3.4 Interface Test

The interface test selectively checks the 9100 front panel operations, covering display memory integrity, keyboard operation, the display itself, integrity and formatting of static RAM memory cards for Procedure mode, the correct operation of a connected mouse, and the correct operation of a connected printer.

### 8.3.4.1 Access to Interface Tests

Once the Test mode has been selected, Interface Test can be selected by pressing the INTERFACE screen key in the 'Select required test' menu:

## Selftest.

Select required test using softkeys.


Pressing INTERFACE transfers to the 'Select test' menu screen:

| Selftest. | DISPLAY <br> MEMORY |
| :---: | :---: |
| Select test using softkeys. <br> KEYBRD |  |
|  | DISPLAY <br> MEMORY <br> CARD |
|  | TRACKER |

The required check can be selected from the list on the right of the screen, using the corresponding screen key.

EXIT returns to the previous 'Select required test' menu screen.
The six available checks are detailed, in list order, in the following paragraphs.

### 8.3.4.2 Display Memory Checks

Pressing the DISPLAY MEMORY key on the 'Select test' menu screen transfers to the 'Memory test.' screen, and the sequence of tests begins. The test in progress is reported on the screen:

| Selftest. <br> Select test using softkeys |  | DISPLAY <br> MEMORY | Memory test. <br> Performing READ/WRITE test 1. |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | KEYBRD |  |  |
|  |  | DISPLAY |  |  |
| tooavs date time |  | $\begin{aligned} & \text { MEMORY } \\ & \text { CARD } \end{aligned}$ |  |  |
|  |  | tracker |  |  |
|  |  | Printer |  |  |
| EXIT |  |  | TOOAYS DATE |  |

The other tests reported are:
Performing WALKING ONES test 1.
Performing READ/WRITE test 2.

The result of the whole Memory test is reported once testing is complete:

## Memory test.

Display memory PASSED.


## Memory test.

Display memory FAILED.
odars date
EXIT
If a failure is reported, rectification will require access to the internal circuitry, so no further user action is recommended, except to report the result to your Fluke Service Center.

EXIT returns to the Interface 'Select test' menu screen.

### 8.3.4.3 Keyboard Checks

Keyboard checks are initiated by pressing the KEYBOARD key on the 'Select test' menu screen:

|  |  | DISPLAY MEMORY |
| :---: | :---: | :---: |
|  |  | KEYBRD |
| Selftest. <br> Select test using softkeys |  | display |
|  |  | $\begin{gathered} \text { MEMORY } \\ \text { CARD } \end{gathered}$ |
|  |  | tracker |
|  |  | Printer |
| TODAY DATE TIME |  |  |
| EXIT |  |  |

Selecting 'KEYBRD' transfers to the 'Keyboard test.' screen. This invites a user to press the front panel key to be tested, and reports on the screen the details of the last key to be pressed:

## Keyboard test.

Press key to be tested.


The 'Keyboard matrix reference' ( $\mathrm{X}, \mathrm{Y}$ ) relates to the electronic matrix which is used to transfer keypress information to the internal processor, and does not relate closely to the physical layout of keys. The 'Key name' ( $Z$ ) is the name, in words, which describes the last key to be pressed.
If the reported key name does not coincide with the function of the last key to be physically pressed, a failure is implied. Rectification will require access to the internal circuitry, so no further user action is recommended, except to report the result to your Fluke Service Center.

EXIT returns to the Interface 'Select test' menu screen.

### 8.3.4.4 Display Checks

Display checks are initiated by pressing the DISPLAY key on the 'Select test' menu screen:


Selecting 'DISPLAY' transfers to the 'Display test.' screen. This invites a user to use the front panel'tab' ( -1 ) key to move the dark band down the screen, up to the top, and down again, thus testing all the display elements on the screen:

## Display test.

Use the tab key to advance the band and the enter key to exit the test.

The screen text will shift automatically so as not to obscure the band as it jumps back to the top of the screen. If there are elements of the screen which do not show light in the light background or dark in the dark band as it is advanced down the screen, then this implies a failure. Rectification will require access to the internal circuitry, so no further user action is recommended, except to report the result to your Fluke Service Center.

The 'Enter' Key (ل) returns to the Interface 'Select test' menu screen.

### 8.3.4.5 Memory Card Checks

Memory Card checks are initiated by pressing the MEMORY CARD key on the 'Select est' menu screen:

| Selftest. | DISPLAY <br> MEMORY |
| :---: | :---: |
| Select test using softkeys | KEYBRD |
|  | DISPLAY <br> MEMORY <br> CARD |
|  | TRACKER |
| TODAY DATE |  |
| EXIT |  |

Pressing the MEMORY CARD key on the 'Select test' menu screen transfers to the 'Card slot test.' screen. This invites a user to select the memory card slot to be tested, and presents an 'Overwrite' warning:

## Card slot test. proc

Select the card slot to be RESULTS tested using the soft keys.

## WARNING!!

Card data will be overwritten.
foody date
EXIT

## PROC <br> selects the PROCEDURE slot for testing.

RESULTS selects the RESULTS slot for testing.
EXIT returns to the Interface 'Select test' menu screen
Either slot can be used for the test. If one particular slot is suspect then that, naturally, will be the one to choose.
The warning gives notice that the inserted memory card will be overwritten by this test. This is because reformatting is required to perform the checks and the card inserted into the slot will be reformatted as a Results card.

It is not possible to format a Procedure card using this test, as procedures are written onto cards by a different process (Fluke Model 9010).

The 9100 first checks for the presence of the correct SRAM card. If there is no card in the slot, if the card in the slot is not a SRAM card, or if it is a SRAM card but not writeenabled, then the following screen is displayed:

## Card slot test.

Insert a write enabled STATIC RAM card into the selected slot

If no card in selected slot, or if
card not write-enabled, or if not a
SRAM card)

After correcting the defect, press the OK screen key. This transfers to a new screen, and the sequence of tests begins. The test in progress is reported on the screen:
The 9100 first checks the state of the card's internal battery. If the battery voltage is low, this will be stated on the screen:

## Card slot test.

Battery level is low.
roays date
TIME

If there is no battery in the card, or if the battery cannot support read/write operations, then the statement will be 'Battery level is dead.'

## Note:

For a re-chargeable card with a low battery, the low/dead message may take several minutes to clear after pressing OK.

### 8.3.4.5 Memory Card Checks (Contd.)

The next test is to check the size of the card memory. While the 9100 is checking, it will place the following message on the screen:

## Card slot test.

Checking card size

```
TOOAIS OAIE
TIME
```

Once the size check is completed, the 9100 starts on a 'read/write' check; meanwhile the display changes to:

## Card slot test.

Card size: XXXX k Bytes Performing READ/WRITE test.
todars date time

After the read/write check, the 9100 starts on a 'walking ones' check, and the message on the display changes to:

Performing WALKING ONES test.
The test continues, this time to format the memory into 'Results Card' format. A new message appears on the display:

Performing RESULTS CARD format.

Providing that the full range of tests and formatting is completed successfully, the PASS statement is added to the screen:

## Card slot test.

Card size: XXXX k Bytes
Performing RESULTS CARD format.
Selected card interface PASSED.

DOAYS DATE
EXIT

EXIT returns to the Interface 'Select test' menu screen.
If the test fails at any point, then the test will stop, leaving the heading for the failed test on the screen, followed by a failure statement. For example, if the failure occurred during the 'walking ones' check, then the following screen would be presented:

## Card slot test.



To diagnose the reason for a failure, there are several further checks which can be made to localize the fault. Firstly, an attempt should be made to re-check the same card in the other slot, then if this is successful, check a new card in the original slot. This should narrow the fault down to one slot or one card. If it is suspected that the 9100 is at fault, it is wise to report the result to your Fluke Service Center.
EXIT returns to the Interface 'Select test' menu screen.

### 8.3.4.6 Serial Mouse Checks

Checks of a connected serial mouse are initiated by pressing the TRACKER key on the 'Select test' menu screen:

| Selftest. | DISPLAY <br> MEMORY |
| :---: | :---: |
| Select test using softkeys | KEYBRD |
|  |  |

Selecting 'TRACKER' transfers to the 'Tracker test.' screen. This invites a user to use a mouse to test the interface, and reports on the screen the details of the last key to be pressed, and the last movement of the mouse:

## Tracker test.

Use a tracker ball to test interface.


The possible responses are shown on the diagram. Note that other mouse buttons or wheels have no function with the 9100 and are not tested, so pressing these controls should have no effect unless the mouse is defective.
If the last key to be named does not coincide with the last key to be physically pressed, or if the last direction shown does not correspond to the last physical movement, then a failure is implied. It is possible to diagnose the defect source by checking a second mouse on the same 9100 , or the same mouse on a different 9100 . Rectification may require access to the internal circuitry of the 9100 or mouse, so no further user action is recommended, except to report the result to your Fluke Service Center.

EXIT returns to the Interface 'Select test' menu screen.

### 8.3.4.7 Printer Checks

Checks of a connected printer are initiated by pressing the PRINTER key on the 'Select test' menu screen:

| Selftest. | DISPLAY <br> MEMORY |
| :---: | :---: |
| Select test using softkeys | KEYBRD |
|  | DISPLAY <br> MEMORY <br> CARD |

Selecting 'PRINTER' transfers to the 'Printer test.' screen. This invites a user to use a printer to test the interface (e.g. by switching the printer off-line, or removing the paper), and reports on the status of the printer:

## Printer test.

Use a printer to test interface
Press EXIT to stop printout
Printer status: PRINTING
NOT RESPONDiNG
OUT OF PAPER

| TODAY D DAEE | TME |  |  |  |
| ---: | :--- | :--- | :--- | :--- |
| EXIT |  |  |  |  |

Note: If the printer is disabled (Config mode - Volume 1, Section 3, paras 3.3.2.5), the printer will not be set up when starting to print for the first time.
The possible responses are shown on the diagram. They are updated automatically as the printer status changes. When operating correctly, the printer will print a characterset continuously until the EXIT screen key is pressed.

If the reported status of the printer interface does not match the known physical status, then this implies a failure. It is possible to diagnose the defect source by checking a second printer unit on the same 9100 , or the same printer unit on a different 9100 . Rectification may require access to the internal circuitry of the 9100 or printer unit, so no further user action is recommended, except for obvious setup errors. Otherwise it is advisable to report the result to your Fluke Service Center.

EXIT returns to the Interface 'Select test' menu screen.

## 8.4

## Printing Selftest Results

The results of Full and Fast selftests can be printed out by a printer connected to the parallel port J103 on the rear panel. It can also be used to print out certificates for UUTs calibrated in Procedure mode

### 8.4.1 Parallel Port J103 (Rear Panel)

This 25 way D-Type socket is located beneath the IEEE-488 connector on the rear panel. Its connections are similar to the 25 -way printer port on PCs, carrying control and data for an external printer as designated in the table.

Pin Layout


## Pin Designations

| $\begin{gathered} 9100 \\ \text { Pin No. } \end{gathered}$ | $\begin{aligned} & \hline 9100 \\ & \text { Signal Name } \end{aligned}$ | $\begin{gathered} 9100 \\ \text { I/O } \end{gathered}$ | Description or Common Meaning |
| :---: | :---: | :---: | :---: |
| 1 | STROBE_L | Output | $1 \mu \mathrm{~s}$ pulse to cause printer to read one byte of data from data bus DO1 - DO8. |
| 2 | DO1 | Output | Data bit 1 |
| 3 | DO2 | Output | Data bit 2 |
| 4 | DO3 | Output | Data bit 3 |
| 5 | DO4 | Output | Data bit 4 |
| 6 | DO5 | Output | Data bit 5 |
| 7 | DO6 | Output | Data bit 6 |
| 8 | DO7 | Output | Data bit 7 |
| 9 | DO8 | Output | Data bit 8 |
| 10 | ACKNLG_L | Input | Pulse to indicate that the printer has accepted a data byte, and is ready for more data. |
| 11 | BUSY_H | Input | Printer is temporarily busy and cannot receive data. |
| 12 | P_END_H | Input | Printer is out of paper. |
| 13 | SLCT_H | Input | Printer is in online state, or connected. |
| 14 | AUTO_FEED_L | Output | Paper is automatically fed 1 line after printing. This line is fixed _H (high) by the 9100 to disable autofeed. |
| 15 | ERROR_L | Input | Printer is in 'Paper End', 'Offline' or 'Error' state. |
| 16 | INIT_L | Output | Commands printer to reset to power-up state, and in most printers to clear its print buffer. |
| 17 | SLCT_IN_L | Output | Commands some printers to accept data. This line is fixed _L (low) by the 9100 . |
| 18-25 | OV_F | Output | Digital Common |

[^0]
### 8.4.2 Printing Setup

The results of Full and Fast selftest operations can be printed directly via the rear panel parallel port J103. A suitable printer must be connected and switched on-line; then the 9100 internal program will generate the required results.

### 8.4.2.1 Printer Type

The printer to be used should be capable of printing 120 characters per line, and must be able to print the Code Page 437 character set. Most printers compatible with Epson FX, Canon Bubble-Jet or Hewlett-Packard Desk-Jet are suitable.

### 8.4.2.2 Data Formatting

The required printout style, format and data is pre-determined depending on whether Full or Fast test results are being printed, and on the type of printer to be used. It is necessary to enable a particular printer type via Configuration mode, only if the format for that printer is required.
Note: If the printer is disabled (Config mode - Volume 1, Section 3, paras 3.3.2.6), the printer will not be set up when starting to print for the first time.

### 8.4.3 Results Printout

Apart from the heading, both Full and Fast test results have the same printed layout. The results of tests on all test pathways are collected together in a table. Typical samples of tables are given below:

Serial No: XXXXXX S/W Issue: X.XX Date: XX/YY/ZZZZ Time: 12:41 Type: FAST

| TEST PT | MEAS VALUE | MAX LIMIT | MIN LIMIT | NOMINAL | RESULT A | RESULT B | ERROR \% | FAILURES |
| :---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| Aø4. $\varnothing \varnothing 1$ | $-\varnothing . \varnothing \varnothing \varnothing \varnothing 44 ~$ | $+\varnothing . \varnothing \varnothing 15 \varnothing \varnothing$ | $-\varnothing . \varnothing \varnothing 15 \varnothing \varnothing$ | $\varnothing . \varnothing \varnothing \varnothing \varnothing \varnothing \varnothing$ | $\varnothing . \varnothing \varnothing \varnothing \varnothing 41$ | $-\varnothing . \varnothing \varnothing \varnothing \varnothing 48$ | -3 |  |
| Aø1.øø1 | $+6.55334 \varnothing$ | $+6.6 \varnothing 28 \varnothing \varnothing$ | $+6.5 \varnothing 44 \varnothing \varnothing$ | $+6.5536 \varnothing \varnothing$ | +6.553363 | +6.553316 | $\varnothing$ |  |
| Pø5.øø1 | $+5.115 \varnothing \varnothing 5$ | $+5.725 \varnothing \varnothing \varnothing$ | $+4.675 \varnothing \varnothing \varnothing$ | $+5.2 \varnothing \varnothing \varnothing \varnothing \varnothing$ | +5.114981 | $+5.115 \varnothing 29$ | -16 |  |

Serial No: XXXXXX $\quad$ S/W Issue: X.XX

| TEST PT | MEAS VALUE | MAX LIMIT | MIN LIMIT | NOMINAL | RESULT A | RESULT B | ERROR \% | FAILURES |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Aø1.øø1 | +6.553292 | +6.564493 | +6.552743 | $+6.55367 \varnothing$ | +6.553292 | +6.553292 | -3 |  |
| Aø1.øø2 | +6.553137 | $+6.5662 \varnothing \varnothing$ | $+6.541 \varnothing \varnothing \varnothing$ | $+6.5536 \varnothing \varnothing$ | +6.553173 | +6.553181 | -4 |  |
| Aø1.øø3 | -6.553888 | -6.537325 | -6.569875 | $-6.5536 \varnothing \varnothing$ | -6.553864 | -6.553912 | -2 |  |

ERROR \% gives the achieved percentage of full tolerance for that test.
FAILURES In this column a failure is shown by the figure '1' against the relevant test.

## Error Reporting Subsystem

Note to users: For the sake of completeness, this appendix collects together the error codes which might be generated either on the instrument front panel, or via the IEEE 488 system bus

## 8.A. 1 Error Detection

All errors which cannot be recovered without the user's knowledge, result in some system action to inform the user via a message, and where possible restore the system to an operational condition. Errors are classified by the method with which they are handled. Recoverable errors report the
error and then continue. System errors which cannot be recovered cause the system to reset via the Power-on state to a fatal error report state, from which a 'resume' may clear the error, but generally such messages are caused by hardware or software faults, which require user action.

## 8.A. 2 Error Messages

## 8.A.2.1 Fatal System Errors

For all fatal system errors, the error condition is reported only via the front panel. The error will pull the processor reset line to restart the system as at power-on. The screen will display a message indicating that there has been a fatal error and thus the processor has been reset. A user may continue by use of
the 'resume' key, or from power on, and initiate repair if the fault persists.

The following is a list of error numbers, which will be displayed with their fault descriptions:

ALWAYS: record the total message content for possible use by the Service Center.

| 9501 | DAC Default Charactn. Failed | 9508 - UNEXPECTED Power amp overload |
| :---: | :---: | :---: |
| 9502 | - Failed to clear Flash RAM | 9509 - UNEXPECTED compliance flag |
| 9503 | - UNEXPECTED multiple fail flags | 9510 - Measurement command flushed |
| 9504 | - No A/D ready bit after 160 ms | 9511 - UNEXPECTED Output clamp overload |
| 9505 | - Flash RAM protected by switch | 9990 - UNEXPECTED case in switch statemen |
| 9506 | - UNEXPECTED over temperature flag | UNDEFINED FATAL ERROR ) An error number will be |
| 9507 | - UNEXPECTED HV power supply flag | OPERATING SYSTEM ERROR) allocated at run time |

## 8.A.2.2 Recoverable Errors

## 8.A.2.2.1 Type of Errors

These consist of Command Errors, Execution Errors, Query Errors and Device-Dependent Errors. Command, Query and Execution Errors are generated due to incorrect remote programming. Device-Dependent Errors can be generated by manual as well as remote operation. Each of the reportable errors is identified by a code number.

## 8.A.2.2.2 Error Reporting

In response to a bus or a keyboard error, there are certain categories of error reporting. Primarily, the error will be reported to the original source of the error, but in some cases will be reported to both local and remote operators. Locally, the error will be displayed on the front-panel screen; remotely, it will set the relevant ESR bit, and add the error to the Error Queue.

Note about the ERROR Queue (accessible via the IEEE-488 Interface)
The Error Queue is a sequential memory stack. Each reportable error has been given a listed number and explanatory message, which are entered into the error queue as the error occurs. The queue is read destructively as a First-In/First-Out stack, using the query command:SYSTem:ERRor? to obtain a code number and message.
Repeated use of the query:SYSTem:ERRor? will read successive Device-Dependent, Command and Execution errors until the queue is empty, when the 'Empty' message ( 0 , "No error") will be returned.
It would be good practice to repeatedly read the Error Queue until the 'Empty' message is returned.
The common command $*$ CLS clears the queue.

## 8.A.2.2.3 Command Errors (CME) <br> (Remote operation only)

## Command Error Generation

A Command Error is generated when the remote command does not conform, either to the device command syntax, or to the IEEE 488.2 generic syntax. The CME bit (5) is set true in the Standard-defined Event Status Byte, and the error code number is appended to the Error Queue.

## Command Error Reporting

The error is reported by the mechanisms described earlier in Section 6, Sub-section 6.5, which deals with status reporting.

The Command Errors implemented in the 9100 are listed below; their error numbers conform to those defined in the SCPI Standard document:

[^1]ALWAYS: record the total message content for possible use by the Service Center

## 8.A.2.2.4 Execution Errors (EXE)

## (Remote operation only)

## Execution Error Generation

An Execution Error is generated if a received command cannot be executed due to it being incompatible with the current device state, or because it attempts to command parameters which are out-of-limits.

In remote operation, the EXE bit (4) is set true in the Standarddefined Event Status Byte, and the error code number is appended to the Error queue.

## Execution Error Reporting

The error is reported by the mechanisms described earlier in Section 6, Sub-section 6.5, which deals with status reporting.
The Execution Error numbers are given below, with their associated descriptions.

```
-220,"Parameter error"
-221,"Settings conflict"
-222,"Data out of range"
-223,"Too much data"
-258,"Media protected"
```


## Query Error Reporting

The QYE bit (2) is set true in the Standard-defined Event Status Byte, and the error code number is appended to the Error queue. The error is reported by the mechanisms described earlier in Section 6, Sub-section 6.5, which deals with status reporting.

The specific reason for a query error must be determined by inspection of the command program. No error codes are provided from within the 9100 .

## 8.A.2.2.6 Device-Dependent Errors (DDE)

A Device-Dependent Error is generated if the device detects an internal operating fault (eg. during self-test). The DDE bit (3) is set true in the Standard-defined Event Status Byte, and the error code number is appended to the Error queue. The
error description appears on the display, remaining visible until the next key-press or remote command.
Errors are reported by the mechanisms described earlier in Section 6, Sub-section 6.5, which deals with status reporting.

## 8.A.2.2.7 Device-Dependent Errors Reported only Locally on the Front Panel Screen

The error list for local operations, which are not reported to the remote operator, is given below:
Note that the error number will not be presented on the screen

```
-7001,"Entry contains illegal characters"
-7002,"Entered value is outside the
    allowed range"
-7016,"Bus address must be within the
    range 0 - 30"
-7018,"Borderline must be within the
    range 10.00 - 99.99 %"
-7019,"Entry does not match previous
        password entry"
-9001,"Target too big"
-9002,"Target too small"
-9003,"Frequency too high"
-9004,"Frequency too small"
-9005,"Level too big"
-9006,"Level too small"
-9007,"Deviation too big"
-9008,"Deviation too small"
-9009,"Width too big"
-9010,"Width too small"
-9011,"Period too big"
-9012,"Period too small"
-9013,"Duty too big"
-9014,"Duty too small"
-9015,"Temperature too big"
-9016,"Temperature too small"
-9017,"High volt lvl equals low volt lvl
-9019,"High volt lvl below low volt lvl"
-9020,"Low volt lvl above high volt lvl"
-9021,"Outside amp x freq profile"
-9022,"Syntax error"
-9023,"Number too big"
-9024,"Reached upper boundary"
-9025,"Reached lower boundary"
-9026,"Up range required"
-9027,"Down range required"
-9028,"No more ranges"
```

-9029,"Top of range"
-9030,"Bottom of range"
-9031,"Maximum value"
-9032,"Minimum value"
-9033,"Illegal rep/width combination"
-9034,"Illegal duty/width combination"
-9036, "No calibration for this function"
-9037,"THERMAL limit: reduced output"
-9038,"Printer is not responding"
-9039, "Printer out of paper"
-9040,"Invalid test number"
-9041,"Invalid loop counter"
-9042,"Illegal offset"
-9043,"No more failures to view"
-9044,"No more tests to execute"
-9045, "Nominal Resistance too big"
-9046, "Nominal Resistance too small"
-9047, "Maximum positive phase angle"
-9048,"Maximum negative phase angle"
-9049,"Cannot change: $\Phi$ ref out still selected"
-9050,"Cannot change: delta $\Phi$ still selected"
-9051,"Freq too big: 1 kHz max when $\Phi$ ref out active"
-9052,"Freq too big: 1 kHz max when delta $\Phi$ active"
-9053,"Previous test point failed: exceeded UUT spec. limits"
-9054,"Target factor is corrupt - select defaults"
-9055,"Only a restricted setting allowed"
-9056,"No frequency change allowed"
-9057, "Time marker period too big"
-9058,"Time marker period too small" -9059,"Invalid no. of divisions"

ALWAYS: record the total message content for possible use by the Service Center.
-9060,"Invalid V/div value"
-9061,"Illegal V/div, no. of div's combination"
-9062,"-ve edge not available with 1 M 335 load"
-9063, "Frequency too big for $1 \mathrm{M} \backslash 352$ load"
-9064,"Amplitude too big for $50 \backslash 352$ load"
-9065,"Frequency too big for present amplitude"
-9066,"Entered number exceeds limits"
-9067, "Search procedure - NO Test point"
-9068,"Search procedure - Function ID Expected"
-9069,"Harmonic frequency cannot exceed $3000 \mathrm{~Hz} "$
-9070,"Cannot change: phase too high"
-9070,"Cannot change: phase at 0\370"
-9071,"Cannot change: phase at \36190\370"
-9072,"Cannot change: phase at \361180\370"
-9073,"Cannot change: aux channel at zero"

## 8.A.2.2.8 Device-Dependent Errors Reported only Remotely via the IEEE-488 Interface

The error list for remote operations, which are not reported on the front panel screen, is given below:
-300,"Device specific error"
-330,"Configuration memory lost"
-312,"PUD memory lost"
-315,"Selftest failed"

## 8.A.2.2.9 Device-Dependent Errors Reported both Locally and Remotely

Errors are reported both on the front panel screen and via the IEEE-488 interface. Note that the locally-presented error message will not include the error number.

## General

1001,"Overload of power amp"
1002, "Over temperature"
1003,"Over compliance"
1006, "Overload of HV power supply"
1008, "Overload of output clamp"
1009, "MULTIPLE analogue fail flags"
1010, "Softkey label too long"
1011,"Confirm with ON"
1014,"Power output not allowed with 9105 work-mat"
1020,"Unknown keycode"
5010,"Priority OFF received"

## Calibration

4001,"Corrupt factors:- substitution"
4003,"Password incorrect"
4004,"Cal switch not enabled"
4005,"Factory password incorrect"
4006,"Correction block:- invalid"
4007, "Amplitude outside limits"


#### Abstract

4008,"Cal is password protected" 4009,"Frequency outside limits" 4024, "Failed to save (act) factor" 4025,"Failed to save (tgt) factor" 4026, "Failed to save (frq) factor" 4027,"Failed to save (R-eqV) factor" 4028,"Limits: R-eqV" 4029,"Failed to save (act) R-dervd" 4030,"Failed to save (tgt) R-dervd" 4031,"Failed to save (act) C-ref" 4032,"Failed to save (tgt) C-ref" 4033,"Failed to save (frq) C-ref" 4034,"Failed to save (C-eqv) factor 4034,"Failed to save (C-eqv) factor 4035,"Failed to save (cjc) factor" 4051, "Cap meas no 1st reading" 4052,"Cap meas no 2 nd reading" 4053,"Cap meas outside limits" 4055,"Corrupt cal factors" 4056,"Failed --------" 4057,"Corrupt selfcal factor" 4058,"Corrupt res ref factor" 4058,"Corrupt res. ref. factor" 4059, Corrupt cold junc diff factor"


Continued Overleaf

## Calibration (continued)

4060,"Corrupt offset DAC factor"
4061,"Using default DAC factors"
-7021,"Temperature must be in the range 00.00 - $50.00^{\prime \prime}$
-7022,"A valid Cold Junction temperature is required"

## Characterization

501,"Limits: main DAC gain"
4502,"Limits: composite DAC zero"
4503,"Limits: trim DAC gain"
4504,"Limits: offset DAC gain"
4505,"Limits: main DAC linearity"
4506, "Failed to write to flash RAM"
4507,"Limits: gain of 2 zero"
4508," Limits: gain of 0.5 zero"
4509,"Limits: DAC output zero"
4510,"Limits: 0.75 buffer zero"
4511,"Limits: DAC positive zero"
4512,"Limits: DAC negative zero"
4513,"Limits: DAC positive FR"
514 "Jimits: DAC negative FR"
514, Limits: DAC negative FR
515,"Limits: DAC \361FR ratio"
516,"Limits: DAC max - DAC min"
517,"Limits: resistor ratios"
4518,"Failed to save resistor ratios"
4519, "Limits: main DAC offset"
4520,"Failed to save impedance offset"
521,"LF AC Chrctn impossible: default set"
4522,"Excess LF AC flatness"
523,"Failed to save DDS lfac error"
4524,"Limits: Gain of 1 zero"
4525,"Limits: PWR DAC gain"
4526, "Limits: PWR trim DAC gain"
4527,"Limits: PWR DAC zero"
4528,"Limits: PWR DAC linearity"

## DAC Compensation

5001,"Corrupt main DAC gain"
5002,"Corrupt trim DAC gain"
5003, "Corrupt composite DAC zero"
5004,"Corrupt lookup table"
5005, "Corrupt Vmax. Vmin"
5006,"Corrupt +ve zero (DAC)" 5007,"Corrupt -ve zero (DAC)" 5008,"Corrupt polarity gain (DAC)" 5009,"Corrupt LFAC correction"
5011, "Gain request limited"
5012,"Failed to read from flash RAM"

## Cold Junction Compensation

5020,"Invalid CJC measurement -
default to $25^{\circ} \mathrm{C}$
5021,"Temperature table: no entry found"

## Configuration

4002,"Failed to save configuration"
-7003,"Day entry is not a valid number"
-7004,"Day separator is incorrect"
-7005, "Month entry is not a valid number" -7006, "Month separator is incorrect"
-7007,"Century entry is not a valid number"
-7008,"Year entry is not a valid number" -7009, "Year separator is incorrect"
-7010, "Month entry is not a valid month"
-7011,"Day entry is not a valid day"
-7012,"Hours entry is not a valid number"
-7013,"Minutes entry is not a valid number"
-7014,"Entry does not give a valid time setting"
-7017, "Safety Voltage must be in the range $10.00 \mathrm{~V}-110.000 \mathrm{~V}$ "
-7031,"The transducer scaling factor must be between 45 uV and 10 mV

## Section $9 \quad$ Verifying the Model 9100 Specification

### 9.1 About Section 9

Section 9 introduces the principles involved in verification of Model 9100 performance, including the issue of traceability.

### 9.2 Need for Verification

### 9.2.1 Factory Calibration and Traceability

Factory calibration of the Model 9100 ensures full traceability up to and including National Standards. Its traceable accuracy figures are quoted in the specifications given in Section 7, and all relate to a 1-year calibration interval These figures include all calibration uncertainties, including those of National Standards, and therefore constitute absolute accuracies.

### 9.2.2 Verification on Receipt from the Factory

Each 9100 is despatched from Fluke with a Certificate of Calibration, which gives detailed results of its pre-shipment performance. However, many organizations wish to confim that all instruments perform within published specifications, on receipt from their manufacturer. This not only confirms the value of their purchase, but also gives a confident starting point for subsequent instrument use.

Such verification is only possible, however, if the user's organization is in possession of suitable standards equipment, of the necessary traceable accuracy. In the absence of such standards, users may rely on external support organizations to verify the 9100's accuracy, probably also using these organizations to recalibrate the unit at appropriate intervals. For users who wish to carry out verification or recalibration of a 9100 on-site, without having to ship the 9100 to a calibration laboratory, the Fluke Model 4950 Multifunction Transfer Standard can be used automatically to calibrate and/or verify the 9100's accuracy using the PC-based Model 4950 MTS Control Software.

### 9.2.3 Verification after User-Calibration

When a 9100 is calibrated against calibration standards as detailed in Section 10 of this handbook, its pre-calibration and post-calibration performance ateach calibration point can be easily assessed as part of the calibration procedure. However, some organizations may prefer to carry out separate pre- and post-calibration performance verifications.

### 9.3 Equipment Requirements

As stated earlier, the calibration standards required to verify that a 9100 is within its published accuracy specifications must possess the necessary traceable accuracy. The generally accepted minimum test uncertainty ratio (the ratio between the accuracy of the 9100 at a verification point and the absolute accuracy of the standard used to verify it at that point) is $3: 1$, which must apply at all points being used to verify the 9100 's accuracy.

Also note that the measuring equipment must operate within the optimum output conditions of the 9100, as defined in the accuracy tables given in Section 7 of this handbook - i.e. the measurement equipment should be able to operate within the relevant 9100's compliance limits so that no additional accuracy figures have to be taken into account.

### 9.4 Interconnections

The form of interconnection required to ensure optimum conditions for verification measurements will depend on the 9100 function being verified and on the measuring equipment connected to the 9100's terminals. For functions which can be directly calibrated (DC and AC Voltage, DC and AC Current, Resistance and Capacitance) suitable connections are illustrated in the appropriate part of Section 10: Calibrating the 9100, in this handbook.

### 9.5 Verification Points

The accuracy specifications detailed in Section 7 of this handbook cover the full range of output values which can be generated by the 9100 , and its accuracy can therefore be verified against the specification at any number of points in these output ranges.
As the actual verification points chosen will depend to a large extent on the traceable accuracy of the measuring equipment used to measure the 9100's outputs, it is beyond the scope of this handbook to define a precise set of verification points for each of the 9100's functions. However, when selecting verification points the following guidelines should be followed:-

1) Where the 9100 's specification is broken up into several different output amplitude and/or frequency bands, verification points should be close to the top and bottom of these spans.

For 9100 functions which can be directly calibrated (DC and AC Voltage, DC and AC Current, Resistance and Capacitance) the default or recommended 'calibration targets' detailed in Section 10: Calibrating the 9100 can be used as suitable verification points.
2) Capacitance bridges are not generally suited to verifying the 9100 's capacitance outputs for a number of reasons. Firstly, capacitance bridges are too inaccurate at the extremes of frequency and impedance required to verify the full range of 9100 capacitance outputs ( 0.5 nF to 40 mF ). Secondly, bridges often ground one of the 9100's output terminals, which prevents the calibrator from operating correctly (the 9100 is designed to drive fully floating loads.) A suitable transfer measurement technique, using a set of standard capacitors and a floating capacitance meter, is detailed in the capacitance calibration sub-section of Section 10: Calibrating the Model 9100, in this handbook.

### 9.6 Calculating Absolute Specification Limits

For each chosen verification point it will be necessary to calculate absolute measurement limits which can be used to judge whether or not the 9100 is performing within its specification. As mentioned earlier, the accuracy specifications detailed in Section 7 of this handbook are absolute accuracies which incorporate all the uncertainties involved in calibrating the 9100 up to and including those of National Standards.

If verification results are to be at all meaningful, the measuring equipment which is used to verify the 9100 's accuracy must have separate traceability to the same National Standards, and the uncertainties involved in this traceability must be taken into account when determining the absolute verification limits required at the chosen verification points.
To ensure that worst-case conditions are taken into account, these verification limits should be calculated as follows (an example is given alongside each step to aid understanding):-

1. By referring to the appropriate function table in Section 7 of this manual, locate the 9100 output band in which the required verification point is located. Note the accuracy of the 9100 in this band, which is given in the form of a fraction of output value plus a floor (offset) value.
2. Multiply the verification point value by the fraction of Output figure in the specification.
3. Add the Floor figure in the specification to the result obtained in step (2), taking into account any 'engineering unit' multiplier such as $\mu\left(\times 10^{-6}\right), \mathrm{m}\left(\times 10^{-3}\right)$ etc. specified in the Floor value. This will give you a combined Fraction of Output + Floor uncertainty specification for the 9100 at the verification point value.
4. Add the result obtained in step (3) to the verification point value to obtain a 'high' output limit for the 9100 output.
5. Subtract the result obtained in step (3) from the verification point value to obtain a 'low' output limit for the 9100 output.

Example: Foraverification point value of 2 V , the 9100 accuracy specification is:$0.006 \%+41.6 \mu \mathrm{~V}$

$$
\underline{2 \times 0.006}=0.00012
$$

100
$0.00012+41.6 \times 10^{-6}$ $=0.0001616$

Provided that the actual output lies between the high and low limits calculated in steps (4) and (5) above, the 9100 will be within its published accuracy specification. However, in deciding on test limits applicable to the verification measurement you must also take into account the accuracy with which the measuring equipment can measure this output.

For example, if the 9100's 2V DC Voltage output was actually 2.0001616 V , it would still be within its accuracy specification. However, a voltmeter with a traceable accuracy of 10 ppm at 2 V could measure this value as 2.0001816 V , leading you to believe that the 9100 was outside its specified accuracy. To obtain true limits for the verification measurements you must therefore add the total uncertainty of the measuring equipment to limits obtained in steps (4) and (5) above as follows:
6. Determine the traceable absolute accuracy (including $\mid$ For a voltmeter traceable to National Standards uncertainties) of the measuring equipment at the verification point value.
7. Add the figure determined in step (6) to the high output limit obtained in step (4) to obtain the high verification limit.
8. Subtract the figure determined in step (6) from the low output limit obtained in step (5) to obtain the low verification limit.
9. Check that the reading obtained on the measuring equipment, when it is used to measure the 9100 output, is between the high and low verification limits obtained in steps (7) and (8) above.
10. To be absolutely certain that the 9100 is within its specification limits, then the uncertainty of the measuring equipment must be totally discounted. This means that in step (7), when we added the measuring equipment's accuracy derived in step (6), we must now subtract it [and in step (8), it must be added].

Note: At step (9), we can say that the 9100 achieves its accuracy specification, but with 2 times the measuring equipment uncertainty.
At step (10), we have removed the 2 -times uncertainty, so if its reading is within the limits, the 9100 achieves $100 \%$ accuracy specification.

10ppm, absolute accuracy at 2 V is 0.00002 V .
$2.0001616+0.00002$
$=2.0001816$
1.9998384-0.00002
$=1.9998184$

If the reading on the voltmeter is less than 1.9998184 V or greater than 2.0001816 V then the 9100 is outside its accuracy specification at 2 V .
2.0001616-0.00002
$=2.0001416$
$1.9998384+0.00002$
$=1.9998584$
If the reading on the voltmeter is greater than 1.9998584 V or less than 2.0001416 V then the 9100 is within its accuracy specification at 2 V .

## Section 10 Calibrating the Model 9100

### 10.1 About Section 10

Section 10 outlines general procedures for calibrating the Model 9100. In it you will find the recommended calibration methods, details of the parameters that require calibration and the procedures needed to calibrate them.

This section is divided into the following sub-sections:
10.2 The Model 9100's Calibration Mode

Selection of Calibration Mode, Special Calibration and Standard Calibration.
10.3 Standard Calibration - Basic Sequences

Using the function, target selection and calibrate screens
10.4 Front-panel Calibration of Model 9100 Functions

Lists of calibration points, equipment requirements, interconnections, procedures and recording for all Functions requiring calibration.
10.5 Remote Calibration of the Model 9100 via the IEEE-488 Interface The Model 4950 MTS System.

### 10.2 The Model 9100 Calibration Mode

### 10.2.1 Introduction

This section is a guide to the use of the Model 9100's Calibration Mode. The following topics are covered:

| 10.2.2 | Mode Selection |
| :--- | :--- |
|  | 10.2 .2 .1 |
|  | 'Mode' Key |
|  | 10.2 .2 .2 | 'Mode Selection' Screen

10.2.3 Selection of Calibration Mode
10.2.3.1 Calibration Enable Switch
10.2.3.2 Password
10.2.3.3 Calibration Mode Display
10.2.3.4 Calibration Mode Screen Softkeys
10.2.4 Special Calibration
10.2.4.1 Selecting Special Calibration
10.2.4.2 The Characterise DAC Screen Display
10.2.4.3 Characterise DAC Errors
10.2.5 Cold Junction Calibration $\quad$ Final Width $=215 \mathrm{~mm}$
10.2.5.1 Rationale
10.2.5.2 Selecting COLD JUNC CALIB
10.2.5.3 Entering Temperature Values
10.2.5.4 CJC Pod Identification
10.2.5.5 Equipment Requirements
10.2.5.6 Error Reduction
0.2.5.7 Cold Junction Calibration Procedure
10.2.6 Standard Calibration
10.2.6.1 Function Selection
10.2.6.2 Cal Mode Function Screens
10.2.6.3 Hardware Configurations
10.2.7 Overview of Calibration Operations

Selection of any one of the Model 9100's five operating 'Modes' is enabled by pressing the 'Mode' key at the bottom right of the 'CALIBRATION SYSTEM' key panel. This results in display of the mode selection screen shown below.


The Calibration Enable DIP-switch is accessible, using a small screwdriver, through a recess on the Model 9100's rear panel.

Cal Key Disabled With the Calibration Enable switch in the 'DISABLE' position, any attempt to select Calibration mode by pressing the 'CALIB' screen softkey will result in the screen prompt "Calibration switch not enabled!" being displayed, and access to the calibration mode will be denied.

Cal Key Enabled With the Calibration Enable switch in the 'ENABLE' position, pressing the 'CALIB' screen key will result in the 'Password Entry for Calibration' user prompt screen being displayed.

## Password Entry

## For Calibration

Enter your password: © © () () © ( )

### 10.2.3.2 Password

Before the Calibration mode menu screen can be displayed you must now enter a valid password using the Model 9100's alphanumeric keyboard. For information about the initial 'shipment' password, and about the method of changing this to a custom password, refer to Section 3.3.2.23 of the Model 9100 Universal Calibration System User's Handbook - Volume 1-Operation.
As each character in the password is entered, security code icons will appear on the screen as shown above. Once the correct password has been entered, pressing the ' $ل$ ' (Enter) key will result in the Calibration Mode menu screen being displayed. If the password is incorrect, the error message "PASSWORD INCORRECT" will be displayed and the security code character icons will disappear, enabling you to attempt correct password entry again.
The 'EXIT' screen softkey will take you back to the Mode Selection screen.

### 10.2.3.3 Calibration Mode Display

When Calibration mode has been successfully entered by setting the CAL ENABLE switch to the ENABLE position and entering the correct Password, the 'Calibration Mode' menu screen shown below will be displayed:

| Calibration Mode |
| :---: | :---: | :---: |

### 10.2.3.4 Calibration Mode Screen Softkeys

The following screen softkeys are active:-
Special Accesses the Special Calibration menu so that you can perform the 'Chse DAC' (Characterise Digital-to-Analog Converter) calibration operation, which must be performed immediately before carrying out routine recalibration of the Model 9100
COLD The Reference Junctions used in the Thermocouple Temperature function JUNC are housed in an external module, whose internal temperature is monitored automatically by the 9100 . This facility permits the monitor circuitry to be calibrated, while in use. The calibration is performed by measuring the temperature of the reference junctions externally, then entering the measured value via the front panel, or remotely via the IEEE-488 bus.
Factory Accesses 'factory-set' calibration operations which can only be entered use only by a special password. These calibration operations only need to be performed when the instrument is manufactured, or after certain types of repair have been carried out on it.
STD CAL Accesses the user control screens for routine external calibration of each Model 9100 function which can be calibrated.

### 10.2.4 Special Calibration

### 10.2.4.1 Selecting Special Calibration

Pressing the Special softkey in the Calibration Mode screen results in the Special Calibration screen shown below being displayed, in which the only active softkey is the one labelled Chse - DAC (Characterise DAC).


The Characterise DAC operation comprises a set of fully automatic internal adjustments which, using ratiometric techniques, calibrates resistor ratios and AC frequency responses. Chse-DAC also checks and calibrates the linearity of the Model 9100's 20-bit D/A converter which is used to set the amplitude of its analog output functions. These adjustments are only required immediately prior to routine Standard Calibration of the Model 9100 as detailed in subsequent sub-sections of this handbook.
CAUTION: Do not press the Chse - DAC softkey unless you are doing so as part of an authorized recalibration of the Model 9100. Although the internal adjustment operations which it initiates will not dramatically change the overall calibration of the instrument, they will introduce a very small 'artificial' step into its apparent drift performance. If your company maintains historical records on each calibrator's drift performance between calibrations (for example, for the purposes of statistical process control in a total quality management system) this artificial step would need to be determined and suitably recorded in these records. There are no performance advantages to be gained by performing the Characterise DAC operation other than when Standard Calibration of the Model 9100's functions is also performed.

### 10.2.4.2 The 'Characterise DAC' Screen Display

Listed below are the screen messages which will be displayed as the Characterise DAC operation proceeds, together with the associated internal operations which are performed:-

## Characterisation clear RAM Clears all existing calibration constants associated

 with the Characterise DAC operation.Characterisation polarity
Establishes a true zero for the DAC output.
Characterisation impedance
Establishes the true ratios of several resistive dividers which are required to produce certain Model 9100 outputs.

Characterisation LF AC flatness Establishes a flat frequency response in the Model 9100's direct digital synthesis of low frequency AC outputs.

## Characterisation DAC gains

followed by
Characterisation $\mathbf{n}=\mathbf{x x x x x}$
Measures the output of the DAC at over 4,000 different points and corrects any linearity errors detected. The displayed number 'n' represents the current test number.
When all Characterise DAC operations are complete (note that the entire process takes around 20 minutes), you will be returned to the Model 9100's Mode Selection screen.

### 10.2.4.3 'Characterise DAC' Errors

If for any reason the Model 9100 is unable to complete one or more of the Characterise DAC operations, error messages similar to that shown below will be displayed and default correction factors will be written to the Model 9100's non-volatile calibration memory.


Although these default correction factors will allow the Model 9100 to remain functional, you should not proceed with calibration until the cause of the error has been established and rectified. In most cases, occurrence of this type of error will mean that the Model 9100 has developed a fault, in which case you should consult your local Fluke Service Center for assistance. However, before doing so it is worth repeating the Characterise DAC process to make sure that the failure was 'real' and not caused by external influences such as a disturbance in the Model 9100's line supply.

### 10.2.5 Cold Junction Calibration

10.2.5.1 Rationale

The Cold Reference Junctions used in the Thermocouple Temperature function are housed in an external module ('CJC Pod'), whose internal temperature is monitored automatically by the host 9100 . A CJC pod is calibrated for use with a particular host 9100 unit, and is not interchangeable between 9100 s unless a recalibration is carried out. The calibration is performed by measuring the temperature of the reference junctions externally, then entering the measured value via the front panel, or remotely via the IEEE488 bus

### 10.2.5.2 Selecting COLD JUNC CALIB

Pressing the COLD JUNC CALIB softkey in the Calibration Mode screen presents the CJ Temperature Cal screen, with two active screen keys: EXIT and CALIB:

## CJ Temperature CaI

Use numeric keys to enter the temperature of the cold junction before calibration

| ToDars date |  |  |  |
| :---: | :---: | :---: | :---: |
| EXIT |  |  | C ALIB |

EXIT returns to the Calibration Mode screen.
CALIB performs the calibration, as part of the procedure at paras 10.2.5.7.

### 10.2.5.3 Entering Temperature Values

While performing the calibration, there are three major errors which could give rise to screen messages. These appear in a rectangle above the text already on the screen:

- If the 'CALIB' screen key is pressed before a numeric value has been fully entered (including pressing the $\lrcorner$ key), then the following message will appear:

> A valid Cold Junction temperature is reauireo

- If the 'CALIB' screen key is pressed after entering a numeric value, but when the Reference Junction module is not plugged in, then the following message will appear:

$$
\begin{aligned}
& \text { nvalid CJC me } \\
& \text { default to } 25^{\circ} \mathrm{C}
\end{aligned}
$$

- If the 'CALIB' screen key is pressed after entering a numeric value which is outside the range $0-50$, then the following message will appear:

Temperature must be within
the range ØØ. $\varnothing \varnothing-5 \varnothing . \varnothing \varnothing$

### 10.2.5.4 CJC Pod Identification

Because a CJC pod is calibrated together with a particular host 9100 unit, and the pod's correction data is held in the host's non-volatile memory, traceability is maintained only when the pod is used with that host. Where an organisation holds more than one 9100 and pod, there is a need to identify each pod's host 9100 .
To encourage user organisations to register the association of each pod with a particular 9100 , the label affixed to each pod has the serial number of the pod, plus a blank space for recording the serial number of the 9100 with which it is calibrated.
Part of the calibration procedure in paras 10.2.5.7, gives an instruction to record the serial number of the host 9100 in the space on the label.

### 10.2.5.5 Equipment Requirements

To calibrate using front panel controls, the procedure requires a traceably-calibrated Resistance Temperature Detector (RTD) equipped with a special $0.385 \Omega /{ }^{\circ} \mathrm{C}$, 3 mm diameter Platinum Resistance Thermometer (PRT Sensor Assembly - Fluke part no. 401233 - traceably calibrated to an accuracy of $\pm 10 \mathrm{~m} \Omega$ at $100 \Omega$ ). The test uncertainty ratio of this combination over the 9100 RTD function specification must be at least 3:1, at the required calibration temperature between $0^{\circ} \mathrm{C}$ and $50^{\circ} \mathrm{C}$.
Alternatively, the same PRT can be used with a DMM (e.g: Fluke Model 1271), whose $100 \Omega$ or $1 \mathrm{k} \Omega$ range is traceably-calibrated at $100 \Omega$ to an accuracy of better than $0.013 \Omega$. The source current must be limited to $1 \mathrm{~mA} \pm 20 \%$ to avoid self-heating errors in the PRT. A formula for conversion from resistance to temperature is given with the procedure in paras. 10.2.5.7.
For remote calibration, the Fluke Model 4950 Multifunction Transfer Standard can be used, in conjunction with the MTS Control Software, to support this procedure automatically.

### 10.2.5.6 Error Reduction

Any errors in taking external measurements of the Reference Junction temperature can be attributed to environmental conditions and/or bad practice. To minimize these errors the following techniques should be implemented:

- Minimize all handling of the module, PRT element and leads, hence avoiding variations of temperature.
- Throughout all measurements shield the Reference Junction module from draughts, especially from fans in the vicinity.
- Before recording any results, be patient and allow the readings to stabilize.


### 10.2.5.7 Cold Junction Calibration Procedure

1. Test Setup Set up the calibration equipment as shown in Fig. 10.2.5.1, and allow to stabilize thermally for 1 hour, to eliminate any effects of being located at other temperatures.
2. 9100 On the Calibration Mode screen, select 'COLD JUNC CALIB' to see the CJ Temperature Cal screen.
Operation (3) applies only when an RTD is being used for temperature measurement:
3. RTD Take measurements of the temperature until the readings have settled, then record the final reading.
Operations ( 4 \& 5) apply only when a DMM is being used for resistance measurement:
4. DMM Take measurements of the PRT resistance until the readings have settled, then record the final reading.
5. DMM Reading Use the following formula to calculate the temperature of the PRT: PRT Temp. $\left({ }^{\circ} \mathrm{C}\right)=\underline{(\mathrm{C}-\mathrm{A}) \mathrm{R}-(\mathrm{BC}+\mathrm{DA})}$

Where: $\quad \mathrm{A}=$ Actual Temperature $\left({ }^{\circ} \mathrm{C}\right)$ of the PRT nominal $0^{\circ} \mathrm{C}$ calibration point;
$B=$ Actual calibrated resistance at temperature 'A';
$\mathrm{C}=$ Actual Temperature $\left({ }^{\circ} \mathrm{C}\right)$ of the PRT nominal upper calibration point
$D=$ Actual calibrated resistance at temperature ' C '.
$R=$ Measured resistance value recorded in operation (4), above.
6. 9100
a. Use the numeric keys to enter the resulting Reference Junction temperature (the number of degrees Celsius to two places of decimals). The numbers will appear inside a rectangle at the bottom of the screen.
b. Press the $\downarrow$ key. The entered number will remain, but the rectangle will disappear.
c. Immediately press the CALIB screen key to perform the calibration.
7. RTD/DMM If the PRT temperature has changed by $0.03^{\circ} \mathrm{C}$ or more (DMM reading by more than $0.01 \Omega$ ) while calculating/entering the PRT temperature and pressing the CALIB key, repeat operations (5), (6), and this operation (7).
8. 9100 Press the EXIT screen key to return to the Calibration Mode screen.
9. CJC Pod Ensure that the correct 9100 serial number is written on the pod identification label. If not, erase the old number and write in the correct number. Also ensure that any other relevant records reflect the 9100/pod association.


Pressing the 'STD CAL' screen softkey displays the DC Voltage CAL mode function screen shown below, which always appears when you first enter Standard Calibration.


If you wish to calibrate other functions which are available for user-calibration, they can be selected in the same way as for normal operation - i.e. Voltage, Current and Resistance are selected simply by pressing their corresponding front-panel push-button, AC Voltage is selected from the DC Voltage function screen, and Capacitance is selected via the Aux push-button and Auxiliary Function menu screen (see Section 4 of the Model 9100 Universal Calibration System User's Handbook - Volume 1-Operation.)
Note that the Model 9100's Frequency, Conductance, Temperature and Logic functions cannot be externally calibrated (they are either derived directly from functions that can be calibrated or are calibrated 'for life' during manufacture). Attempting to select these functions while the Model 9100 is in CAL mode will result in an error message being displayed:-

No calibration for this function

### 10.2.6.2 Cal Mode Function Screens

Output-value control in the CAL mode of each function screen is essentially the same as for normal operation of the function. For example, the $\mathbf{x 1 0}$ and $\div \mathbf{1 0}$ softkeys respectively multiply and divide the currently displayed output value by 10 , the $\pm$ key changes the polarity of the output, and the ZERO key sets the output to zero. There is no 'Deviation ( $\Delta \%$ ) or 'Offset' ( $\Delta \mathbf{V}, \Delta \Omega$ etc.) key, but there is a new softkey, which appears only in CAL mode, labelled TARGET
In CAL mode, the purpose of the function screens is simply to allow you to set the 9100 into the various 'hardware configurations' required during calibration.

### 10.2.6.3 'Hardware Configurations'

Although all functions in the 9100 appear to the operator to have a single continuous range which covers the entire span of output values from the lowest value to the highest value (for example, for DC Voltage from -1050 V to +1050 V ), the 9100 has internal devices such as voltage dividers and power amplifiers which must be switched in and out of its circuitry to achieve some parts of this total span. As each of these circuits is switched in or out, the 'hardware configuration' of 9100 therefore changes.

Because each of these circuits also introduces slight offset and gain errors into the 9100 output, these errors must be compensated in order to maintain the 9100's very high level of performance. Calibration of the 9100 allows the offset and gain errors associated with each hardware configuration' to be determined, so that they can be digitally compensated for by the instrument's embedded control microprocessor. The microprocessor does this by applying digital correction factors to the output value selected by the operator, so that the 9100's actual analog output accurately matches the selected value. The result is a highly accurate and linear output response across each function's entire output span.
Individual 'hardware configurations' are calibrated by accurately measuring their analog outputs at two or more points using a higher order calibration standard (for example, a long scale length 'standards laboratory' digital multimeter). In most cases these 'target calibration values' are values close to the negative and positive extremes of the hardware configuration's output capability (for example at -1000 V and +1000 V for the DC Voltage function when the power amplifier is switched in.)

### 10.2.7 Overview of Calibration Operations

In general, calibration of each of the 9100 's 'hardware configurations' can be broken down into three distinct stages as follows:-

1) Selection of the required 'hardware configuration'
2) Selection of two or more 'target' values at which this hardware configuration will be calibrated.
3) Determination of the 9100's output error at each of these target values.

As mentioned earlier, the introductory function screen allows you to select the correct hardware configuration.

Pressing the TARGET softkey transfers you to the target selection screen where you can opt to use Fluke's recommended target calibration values or the target values used during the last calibration.

Selecting one of the target values displayed in the target selection screen (by pressing its corresponding Factor softkey) transfers you to the 'calibrate' screen, where you can optionally alter the target value before measuring the output error and generating a compensating correction factor.

These three stages are described in more detail in Section 10.3, while descriptions of the calibration sequences for each individual function are provided in Section 10.4.
The flow chart shown opposite summarizes the operator actions needed to enter Calibration mode, and to then select an appropriate function for calibration.


Fig. 10.2.2 Access to Functions in Calibration Mode

## 10.3 <br> Standard Calibration - Basic Sequences

This sub-section describes in more detail the main processes involved when calibrating each of the Model 9100's 'hardware configurations' from the instrument's front panel.
The following topics are covered:
10.3.1 Introduction
10.3.1.1 Aim of Calibration
10.3.1.2 General Calibration Process
10.3.2 Selecting Hardware Configurations
10.3.3 Selecting Target Calibration Values
10.3.3.1 The Target Selection Screen
10.3.3.2 Using the Saved Calibration Targets
10.3.3.3 Using the Default Calibration Targets
10.3.4 Calibrating the Model 9100 at Target Values
10.3.4.1 The Calibration Screen
10.3.4.2 Changing the Target Value
10.3.4.3 Determining the Output Error at the Selected Target Value
10.3.4.4 Calibration Errors
10.3.5 Standard Calibration of AC Functions
10.3.5.1 Output Frequency Synthesis
10.3.5.2 Changing the Output Frequency of Target Calibration Points
10.3.6 Exit from Calibration - Cal Date and Cal Due Date
10.3.6.1 Exit: Mode Key - Warning Screen
10.3.6.2 Exit Only
10.3.6.3 Update the Date Stamp on a Certificate
10.3.6.4 Setting the Cal Due Date and Advance Warning Period

### 10.3.1 <br> Introduction

10.3.1.1 Aim of Calibration

The aim of calibrating the Model 9100 Universal calibrator is to determine the accuracy of its outputs, and if necessary adjust them so that they are within specification. If this calibration is to be traceable, then the 9100's outputs must be compared with calibration standards whose higher accuracy ('Test Uncertainty Ratio' at least $3: 1$ with respect to the 9100) has been traceably calibrated to National or International Standards.

### 10.3.1.2 General Calibration Process

As mentioned earlier in Section 10.2, calibrating each of the 9100's functions can be broken down into three distinct stages as follows:

1) Select the required 'hardware configuration'.
2) Select 'target' values at which this hardware configuration will be calibrated.
3) Determine the 9100 's output error at each of these target values, and generate a suitable compensating correction factor.
This sub-section 10.3 describes the general process of calibrating the 9100 using frontpanel controls.
To demonstrate this process, the following description uses, as an example, the 9100's DC Voltage hardware configuration which generates output voltages in the range -3.20000V to -0.32001 V and from +0.32001 V to +3.20000 V . This hardware configuration requires two target-value calibration points, and two associated correction factors. The factors are stored in non-volatile memory, and subsequently used to correct all outputs which employ the hardware configuration.

We will start by assuming that the 'Cal' mode of the DC Voltage function has been selected as described in Section 10.2. of this handbook. This presents a Cal mode function screen, similar to that illustrated opposite.


### 10.3.2 <br> Selecting Hardware Configurations

For a given function, setting the 9100 output value selects the relevant hardware configuration which will generate the required span of the function's total output range. For example, the total output range in DC Voltage is generated using five separate hardware configurations that generate the following spans:

| 1: | zero | to | $\pm 320.000 \mathrm{mV}$ |
| :--- | :--- | :--- | :--- |
| 2: | $\pm 0.32001 \mathrm{~V}$ | to | $\pm 3.20000 \mathrm{~V}$ |
| 3: | $\pm 3.2001 \mathrm{~V}$ | to | $\pm 32.0000 \mathrm{~V}$ |
| 4: | $\pm 32.001 \mathrm{~V}$ | to | $\pm 320.000 \mathrm{~V}$ |
| 5: | $\pm 320.01 \mathrm{~V}$ | to | $\pm 100000 \mathrm{~V}$ |

Hence hardware configuration (1) can be selected by setting the output amplitude to any value in the range zero to $\pm 320 \mathrm{mV}$, hardware configuration (2) by setting the output to any value in the range -3.20000 V to -0.32001 V or +0.32001 V to +3.20000 V etc..
Output control in the 'Cal' mode of the function screens is exactly the same as in normal operation of the 9100 , being performed either by the digit edit method (cursor controls/ spinwheel), the direct edit method (numeric keypad), or by use of the $x 10, \div 10, \pm$ and ZERO softkeys. For further information see Section 3.4 of the Model 9100 Universal Calibration System User's Handbook - Volume 1 - Operation.

Suitable output values which can be used to establish all the required hardware configurations for each function are given in the detailed calibration procedures contained in Section 10.4 of this handbook. Note that the initial output value of +1.00000 V , provided in the introductory DC Voltage screen, puts the 9100 into the $\pm 0.32001 \mathrm{~V}$ to $\pm 3.20000 \mathrm{~V}$ hardware configuration.

### 10.3.3 Selecting Target Calibration Values

### 10.3.3.1 The Target Selection Screen

Once the correct hardware configuration has been established by setting the 9100 output control display to a suitable output value, pressing the TARGET softkey will present a 'target selection' screen similar to that shown below. This screen shows those target values at which the selected hardware configuration was last calibrated, indicated by the "SAVED CALIBRATION TARGETS" title positioned above these target values.


The currently-selected output value (and, in the case of AC Voltage or AC Current the frequency value) is compressed to smaller characters, and the digit cursor is deactivated so that these values cannot be changed while this screen is presented.
Depending on the selected function and hardware configuration, the screen can display up to four target values, numbered sequentially from top to bottom. Also, the screen will show the same number of 'Factor' keys, labelled 'Factor 1', 'Factor 2', 'Factor 3' etc., plus an additional screen key labelled 'DEFLT'

At this point you have two options in selecting the target calibration points for use in calibrating this hardware configuration.
You can:-

1) use the same target points (the Saved Calibration Targets) at which this hardware configuration was last calibrated - see Section 10.3.3.2.
2) use default target points which are pre-programmed into the Model 9100's firmware — see Section 10.3.3.3.

Note that the 9100 also provides you with a third option, which is to change the existing calibration targets to new values. However, this option only becomes available when you move on to the Calibration screen - see Section 10.3.4.
At any time you can return to the introductory function screen by re-pressing the TARGET softkey.

### 10.3.3.2 Using the Saved Calibration Targets

To use the 'Saved Calibration Targets' displayed on the target selection screen, there is no need to modify that screen. All that is required, to select one of the displayed target values, is to press the corresponding Factor softkey (i.e. the 'Factor 1' key to calibrate at target value one, the 'Factor 2' key to calibrate at target value two. etc..)
This will transfer you to a 'Calibrate' screen, which you can use to determine the output error, and correct it - see Section 10.3.4.
When you have finished calibrating one target value you will be returned to the function screen, from which you can:
either calibrate the remaining target values for the selected hardware configuration;
or select a new hardware configuration by changing the displayed output value.

### 10.3.3.3 Using the Default Calibration Targets

As mentioned earlier, the Model 9100 's firmware contains a complete set of recommended target calibration values, for every hardware configuration of every function that can be directly calibrated. If you wish to use these 'default' values, rather than the values at which your 9100 was previously calibrated (assuming that the 'saved' and 'default' values are different), simply press the DEFLT (Default) softkey which appears in the target selection screen. The Default Calibration Targets for the selected hardware configuration will be displayed as shown below. Re-pressing the DEFLT will take you back to the display of Saved Calibration Targets - i.e. the DEFLT key toggles between the Saved' and 'Default' sets of target values.


To select one of the displayed 'default' target values for calibration, press the corresponding Factor softkey (i.e. the 'Factor 1' key to calibrate at target value one, the 'Factor 2' key to calibrate at target value two. etc..)
This will transfer you to a Calibrate screen, in which you can determine the output error and correct it - see Section 10.3.4.

When you have finished calibrating one target value you will be returned to the function screen, from which you can:
either calibrate the remaining target values for the selected hardware configuration; or select a new hardware configuration by changing the displayed output value.

Before deciding to change from 'Saved' calibration target values back to the 'Default' target values, consider that there may be good reasons for choosing values other than the default values at the previous calibration. Your organization's calibration standards may be uniquely characterized at particular target values (for example, three series connected standard cells which provide a calibration point voltage of $\pm 3.05426 \mathrm{~V}$ rather than the default value of the $\pm 3.00000 \mathrm{~V}$ for the $\pm 0.32001 \mathrm{~V}$ to $\pm 3.20000 \mathrm{~V}$ DC Voltage hardware configuration). Changing the default target values back to $\pm 3.00000 \mathrm{~V}$ may reduce the usefulness of historical calibration records for this 9100 unit, if it normally uses $\pm 3.05426 \mathrm{~V}$ as the target value.


CAUTION: Do not press the CALIB softkey while using the Calibrate screen unless you are sure that you wish to perform an authorized recalibration of the selected hardware configuration at the selected target value. To prevent accidental calibrations taking place due to inadvertent use of the CALIB key, and for your own safety, it is best to carry out all hardware configuration, target value selection and initial use of the calibrate screen with the 9100 output OFF. If you accidentally press the CALIB key, or attempt a calibration without first turning the 9100 output on, the following error message will be shown:

## Output must be ON for CAL

Under output-off conditions, the existing, stored calibration corrections will remain unchanged.

### 10.3.4.2 Changing the Target Value

As mentioned earlier, in addition to selecting either:

- the previously-saved calibration target values or
- default calibration targets,
a new target value can be defined. This is achieved on the Calibrate screen, for the selected factor, by editing the target value.
To do this, first transfer cursor control to the target value displayed in the lower left of the screen by pressing the $\mathrm{Tab} \oplus 1$ key. (Note: the Tab $\oplus$ key moves the cursor between alternate fields, so that re-pressing it will return cursor control to the output amplitude control display.)
With the cursor on the displayed target value, you can now alter the target value using digit or direct edit employed in normal operation - (Model 9100 Universal Calibration System User's Handbook, Volume 1, Operation, Section 3, sub-section 3.4).
Note that although the $\mathbf{x 1 0}, \div \mathbf{1 0}$ and $\pm$ softkeys remain active, pressing them will always result in the error message:

Target too big or Target too small
being displayed, as they would move the value out of the permissible target range. Pressing the ZERO softkey will also produce this error message, unless the default target value is already zero (as would be the case, for example, for Factor 1 of the DC Voltage, 0 V to $\pm 320.000 \mathrm{mV}$ hardware configuration).

### 10.3.4.3 Determining the Output Error at the Selected Target Value

The output error of the 9100 is determined by connecting a suitable measuring instrument to the calibrator's front-panel terminals to measure the actual analog output value, then determining the difference between this measured value and the selected target value.
N.B. The chosen measuring instrument must have an absolute accuracy considerably better than the accuracy specification of the 9100. (For information on suitable measuring equipment see Appendix 10-A1 at the end of Section 10. in this handbook.)

The process of calibrating the 9100 will correct this output error. The procedure has 3 stages:

1. Set the displayed output value (output control value) to the target value by pressing the TRANSFR (Transfer) key, then turn the calibrator output ON.
2. Increment or decrement the calibrator output using the cursor controls and/or spinwheel until the externally measured value is equal to the target value displayed in the lower left corner of the 9100 screen.
3. Press the CALIB (Calibrate) screen key.

The 9100 reverts to show a function screen with the displayed output value equal to the target value, and both equal to the externally-measured output value (to within normal measurement errors; e.g. within noise limits). The 9100 is now calibrated at that Factor's target value, and the corresponding (digital) correction value has been stored in nonvolatile RAM.
This correction factor is derived from the amount that the output value had to be incremented or decremented in stage (2) of the calibration process, in order to obtain an external measurement equal to the target value (a measure of the output error before calibration).
In order to correct the full span of values generated by the hardware configuration, the calibration process is repeated for each of the configuration's 'Factors', and the corresponding corrections are stored. Subsequently, when in normal operation, the 9100 applies all the stored correction factors to the output in proportions determined by an internal algorithm; ensuring that the hardware configuration generates outputs which are all within the accuracy specification.

After a successful calibration of the 9100 at a target calibration value, the new target value will replace the corresponding old target value in the 'SAVEDCALIBRATIONFACTORS' display. Note that on the target selection screen the target value will change only if the new and the old target values were different.

### 10.3.4.4 Calibration Errors

In stage (2) of the calibration procedure, the output of the 9100 is incremented or decremented by the necessary amount to obtain a measured output equal to the target value. In the process, a condition may arise which prevents generation of a suitable correction factor, due to predefined internal limits for that 'Factor' being exceeded. If this is the case, the error message:

## Amplitude outside limits

will be displayed when you press the CALIB screen key, and the previously-stored calibration correction for this target value will remain unaltered.
The predefined limits, programmed into the 9100 firmware, are sufficiently wide to cope with all normal output errors likely to arise during recalibration. If the above error message appears, it will probably be due to one of two causes:-

1. the Model 9100 has developed a fault.
2. the measuring instrument has developed a fault, is incorrectly set up, or is incorrectly connected to the Model 9100's terminals.

The cause should be determined and rectified before proceeding.

### 10.3.5 Standard Calibration of AC Functions

Standard calibration of the AC Voltage and AC Current functions in the 9100 uses the same procedure as that described in Sections 10.3.1 to 10.3.4 of this section except that the frequency of the target calibration points must also be set.

### 10.3.5.1 Output Frequency Synthesis

The frequency of the Model 9100's AC Voltage and AC Current outputs is derived digitally from an internal reference frequency crystal, which is sufficiently stable for the output frequencies of these functions not to require any routine calibration throughout the lifetime of the instrument. Option 100 introduces an alternative, high-stability reference crystal.

### 10.3.5.2 Changing the Output Frequency of Target Calibration Points.

When you display target selection screens for AC functions (by pressing the TARGET screen key while in the Cal mode of the function screen), you will notice that the Saved Calibration Targets and Default Calibration Targets all include a target calibration point frequency. As an example, the default calibration targets for the AC Voltage 0.32001V to $3.20000 \mathrm{~V}, 0.0100 \mathrm{kHz}$ to 3.2000 kHz hardware range are illustrated in the screen shown below.


When you select one of these calibration points by pressing its corresponding Factor key, the target calibration point voltage and frequency will be displayed below the current output voltage and frequency settings as shown in the following screen illustration.


You should now set the current output voltage and frequency settings to the target values by pressing the TRANSFR softkey, as you would when calibrating any other function.
If you now wish to change the calibration point frequency, this must be done by directly editing the output frequency setting, not by editing the displayed target frequency.
To do this you must first transfer cursor control to the displayed output frequency setting by pressing the Tab $\uparrow$ key. (Note: depending on the current position of the digit cursor you may need to press the $\mathrm{Tab} \oplus$ key one or two times to shift it to the output frequency setting.) You can now alter the frequency setting using the same digit edit (cursor controls/spinwheel) method or direct edit (numeric keypad) method used to change frequency values in normal operation of the Model 9100 - see Section 3.4 of the Model 9100 Universal Calibration System User's Handbook - Volume 1 - Operation.

Note that although the $\mathbf{x 1 0}$ and $\div \mathbf{1 0}$ softkeys remain active, pressing them will always result in the error message:

Frequency too big or Frequency too small
being displayed, as they would move the target frequency out of the permissible range.
You can now continue with the calibration as detailed in Section 10.3.4.3.-stage 2.

Once all calibration has been completed, you will wish to return to normal operation, which requires a short 'exit' process. The normal means of exit from Calibration mode is to press the Mode key on the right of the front panel. When you do this, the 9100 will present a Warning screen to indicate that the 9100 calibration may have changed, and to offer you the following options:

- altering the date-stamp on any directly-printed results certificate (or not),
- entering or altering the calibration due date,
- indicate the advance warning period required before the cal due date.

The following paragraphs show the screens, required actions and consequences.

### 10.3.6.1 Exit: Mode Key — Warning Screen

To exit from Calibration, press the Mode key on the right of the front panel. The 9100 will present a 'Warning' display on the screen:

## WARNING

The calibration of the 9100 may now have changed, if you wish to date stamp the cal or alter the cal due date, select one of the softkeys below
The stored cal date is:
25/01/1995
The stored due date is:
Doavs date


### 10.3.6.2 Exit Only

If you do not wish to alter the date-stamp, and do not wish to alter the cal due date or its advance warning period, press the EXIT key. This terminates the calibration session, and you will be returned to the Mode Selection screen to select another mode.

### 10.3.6.3 Update the Date Stamp on a Certificate

If you wish to update the date stamp to today's date, press the CAL DATE key The 9100 presents the Cal Date screen $\rightarrow$ The alpha-numeric keypad is locked out. If updating the date-stamp is all that is required, without altering the due date, press the EXIT screen key to return to the Mode Selection screen.

## CAL DATE

The calibration date of the 9100 has now been set to

25/01/1995

### 10.3.6.4 Setting the Cal Due Date and Advance Warning Period

N.B. If these parameters are not altered, those parameters which are already stored will be presented on any directly-printed certificate.
To alter the CAL DUE date, press the CAL DUE DATE key. The 9100 will present the CAL DUE DATE screen $\rightarrow$ This screen also displays the stored CAL DATE as a reminder when calculating the cal due date.

If you change your mind and do not wish to update the CAL DUE DATE, press the EXIT screen key.


## Setting the Cal Due Date

To set a new CAL DUE DATE, use the alpha-numeric keypad to type in the required due date, then press the Enter $( \lrcorner)$ key. Note that the screen presentation is couched in the 'DATE TIME' format set in Configuration mode, and should be observed when entering he date, otherwise the advance warning period could be calculated from an incorrect date! - refer to User's Handbook Volume 1, Section 3, paras 3.3.2.10.

## Advance Warning Period

In order to inform a user that the future due date for calibration is approaching, the 9100 will place a warning on the screen, starting at a period of time before the due date. During normal use, a suitable message will appear in a comment box at the top of the screen, after the warning is due, on three types of occasion:

- Every time the 9100 is powered on;
- Every function change into DC Voltage function;
- Every function change into AC Voltage function.


## Setting the Advance Warning Period

During the exit process from Calibration mode, the present setting of the number of days in advance of the due date appears on the screen above, shown highlighted against one of the right screen keys. This period can be altered by pressing the appropriate right screen key.

## Final Exit from Calibration Mode

When you are satisfied that the CAL DUE DATE and advance warning period are correct, press the EXIT screen key to terminate calibration and return to the Mode Selection screen.

The stored Cal Date and Cal Due Date will appear on any directly-printed certificate for this calibration.

### 10.4 Front Panel Calibration by Functions

### 10.4.1 Introduction

Sub-section 10.4 is a guide to the process of calibrating the Model 9100's functions from the front panel. The following topics are covered:

| 10.4.2 | Summary of Calibration Process <br> $10.4 .2 .1 \quad$ General Procedure |
| :--- | :--- |
|  | $10.4 .2 .2 \quad$ Sequencing Calibrations |
| 10.4 .3 | DC Voltage Calibration |
| 10.4 .4 | AC Voltage Calibration |
| 10.4 .5 | DC Current Calibration |
| 10.4 .6 | AC Current Calibration |
| 10.4 .7 | Resistance Calibration |
| 10.4 .8 | Capacitance Calibration |

## Other Functions

No calibration is required for the following functions, as they are either calibrated for life at manufacture, or calibrated automatically as a result of calibrating the functions listed above, as shown in the table:

| Function | Calibration Performed |
| :--- | :--- |
| Capacitance | optionally via Resistance |
| Conductance | via Resistance |
| Frequency | at manufacture |
| Mark/Period | at manufacture |
| \% Duty | at manufacture |
| Temperature - Thermocouple | via DC Voltage |
| Temperature - RTD | via Resistance |
| Logic Pulses | at manufacture |
| Logic Levels | via DC Voltage |

For functions other than capacitance (which can either be calibrated directly or calibrated via Resistance) there are therefore no calibration procedures, although confidence checks for them can be performed (e.g. the Full Selftest procedure detailed in Section 8, subsection 8.3 ).

## CJC Pod Calibration

Calibration of the CJC Pod (the external module which contains the Reference Junction on its iso-thermal block for use with the Thermocouple function) is purely ratiometric, and not dependent on the STD CAL of any function. The calibration should be performed annually, close to the time of STD CAL. The CJC Pod calibration procedure can be found in this section 10; sub-section 10.2.5.

### 10.4.2

Summary of Calibration Process

### 10.4.2.1 General Procedure

Subsections 10.2 and 10.3 introduced the general calibration process for the Model 9100, described how to select and perform the 'Characterise DAC' special calibration operation, and how to calibrate the CJC Pod temperature monitor for the Reference Junction. They also outlined the methods used to select functions, hardware configurations and target calibration points, and how to calibrate the 9100 at these target points.

This entire process is outlined again here as a sequence of simple steps:-

1. Ensure that the 9100 output is OFF.
2. Connect the necessary measuring equipment to the 9100 's output terminals, and set it to the required measurement function and range.
3. Ensure that the rear-panel CAL (Calibration) switch is set to the ENABLE position.
4. Press the front panel Mode key to display the Mode Selection screen.
5. Press the CALIB screen key to display the Password Entry for Calibration screen.
6. Enter the correct password and press the $\Theta$ key to display the Calibration Mode screen.
7. Press the Special screen key to display the Special Calibration screen.
8. Press the Chse-DAC screen key to initiate the Characterise DAC operations and wait until these automatic internal adjustments have been successfully completed. This process will take approximately 20 minutes to complete.
IMPORTANT NOTE: The Characterise DAC operation should be performed once only, immediately before performing Standard Calibration of the 9100. It should not be repeated before calibrating each individual function of the 9100 .
9. Press the front panel Mode key to display the Mode Selection screen.
10. Press the CALIB screen key to display the Password Entry for Calibration screen.
11. Re-enter the appropriate password and press the $\lrcorner$ key to display the Calibration Mode screen.
12. Press the STD CAL screen key to see the Standard Calibration initial default screen - the DC Voltage function screen.
13. Standard Calibration can only be carried out for the following functions:

DC Voltage
AC Voltage
DC Current
AC Current
Resistance
Capacitance
If you are calibrating a function other than DC Voltage, select the required function to see its corresponding function screen. (For selection method, refer to the Model 9100 Universal Calibration System User's Handbook - Volume 1 - Operation, Section 4, subsections 4.4 [ACV], 4.5 [DC Current], 4.6 [ACCurrent], 4.7 [Resistance] and 4.13 [Capacitance].)
14. Select the required hardware configuration by setting the 9100 output to a value that uses the hardware configuration. (Details of each function's hardware configurations and suitable output values to select them can be found in the detailed procedures provided later in this section.)
15. Press the TARGET screen key to display the hardware configuration's target selection screen
16. a) If you wish to use the target calibration points used during the previous calibration of the 9100 , press the Factor screen key corresponding to the required target value, which will display a 'calibrate' screen for the target value.
b) If you wish to use the default target calibration points defined for this hardware configuration, press the DEFLT screen key and then press the Factor screen key corresponding to the required target value, which will display a calibrate screen for the target value.
17. If you wish to change the amplitude of the target calibration point, press the TAB $\Theta$ key one or more times until the cursor is positioned on the target value amplitude. Now use any of the 9100's normal editing modes to change this value. (Note that the new value must lie within the limits specified in the detailed procedures provided later in this section.)
18. Press the TRANSFR screen key to transfer the target calibration point values (amplitude or amplitude and frequency) to the 9100's output control displays.
continued overleaf
19. (For AC functions only)

If you wish to change the target calibration point frequency, press the $\mathbf{T A B} \oplus$ key one or more times until the cursor is positioned on the output frequency control display. Now use any of the 9100's normal editing modes to change this frequency value. (Note that the new value must lie within the limits specified in the detailed procedures provided later in this section.)
20. Press the 9100's ON key to turn its output on.
21. Ensure that cursor control is returned to the 9100 output amplitude display, and increment of decrement this value using the cursor controls and/or spinwheel until the reading on the measuring instrument (connected to the 9100's front-panel terminals) is the same as the displayed target value. (Note: make sure to allow for any settling time required by the external measuring instrument.)
22. When you are satisfied with the measurement, press the CALIB key to generate and implement the correction factor required by the 9100, to ensure that its displayed output value and actual output value coincide. The screen will revert to the CAL mode of the normal function screen, and the measured value should now be equal to the displayed output value.
23. Repeat steps (15) to (22) for each of the target values displayed in the target selection screen.
24. Repeat steps (14) to (23) for each of the hardware configurations associated with the 9100 function that is being calibrated (see note * below).
25. Repeat steps (13) to (24) for each function of the 9100 which is being calibrated (see note * below).
26. Press the Mode key to exit from Calibration mode (refer to Sub-section 10.3, paras 10.3.6 for the processes of date-stamping, altering Cal Due date and setting the advance warning period).
27. Press either the PROC or MANUAL screen keys to return the 9100 to normal Procedure Mode or Manual Mode respectively.

* Note: To ensure that calibrations are done in the correct order and that the calibration process is disturbed as little as possible by thermal dissipation, some of the 9100 's normal functions are split into two separate functions for the purpose of calibration. For example the DC Voltage function is split into a DC Voltage - Zero to $\mathbf{3 2 0 V}$ function and a DC Voltage 320V to 1050 V function.


### 10.4.2.2 Sequencing Calibrations

The table below indicates the order in which the various Model 9100 functions should be calibrated. Although it is not essential to calibrate all the functions indicated below at any one time, functions higher in the list should be calibrated before those lower in the list. If Resistance and Capacitance are being calibrated separately, the Resistance function must be calibrated before the Capacitance function. Similarly if the Resistance function's 'super' UUTi, 'high' UUTi and 'low' UUTi modes are being calibrated, some of the 'super' UUTi hardware, then 'high' UUTi hardware configurations must be calibrated before associated 'low' UUTi hardware configurations.

| Sequence | Function | Reference |
| :---: | :--- | :--- |
| 1 | DC Voltage (Zero to 320V) | Section 10.4.3 |
| 2 | AC Voltage (Zero to 320V) | Section 10.4.4 |
| 3 | Resistance (Super UUTi) | Section 10.4.7 |
| 4 | Resistance (High UUTi) | Section 10.4.7 |
| 5 | Resistance (Low UUTi) | Section 10.4.7 |
| 6 | DC Voltage (320V to 1050V) | Section 10.4.3 |
| 7 | AC Voltage (320V to 1050V) | Section 10.4.4 |
| 8 | Capacitance | Section 10.4.8 |
| 9 | DC Current (Zero to 320mA) | Section 10.4.5 |
| 10 | AC Current (Zero to 320mA) | Section 10.4.6 |
| 11 | DC Current (0.32A to 20A) | Section 10.4.5 |
| 12 | AC Current (0.32A to 20A) | Section 10.4.6 |

Table 10.4.2.1: Recommended Sequence of Calibrations

### 10.4.3.1 Introduction

This section is a guide to calibrating the Model 9100's DC Voltage Function using its front panel controls. The following topics are covered:

| 10.4.3.2 | Calibration Equipment Requirements |
| :--- | :--- |
| 10.4.3.3 | Interconnections |
| 10.4.3.4 | Calibration Setup |
| 10.4.3.5 | Calibration Procedure |

### 10.4.3.2 Calibration Equipment Requirements

A traceably characterized, long scale-length, Standards DMM connected to the Model 9100's output terminals by short, high-quality leads. For example, a Fluke Model 1281 Digital Multimeter.

### 10.4.3.3 Interconnections



### 10.4.3.4 Calibration Setup

1. Connections Ensure that the 9100 is connected to the Standards DMM as shown in Fig. 10.4.3.1, and that both instruments are powered on and warmed up.
2. 9100 Ensure that the 9100 is in STANDARD CAL mode and then select the DC Voltage function by pressing the 'V' key on the right of the front panel.

Table 10.4.3.1: DC Voltage (Zero to 320V) Hardware Configurations and Calibration Points

| Output span covered by hardware configuration | Suitable output to select hardware configuration | Calibration Targets |  |  | Factor Number |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Default | Minimum | Maximum |  |
| 000.000 mV to $\pm 320.000 \mathrm{mV}$ | 100 mV | $\begin{array}{r} 000.000 \mathrm{mV} \\ +300.000 \mathrm{mV} \end{array}$ | $\begin{gathered} -0.080 \mathrm{mV} \\ 180.000 \mathrm{mV} \end{gathered}$ | $\begin{array}{r} 10.000 \mathrm{mV} \\ 320.000 \mathrm{mV} \end{array}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $\pm 0.32001 \mathrm{~V}$ to $\pm 3.20000 \mathrm{~V}$ | 1 V | $\begin{array}{r} -3.00000 \mathrm{~V} \\ +3.00000 \mathrm{~V} \end{array}$ | $\begin{array}{r} -3.20000 \mathrm{~V} \\ +1.80000 \mathrm{~V} \end{array}$ | $\begin{array}{r} -1.80000 \mathrm{~V} \\ +3.20000 \mathrm{~V} \end{array}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $\pm 3.2001 \mathrm{~V}$ to $\pm 32.0000 \mathrm{~V}$ | 10 V | $\begin{array}{r} -30.0000 \mathrm{~V} \\ +30.0000 \mathrm{~V} \end{array}$ | $\begin{array}{r} -32.0000 \mathrm{~V} \\ +18.0000 \mathrm{~V} \end{array}$ | $\begin{array}{r} -18.0000 \mathrm{~V} \\ +32.0000 \mathrm{~V} \end{array}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $\pm 32.001 \mathrm{~V}$ to $\pm 320.000 \mathrm{~V}$ | 100V | $\begin{aligned} & -300.000 \mathrm{~V} \\ & +300.000 \mathrm{~V} \end{aligned}$ | $\begin{array}{r} -320.000 \mathrm{~V} \\ +180.000 \mathrm{~V} \end{array}$ | $\begin{aligned} & -180.000 \mathrm{~V} \\ & +320.000 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |

Table 10.4.3.2: DC Voltage (320V to 1050V) Hardware Configurations and Calibration Points

| Output span covered by hardware configuration | Suitable output to select hardware configuration | Calibration Targets |  |  | Factor Number |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Default | Minimum | Maximum |  |
| $\pm 320.01 \mathrm{~V}$ to $\pm 1050.00 \mathrm{~V}$ | 1000 V | $\begin{aligned} & -1000.00 \mathrm{~V} \\ & +1000.00 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & -1050.00 \mathrm{~V} \\ & +700.00 \mathrm{~V} \end{aligned}$ | $\begin{array}{r} -700.00 \mathrm{~V} \\ +1050.00 \mathrm{~V} \end{array}$ | 1 |

### 10.4.3.5 Calibration Procedure

1. Select the required hardware configuration by setting the 9100 output to a suitable value that uses the hardware configuration.
2. Set the Standards DMM to the appropriate measurement range.
3. Press the 9100's TARGET screen key to display the hardware configuration's target selection screen.
4. Use (a) or (b)
a. To use the target calibration points used during the previous calibration (indicated by the displayed SAVED CALIBRATION TARGETS), press the Factor screen key corresponding to the required target value, to display a 'calibrate' screen for the target value.
b. To use the default target calibration points defined for this hardware configuration, press the DEFLT screen key and then press the Factor screen key corresponding to the required target value, to display a 'calibrate' screen for the target value.
5. To change the amplitude of the target calibration point, press the $\mathbf{T A B} \oplus$ key to position the cursor on the target value amplitude Now use any of the 9100 's normal editing modes to change this value. (Note that the new value must lie within the minimum and maximum limits specified in the tables opposite)
6. Press the TRANSFR screen key to transfer the target calibration point value to the 9100 's output control display
7. Press the ON key to turn the 9100 output on.
8. Press the TAB $\oplus$ key to return the cursor to the 9100 output amplitude display, and increment or decrement this value using the cursor controls and/or spinwheel until the reading on the Standards DMM connected to the 9100 front-panel terminals is the same as the displayed target value. (Note: make sure to allow for any settling time required by the external measuring instrument.)
9. When you are satisfied with the measurement, press the CALIB key to generate and implement the correction factor required by the 9100 , to ensure that its displayed output value and actual output value coincide. The screen will revert to the CAL mode of the normal function screen, and the measured value should now be equal to the displayed output value.
10. Press the OFF key to turn the 9100 output off.
11. Repeat steps (2) to (10) for each of the target values displayed in the target selection screen.
12. Repeat steps (1) to (11) for each of the hardware configurations detailed in the tables opposite (also see note below).

Note: If other functions are being calibrated in addition to DC Voltage, refer to Table 10.4.2.1 on page 10.4-5 for information on sequencing calibrations.

### 10.4.3.6 Calibration of Auxiliary DC Voltage (for Power Option)

## Calibration Setup

1. Connections Ensure that the 9100 is connected to the Standards DMM as shown in Fig. 10.4.3.2, and that both instruments are powered on and warmed up.
2. 9100 Ensure that the 9100 is in STANDARD CAL mode and then select Power and DC Volts by pressing the frontpanel AUX key followed by the softkey sequence POWER*, $=\mathbf{-} \mathbf{W}$, CMANNEL, VOLTAGE. Refer also to Fig. 10.2.2.

* This keystroke is only required if one of the oscilloscope calibration options (Option 250 or Option 600) is fitted.


Table 10.4.3.3: Auxiliary DC Voltage Calibration Points

| Hardware Spans | Calibration Targets |  |  |
| :---: | :---: | :---: | :---: |
|  | Default | Minimum | Maximum |
| 0.000 to 32.00 mV | -30.0000 mV |  |  |
|  | +30.0000 mV | -32.0000 mV <br> +18.0000 mV | -18.0000 mV <br> +32.0000 mV |
| 32.1 mV to 320.0 mV | -300.000 mV |  |  |
|  | +300.000 mV | -320.000 mV |  |
|  | +180.000 mV | -180.000 mV <br> +320.000 mV |  |
| 0.321 V to 3.200 V | -3.00000 V | -3.20000 V | -1.80000 V |
|  | +3.00000 V | +1.80000 V | +3.20000 V |
| 3.201 V to 7.500 V | -6.00000 V | -6.50000 V | -4.00000 V |
|  | +6.00000 V | +4.00000 V | +6.50000 V |

[^2]
## Calibration Procedure

1. Select the required hardware configuration by setting the 9100 output to a suitable value that uses the hardware configuration.
2. Set the Standards DMM to the appropriate measurement range.
3. Press the 9100's TARGET screen key to display the hardware configuration's target selection screen.
4. Use (a) or (b):
a. To use the target calibration points used during the previous calibration (indicated by the displayed SAVED CALIBRATION TARGETS), press the Factor screen key corresponding to the required target value, to display a 'calibrate' screen for the target value.
b. To use the default target calibration points defined for this hardware configuration, press the DEFLT screen key and then press the Factor screen key corresponding to the required target value, to display a 'calibrate' screen for the target value.
5. To change the amplitude of the target calibration point, press the $\mathbf{T A B} \oplus$ key to position the cursor on the target value amplitude. Now use any of the 9100 's normal editing modes to change this value. (Note that the new value must lie within the minimum and maximum limits specified in the tables opposite)
6. Press the TRANSFR screen key to transfer the target calibration point value to the 9100 's output control display.
7. Press the ON key to turn the 9100 output on.
8. Press the TAB $\oplus$ key to return the cursor to the 9100 output amplitude display, and increment or decrement this value using the cursor controls and/or spinwheel until the reading on the Standards DMM connected to the 9100 front-panel terminals is the same as the displayed target value. (Note: make sure to allow for any settling time required by the external measuring instrument.)
9. When you are satisfied with the measurement, press the CALIB key to generate and implement the correction factor required by the 9100 , to ensure that its displayed output value and actual output value coincide. The screen will revert to the CAL mode of the normal function screen, and the measured value should now be equal to the displayed output value.
10. Press the OFF key to turn the 9100 output off.
11. Repeat steps (2) to (10) for each of the target values displayed in the target selection screen.
12. Repeat steps (1) to (11) for each of the hardware configurations detailed in the tables opposite (also see note below).

Note: If other functions are being calibrated in addition to DC Voltage, refer to Table 10.4.2.1 on page 10.4-5 for information on sequencing calibrations.

## Introduction

This section is a guide to calibrating the Model 9100 AC Voltage Function using its front panel controls. The following topics are covered:
10.4.4.2 Calibration Equipment Requirements
10.4.4.3 Interconnections
10.4.4.4 Calibration Setup
10.4.4.5 Calibration Procedure

### 10.4.4.2 Calibration Equipment Requirements

A traceably characterized, long scale-length, Standards DMM connected to the Model 9100 's output terminals by a short, high-quality coaxial cable. For example, a Fluke Model 1281 Digital Multimeter.

### 10.4.4.3 Interconnections



Fig 10.4.4.1 AC Voltage Calibration — Interconnections

Section 10: Calibrating the Model 9100: AC Voltage Function

### 10.4.4.4 Calibration Setup

1. Connections Ensure that the 9100 is connected to the Standards DMM as shown in Fig. 10.4.4.1, and that both instruments are powered on and warmed up.
2. 9100
a. Ensure that the 9100 is in STANDARD CAL mode and then select the AC Voltage function by pressing the 'V' key on the right of the front panel, followed by pressing the ' $\sim \mathbf{V}$ ' screen key adjacent to the display.
b. Ensure that Sinusoidal waveshape is selected, and that the Phase facility is deselected ( $\Delta \Phi$ label dark lettering on light background).

Table 10.4.4.1: AC Voltage (Zero to 320V) Hardware Configurations and Calibration Points

| Output span covered by hardware configuration | Output to select hardware config. | Calibration Targets |  |  |  |  |  | Factor Number |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Amplitude |  |  | Frequency |  |  |  |
|  |  | Default | Minimum | Maximum | Default | Minimum | Maximum |  |
| $\begin{aligned} & \hline 000.000 \mathrm{mV} \\ & \text { to } \\ & 320.000 \mathrm{mV} \end{aligned}$ | 100 mV | $\begin{aligned} & 300.000 \mathrm{mV} \\ & 300.000 \mathrm{mV} \\ & 300.000 \mathrm{mV} \end{aligned}$ | $\begin{aligned} & \hline 180.000 \mathrm{mV} \\ & 180.000 \mathrm{mV} \\ & 180.000 \mathrm{mV} \end{aligned}$ | $\begin{aligned} & 320.000 \mathrm{mV} \\ & 320.000 \mathrm{mV} \\ & 320.000 \mathrm{mV} \end{aligned}$ | $\begin{aligned} & \hline 1.0000 \mathrm{kHz} \\ & 30.000 \mathrm{kHz} \\ & 100.00 \mathrm{kHz} \end{aligned}$ | $\begin{array}{r} 150.00 \mathrm{~Hz} \\ 15.000 \mathrm{kHz} \\ 65.00 \mathrm{kHz} \end{array}$ | $\begin{array}{r} 5.000 \mathrm{kHz} \\ 45.00 \mathrm{kHz} \\ 100.00 \mathrm{kHz} \end{array}$ | $\begin{aligned} & 1 \\ & 2 \\ & 3 \end{aligned}$ |
| $\begin{gathered} 0.32001 \mathrm{~V} \\ \text { to } \\ 3.20000 \mathrm{~V} \end{gathered}$ | 1V | 3.00000 V <br> 3.00000 V <br> 3.00000 V | $\begin{aligned} & 1.80000 \mathrm{~V} \\ & 1.80000 \mathrm{~V} \\ & 1.80000 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 3.20000 \mathrm{~V} \\ & 3.20000 \mathrm{~V} \\ & 3.20000 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 1.0000 \mathrm{kHz} \\ & 30.000 \mathrm{kHz} \\ & 100.00 \mathrm{kHz} \end{aligned}$ | $\begin{array}{r} 150.00 \mathrm{~Hz} \\ 15.000 \mathrm{kHz} \\ 65.00 \mathrm{kHz} \end{array}$ | $\begin{array}{r} 5.000 \mathrm{kHz} \\ 45.00 \mathrm{kHz} \\ 100.00 \mathrm{kHz} \end{array}$ | $\begin{aligned} & 1 \\ & 2 \\ & 3 \end{aligned}$ |
| $\begin{gathered} 3.2001 \mathrm{~V} \\ \text { to } \\ 32.0000 \mathrm{~V} \end{gathered}$ | 10V | 30.0000 V <br> 30.0000 V <br> 30.0000 V | 18.0000 V <br> 18.0000 V <br> 18.0000 V | $\begin{aligned} & 32.0000 \mathrm{~V} \\ & 32.0000 \mathrm{~V} \\ & 32.0000 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 1.0000 \mathrm{kHz} \\ & 30.000 \mathrm{kHz} \\ & 100.00 \mathrm{kHz} \end{aligned}$ | $\begin{array}{r} 150.00 \mathrm{~Hz} \\ 15.000 \mathrm{kHz} \\ 65.00 \mathrm{kHz} \end{array}$ | $\begin{array}{r} 5.000 \mathrm{kHz} \\ 45.00 \mathrm{kHz} \\ 100.00 \mathrm{kHz} \end{array}$ | $\begin{aligned} & \hline 1 \\ & 2 \\ & 3 \end{aligned}$ |
| $\begin{gathered} \hline 32.001 \mathrm{~V} \\ \text { to } \\ 105.000 \mathrm{~V} \end{gathered}$ | 100V | $\begin{aligned} & 100.000 \mathrm{~V} \\ & 100.000 \mathrm{~V} \\ & 100.000 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & \hline 70.000 \mathrm{~V} \\ & 70.000 \mathrm{~V} \\ & 70.000 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 105.000 \mathrm{~V} \\ & 105.000 \mathrm{~V} \\ & 105.000 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & \hline 1.0000 \mathrm{kHz} \\ & 30.000 \mathrm{kHz} \\ & 100.00 \mathrm{kHz} \end{aligned}$ | $\begin{array}{r} 150.00 \mathrm{~Hz} \\ 15.000 \mathrm{kHz} \\ 65.00 \mathrm{kHz} \end{array}$ | $\begin{array}{r} 5.000 \mathrm{kHz} \\ 45.00 \mathrm{kHz} \\ 100.00 \mathrm{kHz} \end{array}$ | $\begin{aligned} & \hline 1 \\ & 2 \\ & 3 \end{aligned}$ |
| $\begin{gathered} 105.001 \mathrm{~V} \\ \text { to } \\ 320.000 \mathrm{~V} \end{gathered}$ | 150V | $\begin{aligned} & 300.000 \mathrm{~V} \\ & 300.000 \mathrm{~V} \\ & 300.000 \mathrm{~V} \\ & 300.000 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 180.000 \mathrm{~V} \\ & 180.000 \mathrm{~V} \\ & 180.000 \mathrm{~V} \\ & 180.000 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 320.000 \mathrm{~V} \\ & 320.000 \mathrm{~V} \\ & 320.000 \mathrm{~V} \\ & 320.000 \mathrm{~V} \end{aligned}$ | $\begin{array}{r} 40.00 \mathrm{~Hz} \\ 200.00 \mathrm{~Hz} \\ 10.000 \mathrm{kHz} \\ 30.000 \mathrm{kHz} \end{array}$ | $\begin{array}{r} 40.00 \mathrm{~Hz} \\ 150.00 \mathrm{~Hz} \\ 3.0000 \mathrm{kHz} \\ 25.000 \mathrm{kHz} \end{array}$ | $\begin{array}{r} 75.00 \mathrm{~Hz} \\ 250.00 \mathrm{~Hz} \\ 20.000 \mathrm{kHz} \\ 30.000 \mathrm{kHz} \end{array}$ | $\begin{aligned} & 1 \\ & 2 \\ & 3 \\ & 4 \\ & \hline \end{aligned}$ |

Table 10.4.4.2: AC Voltage (320V to 1050V) Hardware Configurations and Calibration Points

| Output span covered by hardware configuration | Output to select hardware config. | Calibration Targets |  |  |  |  |  | Factor Number |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Amplitude |  |  | Frequency |  |  |  |
|  |  | Default | Minimum | Maximum | Default | Minimum | Maximum |  |
| 320.01 V | 500 V | 750.00 V | 700.00 V | 1050.00V | 40.00 Hz | 40.00 Hz | 75.00 Hz | 1 |
| to |  | 750.00 V | 700.00 V | 1050.00V | 200.00 Hz | 150.00 Hz | 250.00 Hz | 2 |
| 1050.00V |  | 750.00 V | 700.00 V | 1050.00V | 10.000 kHz | 3.0000 kHz | 20.000 kHz | 3 |
|  |  | 330.00 V | 320.10 V | 350.00 V | 30.000 kHz | 25.000 kHz | 30.000 kHz | 4 |

### 10.4.4.5 Calibration Procedure

1. Select the required hardware configuration by setting the 9100 output to a suitable value that uses the hardware configuration.
2. Set the Standards DMM to the appropriate measurement range.
3. Press the 9100 's TARGET screen key to display the hardware configuration's target selection screen.
4. Use (a) or (b):
a. To use the target calibration points used during the previous calibration (as indicated by the displayed SAVED CALIBRATION TARGETS), press the Factor screen key corresponding to the required target value to display a calibrate screen for the target value.
b. To use the default target calibration points defined for this hardware configuration, press the DEFLT screen key and then press the Factor screen key corresponding to the required target value to display a calibrate screen for the target value.
5. To change the amplitude of the target calibration point, press the $\mathbf{T A B} \oplus$ key one or more times until the cursor is positioned on the target value amplitude. Now use any of the 9100 's normal editing modes to change this value. (Note that the new value must lie within the minimum and maximum limits specified in the tables opposite.)
6. Press the TRANSFR screen key to transfer the target calibration point amplitude and frequency to the 9100 's output control display.
7. If you wish to change the target calibration point frequency, press the $\mathbf{T A B} \oplus$ key one or more times until the cursor is positioned on the output frequency control display. Now use any of the 9100 's normal editing modes to change this frequency value. (Note that the new value must lie within the limits specified in the tables opposite.)
8. Press the ON key to turn the Model 9100 output on.
9. Ensure that cursor control is returned to the 9100 output amplitude display, and increment or decrement this value using the cursor controls and/or spinwheel until the reading on the Standards DMM connected to the 9100 front-panel terminals is the same as the displayed target value. (Note: make sure to allow for any settling time required by the external measuring instrument.)
10. When you are satisfied with the measurement, press the CALIB key to generate and implement the correction factor required by the 9100 to ensure that its displayed output value and actual output value coincide. The screen will revert to the CAL mode of the normal function screen, and the measured value should now be equal to the displayed output value.
11. Press the OFF key to turn the Model 9100 output off.
12. Repeat steps (2) to (11) for each of the target values displayed on the target selection screen.
13. Repeat steps (1) to (11) for each of the hardware configurations detailed in the tables opposite (also see the note below).

Note: If other functions are to be calibrated in addition to AC Voltage, refer to Table 10.4.2.1 on page 10.4-5 for information on sequencing calibrations.

### 10.4.4.6 Calibration of Auxiliary AC Voltage (for Power Option)

## Calibration Setup

1. Connections Ensure that the 9100 is connected to the Standards DMM as shown in Fig. 10.4.3.2, and that both instruments are powered on and warmed up.
2. 9100 Ensure that the 9100 is in STANDARD CAL mode and then select Power and AC Volts by pressing the frontpanel AUX key followed by the softkey sequence POWER*, $\sim \mathbf{W}$, сААААN
Refer also to Fig. 10.2.2.

* This keystroke is only required if one of the oscilloscope calibration options (Option 250 or Option 600) is fitted.

Table 10.4.4.3: Auxiliary AC Voltage Calibration Points

| Hardware Spans | Level |  |  |  | Calibration Targets |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\|c\|$ |  |  |  |  |  |  |
|  | Default | Minimum | Maximum | Default | Minimum | Maximum |  |
| 0.000 mV to 3.200 mV | 3.00000 mV | 1.80000 mV | 3.20000 mV | 40 | 35 | 45 |  |
|  | 3.00000 mV | 1.80000 mV | 3.20000 mV | 150 | 140 | 160 |  |
|  | 3.00000 mV | 1.8000 mV | 3.20000 mV | 1000 | 900 | 1100 |  |
|  | 3.00000 mV | 1.80000 mV | 3.20000 mV | 3000 | 2500 | 3000 |  |
| 3.21 mV to 32.00 mV | 30.0000 mV | 18.0000 mV | 32.0000 mV | 40 | 35 | 45 |  |
|  | 30.0000 mV | 18.0000 mV | 32.0000 mV | 150 | 140 | 160 |  |
|  | 30.0000 mV | 18.0000 mV | 32.0000 mV | 1000 | 900 | 1100 |  |
|  | 30.0000 mV | 18.0000 mV | 32.0000 mV | 3000 | 2500 | 3000 |  |
| 32.1 mV to 320.0 mV | 300.000 mV | 180.000 mV | 320.000 mV | 40 | 35 | 45 |  |
|  | 300.000 mV | 180.000 mV | 320.000 mV | 150 | 140 | 160 |  |
|  | 300.000 mV | 180.000 mV | 320.000 mV | 1000 | 900 | 1100 |  |
|  | 300.000 mV | 180.000 mV | 320.000 mV | 3000 | 2500 | 3000 |  |
| 0.321 V to 3.200 V | 3.00000 V | 1.80000 V | 3.20000 | 40 | 35 | 45 |  |
|  | 3.00000 V | 1.80000 V | 3.20000 | 150 | 140 | 160 |  |
|  | 3.00000 V | 1.80000 V | 3.20000 | 1000 | 900 | 1100 |  |
|  | 3.00000 V | 1.80000 V | 3.20000 | 3000 | 2500 | 3000 |  |
| 3.201 V to 7.500 V | 6.00000 V | 4.00000 V | 6.50000 V | 40 | 35 | 45 |  |
|  | 6.00000 V | 4.00000 V | 6.50000 V | 150 | 140 | 160 |  |
|  | 6.00000 V | 4.00000 V | 6.50000 V | 1000 | 900 | 1100 |  |
|  | 6.00000 V | 4.00000 V | 6.50000 | 3000 | 2500 | 3000 |  |

## Calibration Procedure

1. Select the required hardware configuration by setting the 9100 output to a suitable value that uses the hardware configuration.
2. Set the Standards DMM to the appropriate measurement range.
3. Press the 9100 's TARGET screen key to display the hardware configuration's target selection screen.
4. Use (a) or (b):
a. To use the target calibration points used during the previous calibration (as indicated by the displayed SAVED CALIBRATION TARGETS), press the Factor screen key corresponding to the required target value to display a calibrate screen for the target value.
b. To use the default target calibration points defined for this hardware configuration, press the DEFLT screen key and then press the Factor screen key corresponding to the required target value to display a calibrate screen for the target value.
5. To change the amplitude of the target calibration point, press the $\mathbf{T A B} \oplus$ key one or more times until the cursor is positioned on the target value amplitude. Now use any of the 9100's normal editing modes to change this value. (Note that the new value must lie within the minimum and maximum limits specified in the tables opposite.)
6. Press the TRANSFR screen key to transfer the target calibration point amplitude and frequency to the 9100 's output control display.
7. If you wish to change the target calibration point frequency, press the $\mathbf{T A B} \oplus$ key one or more times until the cursor is positioned on the output frequency control display. Now use any of the 9100 's normal editing modes to change this frequency value. (Note that the new value must lie within the limits specified in the tables opposite.)
8. Press the ON key to turn the Model 9100 output on.
9. Ensure that cursor control is returned to the 9100 output amplitude display, and increment or decrement this value using the cursor controls and/or spinwheel until the reading on the Standards DMM connected to the 9100 front-panel terminals is the same as the displayed target value. (Note: make sure to allow for any settling time required by the external measuring instrument.)
10. When you are satisfied with the measurement, press the CALIB key to generate and implement the correction factor required by the 9100 to ensure that its displayed output value and actual output value coincide. The screen will revert to the CAL mode of the normal function screen, and the measured value should now be equal to the displayed output value.
11. Press the OFF key to turn the Model 9100 output off.
12. Repeat steps (2) to (11) for each of the target values displayed on the target selection screen.
13. Repeat steps (1) to (11) for each of the hardware configurations detailed in the tables opposite (also see the note below).

Note: If other functions are to be calibrated in addition to AC Voltage, refer to Table 10.4.2.1 on page 10.4-5 for information on sequencing calibrations.

## Introduction

This section is a guide to calibrating the Model 9100's DC Current Function using its front panel controls. The following topics are covered:
10.4.5.2 Calibration Equipment Requirements
10.4.5.3 Interconnections
10.4.5.4 Calibration Setup
10.4.5.5 Calibration Procedure

### 10.4.5.2 Calibration Equipment Requirements

A traceably characterized, long scale-length, Standards DMM connected to the 9100 output terminals by short, high-quality leads. For example, a Fluke Model 1281 Digital Multimeter. Note that some DMM's may require a precision current shunt to measure up to 10A.

Interconnections for Low Current Outputs ( $\leq 1 \mathrm{~A}$ )


Fig. 10.4.5.1 DC Low Current Calibration Interconnections

Interconnections for High Current Outputs (>1A)


Fig. 10.4.5.2 DC High Current Calibration Interconnections

### 10.4.5.4 Calibration Setup

1. Connections Ensure that the 9100 is connected to the Standards DMM as shown in Fig. 10.4.5.1 or Fig. 10.4.5.2 (depending on the magnitude of current being calibrated), and that both instruments are powered on and warmed up. If the measuring instrument has a switchable signal guarding facility it should be switched to remote guard. If it does not have a guard facility, there can be no guard lead to the DMM.
2. Model 9100 Ensure that the 9100 is in STANDARD CAL mode and then select the DC Current function by pressing the 'A' key on the right of the front panel.

Table 10.4.5.1: DC Current (Zero to 320mA) Hardware Configurations and Calibration Points

| Output span covered by hardware configuration | Suitable output to select hardware configuration | Calibration Targets |  |  | Factor Number |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Default | Minimum | Maximum |  |
| $000.000 \mu \mathrm{~A}$ to $\pm 320.000 \mu \mathrm{~A}$ | $100 \mu \mathrm{~A}$ | $\begin{array}{r} 000.000 \mu \mathrm{~A} \\ +190.000 \mu \mathrm{~A} \end{array}$ | $\begin{array}{r} -0.080 \mu \mathrm{~A} \\ 180.000 \mu \mathrm{~A} \end{array}$ | $\begin{gathered} 32.000 \mu \mathrm{~A} \\ 320.000 \mu \mathrm{~A} \end{gathered}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $\pm 0.32001 \mathrm{~mA}$ to $\pm 3.20000 \mathrm{~mA}$ | 1 mA | $\begin{array}{r} -1.90000 \mathrm{~mA} \\ +1.90000 \mathrm{~mA} \end{array}$ | $\begin{array}{r} -3.20000 \mathrm{~mA} \\ +1.80000 \mathrm{~mA} \end{array}$ | $\begin{aligned} & -1.80000 \mathrm{~mA} \\ & +3.20000 \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $\pm 3.2001 \mathrm{~mA}$ to $\pm 32.0000 \mathrm{~mA}$ | 10 mA | $\begin{array}{r} -19.0000 \mathrm{~mA} \\ +19.0000 \mathrm{~mA} \end{array}$ | $\begin{array}{r} -32.0000 \mathrm{~mA} \\ +18.0000 \mathrm{~mA} \end{array}$ | $\begin{gathered} -18.0000 \mathrm{~mA} \\ +32.0000 \mathrm{~mA} \end{gathered}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $\pm 32.001 \mathrm{~mA}$ to $\pm 320.000 \mathrm{~mA}$ | 100 mA | $\begin{array}{r} -190.000 \mathrm{~mA} \\ +190.000 \mathrm{~mA} \end{array}$ | $\begin{array}{r} -320.000 \mathrm{~mA} \\ +180.000 \mathrm{~mA} \end{array}$ | $\begin{aligned} & -180.000 \mathrm{~mA} \\ & +320.000 \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |

Table 10.4.5.2: DC Current (0.32A to 20A) Hardware Configurations and Calibration Points

| Output span covered by hardware configuration | Suitable output to select hardware configuration | Calibration Targets |  |  | Factor <br> Number |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Default | Minimum | Maximum |  |
| $\pm 0.32001 \mathrm{~A}$ to $\pm 3.20000 \mathrm{~A}$ | 1 A | $\begin{array}{r} -1.90000 \mathrm{~A} \\ +1.90000 \mathrm{~A} \end{array}$ | $\begin{array}{r} -3.20000 \mathrm{~A} \\ +1.80000 \mathrm{~A} \end{array}$ | $\begin{aligned} & -1.80000 \mathrm{~A} \\ & +3.20000 \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $\pm 3.2001 \mathrm{~A}$ to $\pm 20.0000 \mathrm{~A}$ | 10A | $\begin{array}{r} -10.0000 \mathrm{~A} \\ +10.0000 \mathrm{~A} \end{array}$ | $\begin{array}{r} -10.5000 \mathrm{~A} \\ +7.0000 \mathrm{~A} \end{array}$ | $\begin{array}{r} -7.0000 \mathrm{~A} \\ +10.5000 \mathrm{~A} \end{array}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |

### 10.4.5.5 Calibration Procedure

1. Select the required hardware configuration by setting the 9100 output to a suitable value that uses the hardware configuration
2. Set the Standards DMM to the appropriate measurement range.
3. Press the 9100's TARGET screen key to display the hardware configuration's target selection screen.
4. Use (a) or (b):
a. To use the target calibration points used during the previous calibration (as indicated by the displayed SAVED CALIBRATION TARGETS), press the Factor screen key corresponding to the required target value, to display a 'calibrate' screen for the target value.
b. To use the default target calibration points defined for this hardware configuration, press the DEFLT screen key and then press the Factor screen key corresponding to the required target value, to display a 'calibrate' screen for the target value
5. To change the amplitude of the target calibration point, press the TAB $\oplus$ key to position the cursor on the target value amplitude Now use any of the 9100 's normal editing modes to change this value. (Note that the new value must lie within the minimum and maximum limits specified in the tables opposite.)
6. Press the TRANSFR screen key to transfer the target calibration point value to the Model 9100's output control display
7. Press the ON key to turn the 9100 output on
8. Press the TAB $\oplus$ key to return the cursor to the 9100 output amplitude display, and increment or decrement this value using the cursor controls and/or spinwheel until the reading on the Standards DMM connected to the 9100 front-panel terminals is the same as the displayed target value. (Note: make sure to allow for any settling time required by the external measuring instrument.)
9. When you are satisfied with the measurement, press the CALIB key to generate and implement the correction factor required by the 9100 to ensure that its displayed output value and actual output value coincide. The screen will revert to the CAL mode of the normal function screen, and the measured value should now be equal to the displayed output value.
10. Press the OFF key to turn the 9100 output off
11. Repeat steps (2) to (10) for each of the target values displayed on the target selection screen
12. Repeat steps (1) to (11) for each of the hardware configurations detailed in the tables opposite (also see note below).

Note: If other functions are being calibrated in addition to DC Current, refer to Table 10.4.2.1 on page 10.4-5 for information on sequencing calibrations.

### 10.4.5.6 Calibration of Auxiliary DC Current (for Power Option)

## Calibration Setup

1. Connections For the $\mathbf{3 2 0 m A}$ range connect the 9100 to the Standards DMM as shown in Fig. 10.4.5.3 opposite. If the DMM has a Remote/Local Guard facility, switch it to Local Guard.

For all other ranges connect the 9100 to the Standards DMM as shown in Fig. 10.4.5.4 opposite. If the DMM has a Remote/Local Guard facility, it should be switched to Remote Guard when a connection to the shunt's case can be made. If it does not have a guard facility, there can be no guard lead to the DMM.
Ensure that both instruments are powered on and warmed up.
2. Model 9100 Ensure that the 9100 is in STANDARD CAL mode and then select Power and DC Current by pressing the front-panel AUX key followed by the softkey sequence POWER*, =_W, сُААNNEL, CURRENT
Refer also to Fig. 10.2.2.

* This keystroke is only required if one of the oscilloscope calibration options (Option 250 or Option 600) is fitted.


Table 10.4.5.3: Auxiliary DC Current Calibration Points

| Hardware Spans | Calibration Targets |  |  |
| :---: | :---: | :---: | :---: |
|  | Default | Minimum | Maximum |
| 0.000 mA to $\pm 320.0 \mathrm{~mA}$ <br> (one range) | -300.000 mA <br> +300.000 mA | -320.000 mA <br> +180.000 mA | -180.00 mA <br> +320.000 mA |
| $\pm 0.321 \mathrm{~A}$ to $\pm 3.200 \mathrm{~A}$ | -3.00000 A | -3.20000 A | -1.80000 A |
|  | +3.00000 A | +1.80000 A | +3.20000 A |
| $\pm 3.21$ to $\pm 32.00 \mathrm{~A}$ | -10.0000 A | -10.5000 A | -7.00000 A |
|  | +10.0000 A | +7.00000 A | +10.5000 A |

## Calibration Procedure

1. Select the required hardware configuration by setting the 9100 output to a suitable value that uses the hardware configuration.
2. Set the Standards DMM to the appropriate measurement range.
3. Press the 9100 's TARGET screen key to display the hardware configuration's target selection screen.
4. Use (a) or (b):
a. To use the target calibration points used during the previous calibration (as indicated by the displayed SAVED CALIBRATION TARGETS), press the Factor screen key corresponding to the required target value, to display a 'calibrate' screen for the target value.
b. To use the default target calibration points defined for this hardware configuration, press the DEFLT screen key and then press the Factor screen key corresponding to the required target value, to display a 'calibrate' screen for the target value.
5. To change the amplitude of the target calibration point, press the TAB $\Theta$ key to position the cursor on the target value amplitude. Now use any of the 9100 's normal editing modes to change this value. (Note that the new value must lie within the minimum and maximum limits specified in the tables opposite.)
6. Press the TRANSFR screen key to transfer the target calibration point value to the Model 9100's output control display.
7. Press the ON key to turn the 9100 output on.
8. Press the TAB $\oplus$ key to return the cursor to the 9100 output amplitude display, and increment or decrement this value using the cursor controls and/or spinwheel until the reading on the Standards DMM connected to the 9100 front-panel terminals is the same as the displayed target value. (Note: make sure to allow for any settling time required by the external measuring instrument.)
9. When you are satisfied with the measurement, press the CALIB key to generate and implement the correction factor required by the 9100 to ensure that its displayed output value and actual output value coincide. The screen will revert to the CAL mode of the normal function screen, and the measured value should now be equal to the displayed output value.
10. Press the OFF key to turn the 9100 output off.
11. Repeat steps (2) to (10) for each of the target values displayed on the target selection screen.
12. Repeat steps (1) to (11) for each of the hardware configurations detailed in the tables opposite (also see note below).

Note: If other functions are being calibrated in addition to DC Current, refer to Table 10.4.2.1 on page 10.4-5 for information on sequencing calibrations.

## AC Current Calibration

### 10.4.6.1

 IntroductionThis section is a guide to calibrating the Model 9100's AC Current Function using its front panel controls. The following topics are covered:
10.4.6.2 Calibration Equipment Requirements
10.4.6.3 Interconnections
10.4.6.4 Calibration Setup
10.4.6.5 Calibration Procedure

### 10.4.6.2 Calibration Equipment Requirements

A traceably characterized, long scale-length, Standards DMM connected to the 9100 output terminals by a short, high-quality coaxial cable. For example, a Fluke Model 1281 Digital Multimeter. Note that some DMMs may require a precision AC Current shunt to measure up to 10A.


### 10.4.6.4 Calibration Setup

1. Connections Ensure that the Model 9100 is connected to the Standards DMM as shown in Fig. 10.4.6.1 or 10.4.6.2 (depending on the current being calibrated), and that both instruments are powered on and warmed up. If the measuring instrument has a switchable signal guarding facility it should be switched to remote guard. If it does not have a guard facility, there can be no guard lead to the DMM.
a. Ensure that the 9100 is in STANDARD CAL mode and then select the AC Current function by pressing the ' $\mathbf{A}$ ' key on the right of the front panel, followed by pressing the ' $\sim \mathbf{A}$ ' screen key adjacent to the display.
b. Ensure that Sinusoidal waveshape is selected, and that the Phase facility is deselected ( $\Delta \Phi$ label dark lettering on light background).

Table 10.4.6.1: AC Current (Zero to 320mA) Hardware Configurations and Calibration Points

| Output span covered by hardware configuration | Output to select hardware config. | Calibration Targets |  |  |  |  |  | Factor Number |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Amplitude |  |  | Frequency |  |  |  |
|  |  | Default | Minimum | Maximum | Default | Minimum | Maximum |  |
| 000.000 $\mu \mathrm{A}$ | $100 \mu \mathrm{~A}$ | $300.000 \mu \mathrm{~A}$ | $180.000 \mu \mathrm{~A}$ | $320.000 \mu \mathrm{~A}$ | 110.00 Hz | 10.00 Hz | 320.00 Hz | 1 |
| to |  | $300.000 \mu \mathrm{~A}$ | $180.000 \mu \mathrm{~A}$ | $320.000 \mu \mathrm{~A}$ | 3.0000 kHz | 1.0000 kHz | 5.000 kHz | 2 |
| $320.000 \mu \mathrm{~A}$ |  | $300.000 \mu \mathrm{~A}$ | $180.000 \mu \mathrm{~A}$ | $320.000 \mu \mathrm{~A}$ | 30.000 kHz | 20.000 kHz | 30.000 kHz | 3 |
| 0.32001 mA | 1 mA | 3.00000 mA | 1.80000 mA | 3.20000 mA | 110.00 Hz | 10.00 Hz | 320.00 Hz | 1 |
| to |  | 3.00000 mA | 1.80000 mA | 3.20000 mA | 3.0000 kHz | 1.0000 kHz | 5.000 kHz | 2 |
| 3.20000 mA |  | 3.00000 mA | 1.80000 mA | 3.20000 mA | 30.000 kHz | 20.000 kHz | 30.000 kHz | 3 |
| 3.2001 mA | 10 mA | 30.0000 mA | 18.0000 mA | 32.0000 mA | 110.00 Hz | 10.00 Hz | 320.00 Hz | 1 |
| to |  | 30.0000 mA | 18.0000 mA | 32.0000 mA | 3.0000 kHz | 1.0000 kHz | 5.000 kHz | 2 |
| 32.0000 mA |  | 30.0000 mA | 18.0000 mA | 32.0000 mA | 30.000 kHz | 20.000 kHz | 30.000 kHz | 3 |
| 32.001 mA | 100 mA | 300.000 mA | 180.000 mA | 320.000 mA | 110.00 Hz | 10.00 Hz | 320.00 Hz | 1 |
| to |  | 300.000 mA | 180.000 mA | 320.000 mA | 3.0000 kHz | 1.0000 kHz | 5.000 kHz | 2 |
| 320.000 mA |  | 300.000 mA | 180.000 mA | 320.000 mA | 30.000 kHz | 20.000 kHz | 30.000 kHz | 3 |

Table 10.4.6.2: AC Current (0.32A to 20A) Hardware Configurations and Calibration Points

| Output span covered by hardware configuration | Output to select hardware config. | Calibration Targets |  |  |  |  |  | Factor Number |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Amplitude |  |  | Frequency |  |  |  |
|  |  | Default | Minimum | Maximum | Default | Minimum | Maximum |  |
| 0.32001A | 1A | 3.00000A | 1.80000A | 3.20000 A | 110.00 Hz | 10.00 Hz | 320.00 Hz | 1 |
| to |  | 3.00000A | 1.80000A | 3.20000A | 3.0000 kHz | 2.0000 kHz | 4.000 kHz | 2 |
| 3.20000A |  | 3.00000A | 1.80000A | 3.20000 A | 10.000 kHz | 7.000 kHz | 10.000 kHz | 3 |
| 3.2001 A | 10A | 10.0000A | 7.0000A | 10.5000A | 110.00 Hz | 10.00 Hz | 320.00 Hz | 1 |
| to |  | 10.0000A | 7.0000A | 10.5000A | 3.0000 kHz | 2.0000 kHz | 4.000 kHz | 2 |
| 20.0000A |  | 10.0000A | 7.0000A | 10.5000A | 10.000 kHz | 7.000 kHz | 10.000 kHz | 3 |

### 10.4.6.5 Calibration Procedure

1. Select the required hardware configuration by setting the 9100 output to a suitable value that uses the hardware configuration
2. Set the Standards DMM to the appropriate measurement range.
3. Press the 9100's TARGET softkey to display the hardware configuration's target selection screen
4. Use (a) or (b):
a. To use the target calibration points used during the previous calibration (as indicated by the displayed SAVED CALIBRATION TARGETS), press the Factor softkey corresponding to the required target value to display a calibrate screen for the target value.
b. To use the default target calibration points defined for this hardware configuration, press the DEFLT softkey and then press the Factor softkey corresponding to the required target value to display a calibrate screen for the target value.
5. To change the amplitude of the target calibration point, press the TAB $\oplus$ key one or more times until the cursor is positioned on the target value amplitude. Now use any of the 9100's normal editing modes to change this value. (Note that the new value must lie within the minimum and maximum limits specified in the tables opposite.)
6. Press the TRANSFR softkey to transfer the target calibration point amplitude and frequency to the 9100 output control display.
7. To change the target calibration point frequency, press the $\mathbf{T A B} \oplus$ key one or more times until the cursor is positioned on the output frequency control display. Now use any of the 9100's normal editing modes to change this frequency value. (Note that the new value must lie within the limits specified in the tables opposite.)
8. Press the $\mathbf{O N}$ key to turn the 9100 output on
9. Ensure that cursor control is returned to the 9100 output amplitude display, and increment or decrement this value using the cursor controls and/or spinwheel until the reading on the Standards DMM connected to the 9100's front-panel terminals is the same as the displayed target value. (Note: make sure to allow for any settling time required by the external measuring instrument.)
10. When you are satisfied with the measurement, press the CALIB key to generate and implement the correction factor required by the 9100 to ensure that its displayed output value and actual output value coincide. The screen will revert to the CAL mode of the normal function screen, and the measured value should now be equal to the displayed output value.
11. Press the OFF key to turn the 9100 output off
12. Repeat steps (2) to (11) for each of the target values displayed in the target selection screen.
13. Repeat steps (1) to (12) for each of the hardware configurations detailed in the tables opposite (also see note below).

Note: If other functions are being calibrated in addition to AC Current, refer to Table 10.4.2.1 on page 10.4-5 for information on sequencing calibrations.

### 10.4.6.6 Calibration of Auxiliary AC Current (for Power Option)

## Calibration Setup

1. Connections For the $\mathbf{3 2 0 m A}$ range connect the 9100 to the Standards DMM as shown in Fig. 10.4.6.3 opposite. If the DMM has a Remote/Local Guard facility, switch it to Local Guard.

For all other ranges connect the 9100 to the Standards DMM as shown in Fig. 10.4.6.4 opposite. If the DMM has a Remote/Local Guard facility, it should be switched to Remote Guard when a connection to the shunt's case can be made. If it does not have a guard facility, there can be no guard lead to the DMM.

Ensure that both instruments are powered on and warmed up.
2. Model 9100 Ensure that the 9100 is in STANDARD CAL mode and then select Power and AC Current by pressing the front-panel AUX key followed by the softkey sequence POWER*, ~W, © AAMNEL, CURRENT. Refer also to Fig. 10.2.2.
*This keystroke is only required if one of the oscilloscope calibration options (Option 250 or Option 600) is fitted.

Interconnections for the 320mA range


Fig. 10.4.6.3 320mA Range Calibration Interconnections

Interconnections for ranges above 320mA


Fig. 10.4.6.4 1A range and Higher Calibration Interconnections

Table 10.4.6.3: Auxiliary AC Current Calibration Points

| Output span covered by hardware configuration | Calibration Targets |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Amplitude |  |  | Frequency |  |  |
|  | Default | Minimum | Maximum | Default | Minimum | Maximum |
| 0.000 mA to 320.0 mA (one range) | $\begin{aligned} & 300.000 \mathrm{~mA} \\ & 300.000 \mathrm{~mA} \\ & 300.000 \mathrm{~mA} \\ & 300.000 \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & 180.000 \mathrm{~mA} \\ & 180.000 \mathrm{~mA} \\ & 180.000 \mathrm{~mA} \\ & 180.000 \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & \text { 320.000A } \\ & 320.000 \mathrm{~A} \\ & 320.000 \mathrm{~A} \\ & 320.000 \mathrm{~A} \end{aligned}$ | $\begin{array}{r} \hline 40 \mathrm{~Hz} \\ 150 \mathrm{~Hz} \\ 1000 \mathrm{~Hz} \\ 3000 \mathrm{~Hz} \end{array}$ | $\begin{array}{r} 35 \mathrm{~Hz} \\ 140 \mathrm{~Hz} \\ 900 \mathrm{~Hz} \\ 2700 \mathrm{~Hz} \end{array}$ | $\begin{array}{r} \hline 45 \mathrm{~Hz} \\ 160 \mathrm{~Hz} \\ 1100 \mathrm{~Hz} \\ 3000 \mathrm{~Hz} \end{array}$ |
| 0.3201A to 3.200A | $\begin{aligned} & 3.00000 \mathrm{~A} \\ & 3.00000 \mathrm{~A} \\ & 3.00000 \mathrm{~A} \\ & 3.00000 \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 1.80000 \mathrm{~A} \\ & 1.80000 \mathrm{~A} \\ & 1.80000 \mathrm{~A} \\ & 1.80000 \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 3.20000 \mathrm{~A} \\ & 3.20000 \mathrm{~A} \\ & 3.20000 \mathrm{~A} \\ & 3.20000 \mathrm{~A} \end{aligned}$ | $\begin{array}{r} 40 \mathrm{~Hz} \\ 150 \mathrm{~Hz} \\ 1000 \mathrm{~Hz} \\ 3000 \mathrm{~Hz} \end{array}$ | $\begin{array}{r} 35 \mathrm{~Hz} \\ 140 \mathrm{~Hz} \\ 900 \mathrm{~Hz} \\ 2700 \mathrm{~Hz} \end{array}$ | $\begin{array}{r} 45 \mathrm{~Hz} \\ 160 \mathrm{~Hz} \\ 1100 \mathrm{~Hz} \\ 3000 \mathrm{~Hz} \end{array}$ |
| 3.21 to 20.00A | $\begin{aligned} & \text { 10.0000A } \\ & 10.0000 \mathrm{~A} \\ & 10.0000 \mathrm{~A} \\ & 10.0000 \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 7.00000 \mathrm{~A} \\ & 7.00000 \mathrm{~A} \\ & 7.00000 \mathrm{~A} \\ & 7.00000 \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 10.5000 \mathrm{~A} \\ & 10.5000 \mathrm{~A} \\ & 10.5000 \mathrm{~A} \\ & 10.5000 \mathrm{~A} \end{aligned}$ | $\begin{array}{r} 40 \mathrm{~Hz} \\ 150 \mathrm{~Hz} \\ 1000 \mathrm{~Hz} \\ 3000 \mathrm{~Hz} \end{array}$ | $\begin{array}{r} 35 \mathrm{~Hz} \\ 140 \mathrm{~Hz} \\ 900 \mathrm{~Hz} \\ 2700 \mathrm{~Hz} \end{array}$ | $\begin{array}{r} 45 \mathrm{~Hz} \\ 160 \mathrm{~Hz} \\ 1100 \mathrm{~Hz} \\ 3000 \mathrm{~Hz} \end{array}$ |

## Calibration Procedure

1. Select the required hardware configuration by setting the 9100 output to a suitable value that uses the hardware configuration.
2. Set the Standards DMM to the appropriate measurement range.
3. Press the 9100's TARGET softkey to display the hardware configuration's target selection screen.
4. Use (a) or (b):
a. To use the target calibration points used during the previous calibration (as indicated by the displayed SAVED CALIBRATION TARGETS), press the Factor softkey corresponding to the required target value to display a calibrate screen for the target value.
b. To use the default target calibration points defined for this hardware configuration, press the DEFLT softkey and then press the Factor softkey corresponding to the required target value to display a calibrate screen for the target value.
5. To change the amplitude of the target calibration point, press the TAB $\oplus$ key one or more times until the cursor is positioned on the target value amplitude. Now use any of the 9100's normal editing modes to change this value. (Note that the new value must lie within the minimum and maximum limits specified in the tables opposite.)
6. Press the TRANSFR softkey to transfer the target calibration point amplitude and frequency to the 9100 output control display.
7. To change the target calibration point frequency, press the $\mathbf{T A B} \oplus$ key one or more times until the cursor is positioned on the output frequency control display. Now use any of the 9100's normal editing modes to change this frequency value. (Note that the new value must lie within the limits specified in the tables opposite.)
8. Press the ON key to turn the 9100 output on.
9. Ensure that cursor control is returned to the 9100 output amplitude display, and increment or decrement this value using the cursor controls and/or spinwheel until the reading on the Standards DMM connected to the 9100's front-panel terminals is the same as the displayed target value. (Note: make sure to allow for any settling time required by the external measuring instrument.)
10. When you are satisfied with the measurement, press the CALIB key to generate and implement the correction factor required by the 9100 to ensure that its displayed output value and actual output value coincide. The screen will revert to the CAL mode of the normal function screen, and the measured value should now be equal to the displayed output value.
11. Press the OFF key to turn the 9100 output off.
12. Repeat steps (2) to (11) for each of the target values displayed in the target selection screen.
13. Repeat steps (1) to (12) for each of the hardware configurations detailed in the tables opposite (also see note below).

Note: If other functions are being calibrated in addition to AC Current, refer to Table 10.4.2.1 on page 10.4-5 for information on sequencing calibrations.

### 10.4.7 Resistance Calibration

10.4.7.1 Introduction

This section is a guide to calibrating the Model 9100's Resistance Function using its front panel controls. The following topics are covered:
10.4.7.2 Source Currents
10.4.7.3 Target Calibration Points
10.4.7.4 Calibration Equipment Requirements
10.4.7.5 Interconnections
10.4.7.6 Calibration Setup
10.4.7.7 Calibration of UUTi High Source Current Hardware Configurations
10.4.7.8 Calibration of UUTi Low Source Current Hardware Configurations

### 10.4.7.2 Source Currents

The 9100 synthesizes resistance by sensing the current ( $\mathrm{I}_{\text {source }}$ ) flowing into its terminals, and then driving its terminal voltage to a value given by the equation:
$\mathbf{V}_{\text {terminals }}=\mathbf{I}_{\text {source }} \mathbf{x} \mathbf{R}$, Where $\mathbf{R}$ is the output value set on the 9100 display.
To cope with the wide range of source currents used by different UUTs, most of the hardware configurations (spans of output resistance) associated with the Resistance function have user-selectable 'UUTi Low' 'UUTi High' and 'UUTi Super' source current operating modes.
These hardware configurations, and their corresponding ranges of UUTi source currents used during normal operation of the 9100 are shown in Table 10.4.7.1. The 9100 is switched between UUTi source currents by pressing the CHANGE CURRENT screen key.

| Hardware Configuration Limits <br> on Span of Output Resistance | UUTi Low | Constant Source Current Limits |  |
| :---: | :---: | :---: | :---: |
|  | $250 \mu \mathrm{~A}$ to 3.5 mA | 2.5 mA to 35 mA | 25 mA to 350 mA |
| $040.001 \Omega$ to $400.000 \Omega$ | $25 \mu \mathrm{~A}$ to $320 \mu \mathrm{~A}$ | $250 \mu \mathrm{~A}$ to 3.5 mA | 2.5 mA to 35 mA |
| $0.40001 \mathrm{k} \Omega$ to $4.00000 \mathrm{k} \Omega$ | $25 \mu \mathrm{~A}$ to $320 \mu \mathrm{~A}$ | $250 \mu \mathrm{~A}$ to 3.5 mA | 2.5 mA to 35 mA |
| $04.0001 \mathrm{k} \Omega$ to $40.0000 \mathrm{k} \Omega$ | $2.5 \mu \mathrm{~A}$ to $32 \mu \mathrm{~A}$ | $25 \mu \mathrm{~A}$ to $350 \mu \mathrm{~A}$ | $250 \mu \mathrm{~A}$ to 3.5 mA |
| $040.001 \mathrm{k} \Omega$ to $400.000 \mathrm{k} \Omega$ | 250 nA to $3.2 \mu \mathrm{~A}$ | $2.5 \mu \mathrm{~A}$ to $35 \mu \mathrm{~A}$ | $25 \mu \mathrm{~A}$ to $350 \mu \mathrm{~A}$ |
| $0.40001 \mathrm{M} \Omega$ to $4.00000 \mathrm{M} \Omega$ | 25 nA to 320 nA | 250 nA to $3.5 \mu \mathrm{~A}$ | $2.5 \mu \mathrm{~A}$ to $35 \mu \mathrm{~A}$ |
| $04.0001 \mathrm{M} \Omega$ to $40.0000 \mathrm{M} \Omega$ | 8 nA to 32 nA | 25 nA to 350 nA | 250 nA to $3.5 \mu \mathrm{~A}$ |
| $040.001 \mathrm{M} \Omega$ to $400.000 \mathrm{M} \Omega$ | 4 nA to 32 nA | 25 nA to 200 nA | $\mathrm{N} / \mathrm{A}$ |

Table 10.4.7.1: Resistance Spans and Source Current Limits in Normal Operation

## Output Voltage Limitation

The terminal voltage compliance in the Resistance function is limited to 10 V . As a result, if the product ( $\mathbf{I}_{\text {source }} \mathbf{x} \mathbf{R}$ ) is greater than 10 V , the output will saturate and the apparent output resistance will be less than the value indicated on the screen. Under these conditions the following error message will be displayed:

$$
=======\text { WARNING }=======
$$

UUT sense current is high.
Internal circuits saturated.
Change current setting.

### 10.4.7.3 Target Calibration Points

All Resistance function hardware configurations, except the one which produces outputs in the range $00.0000 \Omega$ to $40.0000 \Omega$, have 'UUTi High' and 'UUTi Low' source current modes which can be calibrated separately using appropriate source currents. It is not advisable to calibrate the 'UUTi Super' source current mode externally, as this requires high source voltages. Because of this, the 'UUTi Super' calibration is done internally from the UUTi High and Low calibrations, and external calibration is not necessary.

Because these source currents are driven into the 9100 front-panel terminals by the calibration equipment, it is essential that the calibration equipment's range is selected on the basis of the source current which it generates and not solely on the basis of its resistance measurement range

To create optimum calibration conditions, the calibration equipment range must be selected so that it:
a. generates a source current which lies within the range required by the 9100 selected hardware configuration and
b. allows measurement of the 9100 output to be made at as high a percentage of the calibration equipment's range as possible.

For example, suppose your calibration equipment is a standards laboratory DMM which generates a source current of $10 \mu \mathrm{~A}$ on its $1 \mathrm{M} \Omega$ range and $1 \mu \mathrm{~A}$ on its $10 \mathrm{M} \Omega$ range. Its $10 \mathrm{M} \Omega$ range should be used to calibrate both the $40.001 \mathrm{k} \Omega$ to $400.000 \mathrm{k} \Omega$ UUTi Low source current hardware configuration and the $0.40001 \mathrm{M} \Omega$ to $4.00000 \mathrm{M} \Omega$ UUTi High source current hardware configuration, as both of these require a source current during calibration between 500 nA and $2 \mu \mathrm{~A}$ (see Table 10.4.7.3 and Table 10.4.7.2 respectively). Although it would appear that the DMM could measure the $40.001 \mathrm{k} \Omega$ to $400.000 \mathrm{k} \Omega$ hardware configuration outputs more accurately on its $1 \mathrm{M} \Omega$ range, this range cannot be used because its source current is too high.
Table 10.4.7.2 and Table 10.4.7.3 list both the default calibration targets and a set of recommended calibration targets, together with the source current limits which are applicable during calibration of the 9100 .

The default calibration targets are 'ideal' values which give optimum calibration conditions, but are only usable if suitable calibration equipment is available - i.e. calibration equipment which generates the correct source currents and is traceably calibrated at these target values. The recommended calibration targets are devised to enable measuring instruments with decade ranges (for example, DMMs) to be used as the calibration equipment, while employing high-accuracy points on their ranges.

### 10.4.7.4 Calibration Equipment Requirements

The procedure is based on the use of a traceably-characterized, long scale-length Standards DMM, using short leads to deliver the 9100 output to the DMM input using a 4-wire connection. For example, a Fluke Model 1281 Digital Multimeter.


Fig. 10.4.7.1 Resistance Calibration Interconnections

### 10.4.7.6 Calibration Setup

1. Connections Ensure that the 9100 is connected to the Standards DMM as shown in Fig. 10.4.7.1, and that both instruments are powered on and warmed up.
2. 9100 Select the Resistance Function by pressing the ' $\Omega$ ' key on the right of the front panel.

### 10.4.7.7 Calibration of 'UUTi High' Source Current Hardware Configurations

If both UUTi High and UUTi Low source current hardware configurations are being calibrated, the UUTi High source current calibrations shown in Table 10.4.7.2 below should be performed before the UUTi Low source current calibrations.

Table 10.4.7.2: Resistance - 'UUTi High' Source Current Hardware Configurations and Calibration Points

| Output span covered by hardware configuration | Output to select hardware config. | Calibration Targets |  |  |  |  |  | Factor Number |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Amplitude |  |  |  | Source Current |  |  |
|  |  | Default | Minimum | Maximum | Recommended | Minimum | Maximum |  |
| $\begin{aligned} & 00.0000 \Omega \\ & \text { to } 40.0000 \Omega \end{aligned}$ | $10 \Omega$ | $\begin{array}{r} 1.0000 \Omega \\ 30.0000 \Omega \end{array}$ | $\begin{array}{r} 0.0100 \Omega \\ 10.0000 \Omega \end{array}$ | $\begin{array}{r} 7.5000 \Omega \\ 39.0000 \Omega \end{array}$ | $\begin{array}{r} 0.1000 \Omega \\ 38.0000 \Omega \end{array}$ | $\begin{aligned} & 500 \mu \mathrm{~A} \\ & 500 \mu \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 2.0 \mathrm{~mA} \\ & 2.0 \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $\begin{aligned} & 40.001 \Omega \\ & \text { to } 400.000 \Omega \end{aligned}$ | $100 \Omega$ | $\begin{array}{r} 60.000 \Omega \\ 300.000 \Omega \end{array}$ | $\begin{array}{r} 41.000 \Omega \\ 100.000 \Omega \end{array}$ | $\begin{array}{r} 75.000 \Omega \\ 390.000 \Omega \end{array}$ | $\begin{array}{r} 45.000 \Omega \\ 380.000 \Omega \end{array}$ | $\begin{aligned} & 500 \mu \mathrm{~A} \\ & 500 \mu \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 2.0 \mathrm{~mA} \\ & 2.0 \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $\begin{aligned} & 0.40001 \mathrm{k} \Omega \\ & \text { to } 4.00000 \mathrm{k} \Omega \end{aligned}$ | $1 \mathrm{k} \Omega$ | $\begin{aligned} & 0.60000 \mathrm{k} \Omega \\ & 3.00000 \mathrm{k} \Omega \end{aligned}$ | $\begin{aligned} & 0.41000 \mathrm{k} \Omega \\ & 1.00000 \mathrm{k} \Omega \end{aligned}$ | $\begin{aligned} & 0.75000 \mathrm{k} \Omega \\ & 3.90000 \mathrm{k} \Omega \end{aligned}$ | $\begin{aligned} & 0.45000 \mathrm{k} \Omega \\ & 1.95000 \mathrm{k} \Omega \end{aligned}$ | $\begin{aligned} & 500 \mu \mathrm{~A} \\ & 500 \mu \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 2.0 \mathrm{~mA} \\ & 2.0 \mathrm{~mA} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $\begin{aligned} & 4.0001 \mathrm{k} \Omega \\ & \text { to } 40.0000 \mathrm{k} \Omega \end{aligned}$ | 10k $\Omega$ | $\begin{array}{r} 6.0000 \mathrm{k} \Omega \\ 30.0000 \mathrm{k} \Omega \end{array}$ | $\begin{array}{r} 4.1000 \mathrm{k} \Omega \\ 10.000 \mathrm{k} \Omega \end{array}$ | $\begin{array}{r} 7.5000 \mathrm{k} \Omega \\ 39.0000 \mathrm{k} \Omega \end{array}$ | $\begin{array}{r} 4.5000 \mathrm{k} \Omega \\ 38.0000 \mathrm{k} \Omega \end{array}$ | $\begin{aligned} & 50 \mu \mathrm{~A} \\ & 50 \mu \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 200 \mu \mathrm{~A} \\ & 200 \mathrm{uA} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $\begin{aligned} & 40.001 \mathrm{k} \Omega \\ & \text { to } 400.000 \mathrm{k} \Omega \end{aligned}$ | $100 \mathrm{k} \Omega$ | $\begin{array}{r} 60.000 \mathrm{k} \Omega \\ 300.000 \mathrm{k} \Omega \end{array}$ | $\begin{array}{r} 41.000 \mathrm{k} \Omega \\ 100.000 \mathrm{k} \Omega \end{array}$ | $\begin{array}{r} 75.000 \mathrm{k} \Omega \\ 390.000 \mathrm{k} \Omega \end{array}$ | $\begin{array}{r} 45.000 \mathrm{k} \Omega \\ 380.000 \mathrm{k} \Omega \end{array}$ | $\begin{aligned} & 5.0 \mu \mathrm{~A} \\ & 5.0 \mu \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 20 \mu \mathrm{~A} \\ & 20 \mu \mathrm{~A} \\ & \hline \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $\begin{aligned} & 0.40000 \mathrm{M} \Omega \\ & \text { to } 4.00000 \mathrm{M} \Omega \end{aligned}$ | $1 \mathrm{M} \Omega$ | $\begin{aligned} & \hline 0.60000 \mathrm{M} \Omega \\ & 3.00000 \mathrm{M} \Omega \end{aligned}$ | $\begin{aligned} & 0.41000 \mathrm{M} \Omega \\ & 1.00000 \mathrm{M} \Omega \end{aligned}$ | $\begin{aligned} & 0.75000 \mathrm{M} \Omega \\ & 3.90000 \mathrm{M} \Omega \end{aligned}$ | $\begin{aligned} & 0.45000 \mathrm{M} \Omega \\ & 3.80000 \mathrm{M} \Omega \end{aligned}$ | $\begin{aligned} & 500 \mathrm{nA} \\ & 500 \mathrm{nA} \end{aligned}$ | $\begin{aligned} & 2.0 \mu \mathrm{~A} \\ & 2.0 \mu \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $\begin{aligned} & 4.0001 \mathrm{M} \Omega \\ & \text { to } 40.0000 \mathrm{M} \Omega \end{aligned}$ | $10 \mathrm{M} \Omega$ | $\begin{array}{r} 6.0000 \mathrm{M} \Omega \\ 30.0000 \mathrm{M} \Omega \end{array}$ | $\begin{array}{r} \hline 4.1000 \mathrm{M} \Omega \\ 10.0000 \mathrm{M} \Omega \end{array}$ | $\begin{array}{r} 7.5000 \mathrm{M} \Omega \\ 39.0000 \mathrm{M} \Omega \end{array}$ | $\begin{array}{r} 4.5000 \mathrm{M} \Omega \\ 38.0000 \mathrm{M} \Omega \end{array}$ | 50nA $50 \mathrm{nA}$ | $\begin{aligned} & 200 \mathrm{nA} \\ & 200 \mathrm{nA} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $\begin{aligned} & 40.001 \mathrm{M} \Omega \\ & \text { to } 400.000 \mathrm{M} \Omega \end{aligned}$ | $100 \mathrm{M} \Omega$ | $\begin{gathered} 60.000 \mathrm{M} \Omega \\ 300.000 \mathrm{M} \Omega \end{gathered}$ | $\begin{aligned} & 41.000 \mathrm{M} \Omega \\ & 76.500 \mathrm{M} \Omega \\ & \hline \end{aligned}$ | $\begin{array}{r} 70.000 \mathrm{M} \Omega \\ 390.000 \mathrm{M} \Omega \\ \hline \end{array}$ | $\begin{aligned} & 45.000 \mathrm{M} \Omega \\ & 80.000 \mathrm{M} \Omega \\ & \hline \end{aligned}$ | $\begin{aligned} & \text { 50nA } \\ & 50 \mathrm{nA} \end{aligned}$ | $\begin{aligned} & 100 \mathrm{nA} \\ & 100 \mathrm{nA} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2[1] \end{aligned}$ |

Notes:
[1] This calibration point is limited by the maximum source current. If the actual source current is less than the indicated maximum, the output value can be raised in inverse proportion. For example, a 50 nA source current would allow the calibration point to be increased to $160 \mathrm{M} \Omega$.

## Calibration Procedure

1. Select the required hardware configuration by setting the 9100 output to a suitable value that uses the hardware configuration.
2. Set the Standards DMM to the appropriate measurement range.
3. Press the 9100's TARGET screen key to display the hardware configuration's target selection screen.
4. Use (a) or (b):
a. To use the target calibration points used during the previous calibration (as indicated by the displayed SAVED CALIBRATION TARGETS), press the Factor screen key corresponding to the required target value, to display a 'calibrate' screen for the target value.
b. To use the default target calibration points defined for this hardware configuration, press the DEFLT screen key and then press the Factor screen key corresponding to the required target value, to display a 'calibrate' screen for the target value.
5. To change the amplitude of the target calibration point, press the $\mathbf{T A B} \oplus$ key to position the cursor on the target value amplitude. Now use any of the 9100 's normal editing modes to change this value. (Note that the new value must lie within the minimum and maximum limits specified in the table opposite.)
6. Press the TRANSFR screen key to transfer the target calibration point value to the 9100 output control display.
7. Press the ON key to turn the 9100 output on.
8. Press the TAB $\oplus$ key to return the cursor to the 9100 output amplitude display, and increment or decrement this value using the cursor controls and/or spinwheel until the reading on the Standards DMM connected to the 9100 front-panel terminals is the same as the displayed target value. (Note: make sure to allow for any settling time required by the external measuring instrument.)
9. When you are satisfied with the measurement, press the CALIB key to generate and implement the correction factor required by the 9100 to ensure that its displayed output value and actual output value coincide. The screen will revert to the CAL mode of the normal function screen, and the measured value should now be equal to the displayed output value.
10. Press the OFF key to turn the 9100 output off.
11. Repeat steps (2) to (10) for each of the target values displayed in the target selection screen.
12. Repeat steps (1) to (11) for each of the hardware configurations detailed in the table opposite (also see note below).

Note: If other functions are being calibrated in addition to Resistance, refer to Table 10.4.2.1 on page 10.4-5 for information on sequencing calibrations.

### 10.4.7.8 Calibration of 'UUTi Low' Source Current Hardware Configuration

If both UUTi High source current and UUTi Low source current hardware configurations are being calibrated, the UUTi Low source current calibrations shown in Table 10.4.7.3 below should be performed after the UUTi High source current calibrations. (See Note [2] below)

Table 10.4.7.3: Resistance - 'UUTi Low' Source Current Hardware Configurations and Calibration Points

| Output span covered by hardware configuration | Output to select hardware config. | Calibration Targets |  |  |  |  |  | Factor Number |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Amplitude |  |  |  | Source Current |  |  |
|  |  | Default | Minimum | Maximum | Recommended | Minimum | Maximum |  |
| $\begin{aligned} & 40.001 \Omega \\ & \text { to } 400.000 \Omega \end{aligned}$ | $100 \Omega$ | $\begin{gathered} 60.000 \Omega \\ 300.000 \Omega \end{gathered}$ | $\begin{array}{r} \hline 41.000 \Omega \\ 100.000 \Omega \end{array}$ | $\begin{array}{r} 75.000 \Omega \\ 390.000 \Omega \end{array}$ | $\begin{gathered} 45.000 \Omega \\ 380.000 \Omega \end{gathered}$ | $\begin{aligned} & 50 \mu \mathrm{~A} \\ & 50 \mu \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 200 \mu \mathrm{~A} \\ & 200 \mu \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $0.40001 \mathrm{k} \Omega$ to $4.00000 \mathrm{k} \Omega$ | $1 \mathrm{k} \Omega$ | $\begin{aligned} & 0.60000 \mathrm{k} \Omega \\ & 3.00000 \mathrm{k} \Omega \end{aligned}$ | $\begin{aligned} & 0.41000 \mathrm{k} \Omega \\ & 1.00000 \mathrm{k} \Omega \end{aligned}$ | $\begin{aligned} & 0.75000 \mathrm{k} \Omega \\ & 3.90000 \mathrm{k} \Omega \end{aligned}$ | $\begin{aligned} & 0.45000 \mathrm{k} \Omega \\ & 3.80000 \mathrm{k} \Omega \end{aligned}$ | $\begin{aligned} & 50 \mu \mathrm{~A} \\ & 50 \mu \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 200 \mu \mathrm{~A} \\ & 200 \mu \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $\begin{aligned} & 4.0001 \mathrm{k} \Omega \\ & \text { to } 40.0000 \mathrm{k} \Omega \end{aligned}$ | $10 \mathrm{k} \Omega$ | $\begin{array}{r} \hline 6.0000 \mathrm{k} \Omega \\ 30.0000 \mathrm{k} \Omega \end{array}$ | $\begin{array}{r} 4.1000 \mathrm{k} \Omega \\ 10.0000 \mathrm{k} \Omega \\ \hline \end{array}$ | $\begin{array}{r} 7.5000 \mathrm{k} \Omega \\ 39.0000 \mathrm{k} \Omega \end{array}$ | $\begin{array}{r} 4.5000 \mathrm{k} \Omega \\ 38.0000 \mathrm{k} \Omega \end{array}$ | $\begin{aligned} & 5.0 \mu \mathrm{~A} \\ & 5.0 \mu \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 20 \mu \mathrm{~A} \\ & 20 \mu \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $\begin{aligned} & 40.001 \mathrm{k} \Omega \\ & \text { to } 400.000 \mathrm{k} \Omega \end{aligned}$ | $100 \mathrm{k} \Omega$ | $\begin{array}{r} 60.000 \mathrm{k} \Omega \\ 300.000 \mathrm{k} \Omega \end{array}$ | $\begin{array}{r} 41.000 \mathrm{k} \Omega \\ 100.000 \mathrm{k} \Omega \end{array}$ | $\begin{array}{r} 75.000 \mathrm{k} \Omega \\ 390.000 \mathrm{k} \Omega \end{array}$ | $\begin{array}{r} 45.000 \mathrm{k} \Omega \\ 380.000 \mathrm{k} \Omega \end{array}$ | 500nA 500nA | $\begin{aligned} & 2.0 \mu \mathrm{~A} \\ & 2.0 \mu \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $0.40000 \mathrm{M} \Omega$ to $4.00000 \mathrm{M} \Omega$ | $1 \mathrm{M} \Omega$ | $\begin{aligned} & 0.60000 \mathrm{M} \Omega \\ & 3.00000 \mathrm{M} \Omega \end{aligned}$ | $\begin{aligned} & 0.41000 \mathrm{M} \Omega \\ & 1.00000 \mathrm{M} \Omega \end{aligned}$ | $\begin{aligned} & 0.75000 \mathrm{M} \Omega \\ & 3.90000 \mathrm{M} \Omega \end{aligned}$ | $\begin{aligned} & 0.45000 \mathrm{M} \Omega \\ & 3.80000 \mathrm{M} \Omega \end{aligned}$ | 50nA <br> 50nA | $\begin{aligned} & 200 n A \\ & 200 n A \end{aligned}$ | $\begin{aligned} & 1[2] \\ & 2[2] \end{aligned}$ |
| $\begin{aligned} & 4.0001 \mathrm{M} \Omega \\ & \text { to } 40.0000 \mathrm{M} \Omega \end{aligned}$ | $10 \mathrm{M} \Omega$ | $\begin{array}{r} 6.0000 \mathrm{M} \Omega \\ 30.0000 \mathrm{M} \Omega \end{array}$ | $\begin{array}{r} 4.1000 \mathrm{M} \Omega \\ 10.0000 \mathrm{M} \Omega \end{array}$ | $\begin{array}{r} 7.5000 \mathrm{M} \Omega \\ 39.0000 \mathrm{M} \Omega \end{array}$ | $\begin{array}{r} 4.5000 \mathrm{M} \Omega \\ 38.0000 \mathrm{M} \Omega \end{array}$ | $\begin{aligned} & 5.0 \mathrm{nA} \\ & 5.0 \mathrm{nA} \end{aligned}$ | $\begin{aligned} & 20 \mathrm{nA} \\ & 20 \mathrm{nA} \end{aligned}$ | $\begin{aligned} & 1[2] \\ & 2[2] \end{aligned}$ |
| $40.001 \mathrm{M} \Omega$ to $400.000 \mathrm{M} \Omega$ | $100 \mathrm{M} \Omega$ | $\begin{array}{r} 60.000 \mathrm{M} \Omega \\ 300.000 \mathrm{M} \Omega \end{array}$ | $\begin{array}{r} 41.000 \mathrm{M} \Omega \\ 100.000 \mathrm{M} \Omega \end{array}$ | $\begin{array}{r} 75.000 \mathrm{M} \Omega \\ 390.000 \mathrm{M} \Omega \end{array}$ | $\begin{array}{r} 45.000 \mathrm{M} \Omega \\ 380.000 \mathrm{M} \Omega \end{array}$ | $\begin{aligned} & 5.0 \mathrm{nA} \\ & 5.0 \mathrm{nA} \end{aligned}$ | $\begin{aligned} & 20 \mathrm{nA} \\ & 20 \mathrm{nA} \end{aligned}$ | $\begin{aligned} & 1[2] \\ & 2[2] \end{aligned}$ |

Notes:
2] Calibration of these UUTi Low source current hardware configurations may be omitted if the Standards DMM has no suitable range, as they are automatically calibrated by internal transfers, to an accuracy greater than that obtainable using the majority of DMMs, when the corresponding UUTi High source current hardware configurations are calibrated. (When the $4 M \Omega$ UUTi High source current hardware configuration is calibrated, the $4 M \Omega$ UUTi Low source current hardware configuration is automatically calibrated. When the $40 M \Omega$ UUTi High source current hardware configuration is calibrated, the $40 \mathrm{M} \Omega$ and $400 \mathrm{M} \Omega$ UUTi Low source current hardware configurations are automatically calibrated.)
If these UUTi Low source current hardware configurations are being calibrated against an external standard as detailed in the table above, the calibration operations must be performed after the corresponding UUTi High source current hardware configurations have been calibrated. Otherwise the calibration correction factors produced will be overwritten by those generated automatically by the UUTi High source current calibrations.

## Calibration Procedure

1. Select the required hardware configuration by setting the 9100 output to a suitable value that uses the hardware configuration.
2. Set the Standards DMM to the appropriate measurement range.
3. Press the 9100 's TARGET screen key to display the hardware configuration's target selection screen.
4. Use (a) or (b):
a. To use the target calibration points used during the previous calibration (as indicated by the displayed SAVED CALIBRATION TARGETS), press the Factor screen key corresponding to the required target value, to display a 'calibrate' screen for the target value.
b. To use the default target calibration points defined for this hardware configuration, press the DEFLT screen key and then press the Factor screen key corresponding to the required target value, to display a 'calibrate' screen for the target value.
5. To change the amplitude of the target calibration point, press the $\mathbf{T A B} \oplus$ key to position the cursor on the target value amplitude. Now use any of the 9100 's normal editing modes to change this value. (Note that the new value must lie within the minimum and maximum limits specified in the tables opposite.)
6. Press the TRANSFR screen key to transfer the target calibration point value to the 9100 output control display.
7. Press the ON key to turn the 9100 output on.
8. Press the TAB $\oplus$ key to return the cursor to the 9100 output amplitude display, and increment or decrement this value using the cursor controls and/or spinwheel until the reading on the Standards DMM connected to the 9100 front-panel terminals is the same as the displayed target value. (Note: make sure to allow for any settling time required by the external measuring instrument.)
9. When you are satisfied with the measurement, press the CALIB key to generate and implement the correction factor required by the 9100 to ensure that its displayed output value and actual output value coincide. The screen will revert to the CAL mode of the normal function screen, and the measured value should now be equal to the displayed output value.
10. Press the OFF key to turn the 9100 output off
11. Repeat steps (2) to (10) for each of the target values displayed in the target selection screen.
12. Repeat steps (1) to (11) for each of the hardware configurations detailed in the table opposite (also see note below).

Note: If other functions are being calibrated in addition to Resistance, refer to Table 10.4.2.1 on page 10.4-5 for information on sequencing calibrations.

### 10.4.7.9 Verification procedures

A full Verification is available at a Fluke service centre, and this is the preferred method.
The user may adopt the following procedural guidance to give a high confidence level that the 9100 is functioning within its specification. Whether an acceptance test or verification test is required, the procedure is the same. The primary points for verification are the calibration points. These are usually multiples of threes. If preferred, the user may use the multiple of 1.9 immediately below; this usually gives slightly better uncertainty, due to better specifications from the 1281
The chosen points should be measured using a Fluke 1281, 1271, or 4950. A 1281 (or 1271 within 24 hours of self cal) will usually be preferred by the user for reasons of availability and speed. If it is desired to verify the 10A range, the use of a Fluke 4953 shunt is recommended.
The specifications which determine acceptable performance at $23^{\circ} \mathrm{C} \pm 2^{\circ} \mathrm{C}$ for the auxiliary functions are simply those published in the handbook. For verification purposes, the errors of the 1281 or 1271 are compensated for by the fact that the handbook spec is for five degrees. The $3^{\circ}$ margin allows for the 1281 errors.

### 10.4.8 <br> Capacitance Calibration

### 10.4.8.1 Introduction

This section is a guide to calibrating the Model 9100's Capacitance Function using its front panel controls. The following topics are covered:
10.4.8.2 Calibration Equipment Requirements
10.4.8.3 Interconnections
10.4.8.4 Calibration Setup
10.4.8.5 Calibration of 'UUTi Low' Source Current Hardware Configuration
10.4.8.6 'UUTi Low' Source Current Hardware Configuration Calibration Procedure
10.4.8.7 Calibration of 'UUTi Super' Source Current Hardware Configuration
10.4.8.8 'UUTi Super' Source Current Hardware Configuration Calibration Procedure

## Is a Local External User-Calibration Really Necessary?

It should be noted that all the hardware configurations associated with the 9100 Capacitance function are automatically calibrated whenever the Resistance function is calibrated. If both the Capacitance and Resistance functions are being separately calibrated against external standards, Capacitance must be calibrated after Resistance to prevent overwriting of the Capacitance function's calibration correction factors.

Due to the cost of maintaining a suitable set of standard capacitors, ( 2 per 9100 capacitance span), it is not really practicable to use this technique for values above about $400 \mu \mathrm{~F}$. Specially-designed equipment is used at manufacture to calibrate the 9100 before shipment.

### 10.4.8.2 Calibration Equipment Requirements

A set of traceably calibrated standard capacitors at values between the minimum and maximum calibration targets defined in Table 10.4.8.1 overleaf, and a 3-1/2 digit or better capacitance meter (for example, a Wavetek DM97 Digital Multimeter for UUTi Low source current, and a Wavetek DM28 Digital Multimeter for UUTi Super source current) which is used to make transfer measurements between these standard capacitors and the 9100.


Fig 10.4.8.1 Capacitance Calibration — Interconnections

### 10.4.8.4 Calibration Setup

1. Connections Ensure that the 9100 is connected to the capacitance meter as shown in Fig. 10.4.8.1, and that both instruments are powered on and warmed up.
2. 9100 Ensure that the 9100 is in STANDARD CAL mode and then select the Capacitance function by pressing the 'Aux' key on the right of the front panel followed by the '- $-(-$ ' screen key adjacent to the display.

### 10.4.8.5 Calibration of 'UUTi Low' Source Current Hardware Configurations

For calibration of UUTi Low source current hardware configurations use Table 10.4.8.1.

Table 10.4.8.1: Capacitance UUTi Low Hardware Configurations and Calibration Points

| Output span covered by hardware configuration | Suitable output to select hardware configuration | Calibration Targets |  |  | Factor Number |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Recommended | Minimum | Maximum |  |
| 0.5000 nF to 4.00000 nF | 1 nF | $\begin{aligned} & \hline 0.60000 \mathrm{nF} \\ & 3.00000 \mathrm{nF} \end{aligned}$ | $\begin{aligned} & \hline 0.52000 \mathrm{nF} \\ & 2.50000 \mathrm{nF} \end{aligned}$ | $\begin{aligned} & 0.80000 \mathrm{nF} \\ & 3.90000 \mathrm{nF} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| 4.0001 nF to 40.0000 nF | 10 nF | $\begin{gathered} 6.0000 \mathrm{nF} \\ 30.0000 \mathrm{nF} \end{gathered}$ | $\begin{gathered} 4.1000 \mathrm{nF} \\ 25.0000 \mathrm{nF} \end{gathered}$ | $\begin{gathered} 8.0000 \mathrm{nF} \\ 39.0000 \mathrm{nF} \end{gathered}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| 40.001 nF to 400.000 nF | 100 nF | $\begin{gathered} 60.000 \mathrm{nF} \\ 300.000 \mathrm{nF} \end{gathered}$ | $\begin{gathered} 41.000 \mathrm{nF} \\ 250.000 \mathrm{nF} \end{gathered}$ | $\begin{array}{r} 80.000 \mathrm{nF} \\ 390.000 \mathrm{nF} \end{array}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $0.40001 \mu \mathrm{~F}$ to $4.00000 \mu \mathrm{~F}$ | $1 \mu \mathrm{~F}$ | $\begin{aligned} & 0.60000 \mu \mathrm{~F} \\ & 3.00000 \mu \mathrm{~F} \end{aligned}$ | $\begin{aligned} & 0.41000 \mu \mathrm{~F} \\ & 2.50000 \mu \mathrm{~F} \end{aligned}$ | $\begin{aligned} & 0.80000 \mu \mathrm{~F} \\ & 3.90000 \mu \mathrm{~F} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $4.0001 \mu \mathrm{~F}$ to $40.0000 \mu \mathrm{~F}$ | 10رF | $\begin{array}{r} 6.0000 \mu \mathrm{~F} \\ 30.0000 \mu \mathrm{~F} \end{array}$ | $\begin{gathered} 4.1000 \mu \mathrm{~F} \\ 25.0000 \mathrm{nF} \end{gathered}$ | $\begin{array}{r} 8.0000 \mu \mathrm{~F} \\ 39.0000 \mu \mathrm{~F} \end{array}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $40.001 \mu \mathrm{~F}$ to $400.000 \mu \mathrm{~F}$ | $100 \mu \mathrm{~F}$ | $\begin{array}{r} 60.000 \mu \mathrm{~F} \\ 300.000 \mu \mathrm{~F} \end{array}$ | $\begin{array}{r} 41.000 \mu \mathrm{~F} \\ 250.000 \mu \mathrm{~F} \end{array}$ | $\begin{array}{r} 80.000 \mu \mathrm{~F} \\ 390.000 \mu \mathrm{~F} \end{array}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| 0.40001 mF to 4.00000 mF | 1 mF | $\begin{aligned} & 0.60000 \mathrm{mF} \\ & 3.00000 \mathrm{mF} \end{aligned}$ | $\begin{aligned} & 0.41000 \mathrm{mF} \\ & 2.50000 \mathrm{mF} \end{aligned}$ | $\begin{aligned} & 0.80000 \mathrm{mF} \\ & 3.90000 \mathrm{mF} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| 4.0001 mF to 40.0000 mF | 10 mF | $\begin{array}{r} 6.0000 \mathrm{mF} \\ 30.0000 \mathrm{mF} \end{array}$ | $\begin{gathered} 4.1000 \mathrm{mF} \\ 25.0000 \mathrm{mF} \end{gathered}$ | $\begin{array}{r} 8.0000 \mathrm{mF} \\ 39.0000 \mathrm{mF} \\ \hline \end{array}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |

### 10.4.8.6 'UUTi Low' Source Current Hardware Configurations - Calibration Procedure

1. Select the required hardware configuration by setting the 9100 output to a suitable value that uses the hardware configuration. Select 'UUTi Low' source current (refer to Model 9100 Universal Calibration System User's Handbook, Volume 1, Section 4, page 4.13-11).
2. Set the capacitance meter to the appropriate measurement range.
3. Press the 9100 's TARGET screen key to display the hardware configuration's target selection screen
4. Press the Factor screen key corresponding to the required target value to display a calibrate screen for the target value.
5. If the displayed target value is not the same as the value of your standard capacitor for this calibration point, press the TAB $\uparrow$ key to position the cursor on the target value and use any of the 9100's normal editing modes to change the target value to that of the standard capacitor. (Note that the new value must lie within the minimum and maximum limits specified in the table opposite.)
6. Press the TRANSFR screen key to transfer the target calibration point value to the 9100 output control display.
7. Connect the capacitance meter to the standard capacitor and note its reading. (Note: make sure to allow for any settling time required by the capacitance meter.)
8. Reconnect the capacitance meter to the 9100 .
9. Press the $\mathbf{O N}$ key to turn the 9100 output on.
10. Ensure that the cursor is on the 9100 output amplitude display (press the TAB $\Theta$ ) if necessary), and increment or decrement this value using the cursor controls and/or spinwheel until the reading on the capacitance meter is the same as that noted in step (7) above. (Note: make sure to allow for any settling time required by the capacitance meter.)
11. When you are satisfied with the measurement, press the CALIB key to generate and implement the correction factor required by the 9100 .
12. Press the OFF key to turn the 9100 output off.
13. Repeat steps (2) to (12) for each of the target values displayed in the target selection screen.
14. Repeat steps (1) to (13) for each of the hardware configurations detailed in the tables opposite (also see note below).

Note: If other functions are being calibrated in addition to Capacitance, refer to Table 10.4.2.1 on page 10.4-5 for information on sequencing calibrations.

### 10.4.8.7 Calibration of 'UUTi Super' Source Current Hardware Configurations

For calibration of UUTi Super source current hardware configurations use Table 10.4.8.2.

Table 10.4.8.2: Capacitance UUTi Super Hardware Configurations and Calibration Points

| Output span covered <br> by hardware configuration | Suitable output to <br> select hardware <br> configuration | Calibration Targets |  |  | Factor <br> Number |
| :---: | :---: | :---: | :---: | ---: | :---: |
|  |  | Minimum | Maximum |  |  |
| $40.001 \mu \mathrm{~F}$ to $400.000 \mu \mathrm{~F}$ | $100 \mu \mathrm{~F}$ | $60.000 \mu \mathrm{~F}$ | $41.000 \mu \mathrm{~F}$ | $80.000 \mu \mathrm{~F}$ | 1 |
|  |  | $190.000 \mu \mathrm{~F}$ | $250.000 \mu \mathrm{~F}$ | $390.000 \mu \mathrm{~F}$ | 2 |
| 0.40001 mF to 4.00000 mF | 1 mF | 0.60000 mF | 0.41000 mF | 0.80000 mF | 1 |
|  |  | 1.90000 mF | 2.50000 mF | 3.90000 mF | 2 |
| 4.0001 mF to 40.0000 mF | 6.0000 mF | 4.1000 mF | 8.0000 mF | 1 |  |
|  | 10 mF | 19.0000 mF | 25.0000 mF | 39.0000 mF | 2 |

### 10.4.8.8 'UUTi Super' Source Current Hardware Configurations — Calibration Procedure

1. Select the required hardware configuration by setting the 9100 output to a suitable value that uses the hardware configuration. Select 'UUTi Super' source current (refer to Model 9100 Universal Calibration System User's Handbook, Volume 1, Section 4, page 4.13-11).
2. Set the capacitance meter to the appropriate measurement range.
3. Press the 9100's TARGET screen key to display the hardware configuration's target selection screen
4. Press the Factor screen key corresponding to the required target value to display a calibrate screen for the target value.
5. If the displayed target value is not the same as the value of your standard capacitor for this calibration point, press the $\mathbf{T A B} \oplus 1$ key to position the cursor on the target value and use any of the 9100's normal editing modes to change the target value to that of the standard capacitor. (Note that the new value must lie within the minimum and maximum limits specified in the table opposite.)
6. Press the TRANSFR screen key to transfer the target calibration point value to the 9100 output control display.
7. Connect the capacitance meter to the standard capacitor and note its reading. (Note: make sure to allow for any settling time required by the capacitance meter.)
8. Reconnect the capacitance meter to the 9100 .
9. Press the $\mathbf{O N}$ key to turn the 9100 output on.
10. Ensure that the cursor is on the 9100 output amplitude display (press the TAB $\Theta$ ) if necessary), and increment or decrement this value using the cursor controls and/or spinwheel until the reading on the capacitance meter is the same as that noted in step (7) above. (Note: make sure to allow for any settling time required by the capacitance meter.)
11. When you are satisfied with the measurement, press the CALIB key to generate and implement the correction factor required by the 9100
12. Press the OFF key to turn the 9100 output off.
13. Repeat steps (2) to (12) for each of the target values displayed in the target selection screen.
14. Repeat steps (1) to (13) for each of the hardware configurations detailed in the table opposite (also see note below).

Note: If other functions are being calibrated in addition to Capacitance, refer to Table 10.4.2.1 on page 10.4-5 for information on sequencing calibrations.

### 10.4.9 Insulation Resistance Calibration

### 10.4.9.1 Introduction

This sub-section is a guide to calibrating the Model 9100's Insulation Resistance function (part of Option 135) using the front panel controls.

Due to the high voltages and high resistance values required, it is not practical to calibrate the Option 135 Insulation Resistance function using a standard resistance meter. Special equipment is used at manufacture to calibrate this function of the Model 9100 before shipment.

The following topics are covered in this sub-section:
10.4.9.2 Calibration Equipment Requirements
10.4.9.3 Interconnections
10.4.9.4 Calibration Setup
10.4.9.5 Calibration Procedure
10.4.9.6 Verification of Output Voltage Display

### 10.4.9.2 Calibration Equipment Requirements

- A set of traceably calibrated standard resistors at values between the minimum and maximum targets defined in the following table, capable of withstanding at least 1000 V DC for a prolonged period.
- A $3^{1 / 2}$ digit (or better) insulation test meter (for example, a Yokogawa 2426). This is used to make transfer measurements between the standard resistors and the Model 9100.


### 10.4.9.3 <br> Interconnections

Connect the positive output terminal of the insulation meter to the HI terminal of the 9100 and the negative output terminal of the insulation meter to the LO terminal of the 9100 as shown in Fig. 10.4.9.1 below.


Fig 10.4.9.1 Insulation Resistance Calibration Interconnections

### 10.4.9.4 Calibration Setup

1. Connections
2. 9100

Ensure that the 9100 is connected to the insulation tester as shown in Fig. 10.4.9.1 and that both instruments are powered on and warmed up.

Ensure that the 9100 is in STANDARD CAL mode and then select the Insulation Resistance function by pressing the AUX key on the right of the front panel followed by the $\Omega \zeta$ softkey.

Table 10.4.9.1: Insulation Resistance Hardware Configurations and Calibration Points

| Output span covered by hardware configuration |  | Suitable output to select $\mathrm{h} / \mathrm{w}$ configuration | Recommended | Minimum | Maximum | Factor Number |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 100.0K | 299.9K | 200.0K | $\begin{aligned} & 110.0 \mathrm{~K} \\ & 270.0 \mathrm{~K} \end{aligned}$ | $\begin{aligned} & 100.0 \mathrm{~K} \\ & 240.0 \mathrm{~K} \end{aligned}$ | $\begin{aligned} & 120.0 \mathrm{~K} \\ & 299.9 \mathrm{~K} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| 300.0K | 2.999M | 2.000 M | $\begin{aligned} & 330.0 \mathrm{~K} \\ & 1.000 \mathrm{M} \end{aligned}$ | $\begin{aligned} & 300.0 \mathrm{~K} \\ & 0.900 \mathrm{M} \end{aligned}$ | $\begin{aligned} & 360.0 \mathrm{~K} \\ & 1.100 \mathrm{M} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| 3.000 M | 29.99M | 20.00M | $\begin{aligned} & 3.300 \mathrm{M} \\ & 10.00 \mathrm{M} \end{aligned}$ | $\begin{aligned} & 3.000 \mathrm{M} \\ & 9.000 \mathrm{M} \end{aligned}$ | $\begin{aligned} & 3.600 \mathrm{M} \\ & 11.00 \mathrm{M} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| 30.00 M | 299.9M | 200.0M | $\begin{aligned} & 33.00 \mathrm{M} \\ & 100.0 \mathrm{M} \end{aligned}$ | $\begin{aligned} & 30.00 \mathrm{M} \\ & 90.00 \mathrm{M} \end{aligned}$ | $\begin{aligned} & 36.00 \mathrm{M} \\ & 110.0 \mathrm{M} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| 300.0M | 2.000G | 0.600G | $\begin{aligned} & 660.0 \mathrm{M} \\ & 1.800 \mathrm{G} \end{aligned}$ | $\begin{aligned} & 600.0 \mathrm{M} \\ & 1.600 \mathrm{G} \end{aligned}$ | $\begin{aligned} & 720.0 \mathrm{M} \\ & 2.000 \mathrm{a} \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |

### 10.4.9.6

## Calibration Procedure

1. Select the required hardware configuration by setting the 9100 output to a suitable value that uses the hardware configuration.
2. Set the insulation tester to the appropriate measurement range (note that the ' 1000 V ' range will provide best accuracy when calibrating the 9100 ).
3. Press the 9100 TARGET softkey to display the hardware configuration's target selection screen.
4. Press the FACTOR softkey corresponding to the required target value to display the calibration screen for this value
5. If the displayed target value is not the same as the value of your standard resistor for this calibration point, press the TAB key to position the cursor on the target value and edit this value to that of your standard resistor.
6. Press the TRANSFER softkey to transfer the target calibration point to the 9100 output control display.
7. Connect the insulation tester to the standard resistor, press the TEST button and note its reading (allow for the settling time of the insulation test meter).
8. Release the TEST button and reconnect the insulation tester to the 9100 .
9. Press the ON key to turn the 9100 output on. Press the TEST button on the insulation tester and note the reading.
10. Adjust the 9100 output amplitude until the reading on the insulation tester is the same as that noted in step (7) (allowing for the settling time of the insulation test meter).
11. When you are satisfied with the measurement, press the CALIB softkey to generate and implement the correction factor required by the 9100 .
12. Press the OFF key to turn the 9100 output off.
13. Repeat steps (2) through (12) for both of the target factor values displayed in the target selection screen.
14. Repeat steps (1) through (13) for each of the hardware configurations detailed in the table opposite.

### 10.4.9.6 Verification of Output Voltage Display

It is not possible to adjust the factors which scale the display of output voltage in the 9100's Insulation Resistance mode. However, a suitable method of verification is as follows:

1. Connect the insulation tester across the HI and LO terminals of the 9100 as shown in Fig. 10.4.9.1
2. Set the 9100 to MANUAL mode and select the insulation resistance function.
3. Connect a 1271 (or equivalent long scale DMM across the HI and LO terminals of the 9100 , with the 1271 input switched to DCV on the 1000 volt range (i.e. the 1271 is connected in parallel with the 9100 output terminals)
4. Set the 9100 output impedance to be $1.000 \mathrm{M} \Omega$.
5. Select the 500 V test range on the insulation tester.
6. Turn the 9100 output ON.
7. Press the TEST button on the insulation tester.
8. Note the voltage displayed on the 9100 output screen versus the voltage displayed on the 1271 and confirm that the 9100 displayed voltage is within its published specification of $\pm(0.6 \%+1.5 \mathrm{~V})$.
9. You will note that the insulation tester will display an impedance of approximately $0.91 \mathrm{M} \Omega$ - this is because of the $10 \mathrm{M} \Omega$ input impedance of the 1271 seen in parallel with the $1 \mathrm{M} \Omega$ impedance being generated by the 9100 .
10. Release the TEST button on the insulation tester.
11. Turn the 9100 output OFF.

### 10.4.10 Continuity Calibration

### 10.4.10.1 Introduction

This sub-section is a guide to calibrating the Model 9100's Continuity function (part of Option 135) using the front panel controls.

The following topics are covered in this sub-section:
10.4.10.2 Calibration Equipment Required
10.4.10.3 Interconnections
10.4.10.4 Calibration Setup
10.4.10.5 Calibration Procedure
10.4.10.6 Verification of Output Current Display

### 10.4.10.2 Calibration Equipment Required

- A set of traceably calibrated standard resistors at values between the minimum and maximum targets defined in the following table, capable of passing at least 350 mA DC.
- A $3^{1 / 2}$ digit (or better) continuity test meter (for example a Yokogawa 2426). This is used to make transfer measurements between the standard resistors and the 9100.


### 10.4.10.3 Interconnections

Connect the positive output terminal of the insulation meter to the HI terminal of the 9100 and the negative output terminal of the insulation meter to the LO terminal of the 9100 as shown in Fig. 10.4.9.1 below.


Section 10: Calibrating the Model 9100: Continuity Function

### 10.4.9.4 Calibration Setup

1. Connections Ensure that the 9100 is connected to the continuity tester as shown in Fig. 10.4.10.1 and that both instruments are powered on and warmed up.
2. 9100 Ensure that the 9100 is in STANDARD CAL mode and then select the Continuity function by pressing the AUX key on the right of the front panel followed by the $\left.\Omega^{\prime}\right)$ ) softkey.

Table 10.4.9.2: Continuity Hardware Configurations and Calibration Points

| Output span covered by hardware configuration |  | Suitable output to select h/w configuration | Recommended | Minimum | Maximum | Factor Number |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $00.0000 \Omega$ | $40.0000 \Omega$ | $10 \Omega$ | $\begin{gathered} 1.00 \Omega \\ 30.00 \Omega \end{gathered}$ | $\begin{gathered} 0.01 \Omega \\ 10.00 \Omega \end{gathered}$ | $\begin{aligned} & 7.50 \Omega \\ & 39.0 \Omega \end{aligned}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $40.001 \Omega$ | $400.000 \Omega$ | $100 \Omega$ | $\begin{aligned} & 60.00 \Omega \\ & 300.0 \Omega \end{aligned}$ | $\begin{aligned} & 41.00 \Omega \\ & 100.0 \Omega \end{aligned}$ | $\begin{gathered} 75.00 \Omega \\ 390 \Omega \end{gathered}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |
| $0.40001 \mathrm{k} \Omega$ | $4.00000 \mathrm{k} \Omega$ | $1 \mathrm{k} \Omega$ | $\begin{gathered} 600.0 \Omega \\ 3.000 \mathrm{k} \Omega \end{gathered}$ | $\begin{gathered} 410.0 \Omega \\ 1.000 \mathrm{k} \Omega \end{gathered}$ | $\begin{gathered} 750.0 \Omega \\ 3.900 \mathrm{k} \Omega \end{gathered}$ | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ |

### 10.4.10.3 Calibration Procedure

1. Select the required hardware configuration by setting the 9100 output to a suitable value that uses the hardware configuration.
2. Set the continuity tester to the appropriate measurement range
3. Press the TARGET softkey to display the hardware configuration's target selection screen.
4. Press the FACTOR softkey corresponding to the required target value to display the calibration screen for this value.
5. If the displayed target value is not the same as the value of your standard resistor for this calibration point, press the TAB key to position the cursor on the target value and edit this value to that of your standard resistor.
6. Press the TRANSFER softkey to transfer the target calibration point to the 9100 output control display.
7. Connect the continuity tester to the standard resistor, press the TEST button and note its reading (allow for the settling time of the test meter).
8. Release the TEST button and reconnect the continuity tester to the 9100 using the same test leads.
9. Press the ON key to turn the 9100 output on. Press the TEST button on the continuity tester and note the reading.
10. Adjust the 9100 output amplitude until the reading on the continuity tester is the same as that noted in step (7)
11. When you are satisfied with the measurement, press the CALIB softkey to generate and implement the correction factor required by the 9100 .
12. Press the OFF key to turn the 9100 output off.
13. Repeat steps (2) through (12) for both of the target values displayed in the target selection screen.
14. Repeat steps (1) through (13) for each of the hardware configurations detailed in the table opposite.

### 10.4.10.4 Verification of Output Current Display

1. Connect a $1271 / 1281$ or similar long-scale meter between the 9100 and the continuity meter
2. Select the 1 A range on the 1271
3. Set the 9100 output to zero ohm
4. Turn the 9100 output ON
5. Press the TEST button on the continuity meter and confirm that the current reading displayed by the 9100 is within $1.5 \%$ of the current displayed on the reference meter.

### 10.5 Remote Calibration of the Model 9100 via the IEEE 488 Interface

### 10.5.1 Model 4950 MTS System

The Model 4950 System is a self-contained, programmable Transfer Standard, capable of fully-traceable, high-accuracy calibration of the latest generation of high-performance multifunction calibrators. It is used to transfer traceable accuracy from standards laboratories to multifunction calibrators at remote locations, and has the following features:

- Wide Application - supports all Fluke calibrators, and other manufacturers' calibrators.
- Transfer Traceability - transfers traceable accuracy directly to the calibrator output terminals for all ranges and functions.
- Fully Automated - fully automates the calibration process and provides data for Statistical Process Control in order to define tailored certification intervals. Operates in industry-standard PC environment.
- Portability - specifically designed and constructed for extensive travel.
- Cost-Effective - provides 'on-site' calibration, drastically reducing calibrator downtime.
- High Confidence Levels - utilizes a closed-loop calibration process.

Calibration procedures for the Model 9100 are included in the Model 4950 Support Software. For further details of the Model 4950, please contact your local Fluke Sales/ Service center.


[^0]:    $\mathrm{H} \equiv$ Logic- 1 active; $\quad \mathrm{L} \equiv$ Logic- $\varnothing$ active

[^1]:    -100,"Command error"
    -101," Invalid character"
    -103,"Invalid separator"
    -104,"Data type error"
    -105,"GET not allowed"
    -108,"Parameter not allowed"
    -110,"Command header error"
    -111,"Header separator error"

[^2]:    Final Width $=215 \mathrm{~mm}$

